

**AFRL-VA-WP-TR-1999-3051**

**DEVELOPMENT OF THE  
AERODYNAMIC/AEROSERVOELASTIC  
MODULES IN ASTROS**

**VOLUME 3: ZAERO APPLICATIONS  
MANUAL (F33615-96-C-3217)**

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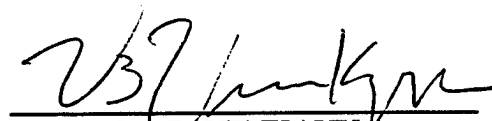
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## **FOREWORD**

This final report is submitted in fulfillment of CDRL CLIN 0001, Data Item A001, Title: Scientific and Technical Reports of a Small Business Technology Transfer (STTR) Phase II contract No. F33615-96-C-3217 entitled, "Development of the Aerodynamic/Aeroservoelastic Modules in ASTROS," covering the performance period from 24 September 1996 to 24 September 1998. This document provides the sample cases demonstrating the main features of the ZAERO module in ASTROS\*.

This work was performed by ZONA Technology, Inc. and its subcontractor, the University of Oklahoma (Research Institute). This work is the second phase of a continuing two-phase STTR contract supported by AFRL/Wright-Patterson. The first phase STTR contract No. F33615-95-C-3219 entitled, "Enhancement of the Aeroservoelastic Capability in ASTROS," was completed in May 1996 and published as WL-TR-96-3119. Started in September 1996, the present second phase STTR contract was conducted by the same team members as in Phase I. These contributors are: P.C. Chen (P.I.), D. Sarhaddi and D.D. Liu of ZONA Technology Inc. and Fred Striz of the University of Oklahoma.

At AFRL/Wright-Patterson, Capt. Gerald Andersen is the contract monitor and Dr. V.B. Venkayya is the initiator of the whole STTR effort. The technical advice and assistance received from Mr. Doug Niell of The MacNeal Schwendler Corporation, Dr. V.B. Venkayya and others from AFRL during the course of the present phase on the development of ASTROS\* are gratefully acknowledged.

## 1.0 INTRODUCTION

There are four major documents that describe the ZONA Aerodynamics (ZAERO) Module which has been seamlessly integrated into the Automated STRuctural Optimization System (ASTROS). These are: the ZAERO User's, Programmer's, Application and Theoretical Manuals for ASTROS\*. While ZAERO represents the ZONA Aerodynamics Module, ASTROS\* is defined as the seamless integration of ZAERO into ASTROS, i.e.  $\text{ASTROS}^* = \text{ZAERO} + \text{ASTROS}$ . This Applications Manual provides guidelines and sample cases to demonstrate the key features and use of the ZAERO module within ASTROS.

This Applications Manual is divided into two Volumes. Volume I presents sample analysis cases in the flutter and static aeroelasticity disciplines. Volume II provides sample optimization cases of more complex configurations.

The aerodynamic models in Volume I are kept small and are intended to demonstrate proper implementation and usage of the four ZAERO methods (i.e. ZONA6/subsonic, ZTAIC/transonic, ZONA7/supersonic and ZONA7U/hypersonic), as well as, proper aerodynamic geometry modeling and splining of the aerodynamic model to the structure.

The aerodynamic models in Volume II involve more realistic aircraft configurations and are consequently more complicated. Emphasis is placed on ASTROS\* optimization using the ZAERO method.

Sections 2.0 and 3.0 comprise Volume I and present the Flutter and Static Aeroelastic cases, respectively. Many cases are taken from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68, and have been modified for ASTROS\* input for validation of the ZAERO results.

Section 4.0 comprises Volume II of this manual and presents the static aeroelastic, normal modes and combined multidisciplinary (MDO) optimization cases.



# **VOLUME I**

## ***Flutter and Static Aeroelastic Analysis Cases***

## 2.0 FLUTTER CASES

### 2.1 Case 1: Subsonic ( $M=0.45$ ) Flutter Analysis of a 15-Degree Sweptback Wing (HA145E)

- **Purpose:** Demonstrate a wing only, subsonic (i.e. ZONA6 method) flutter case using the P-K and K flutter solution methods.

- **Description of Input:**

A 15 degree sweptback wing (modified HA145E case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68) is considered for this case. The structural and aerodynamic models are shown in Fig 2.1.1.

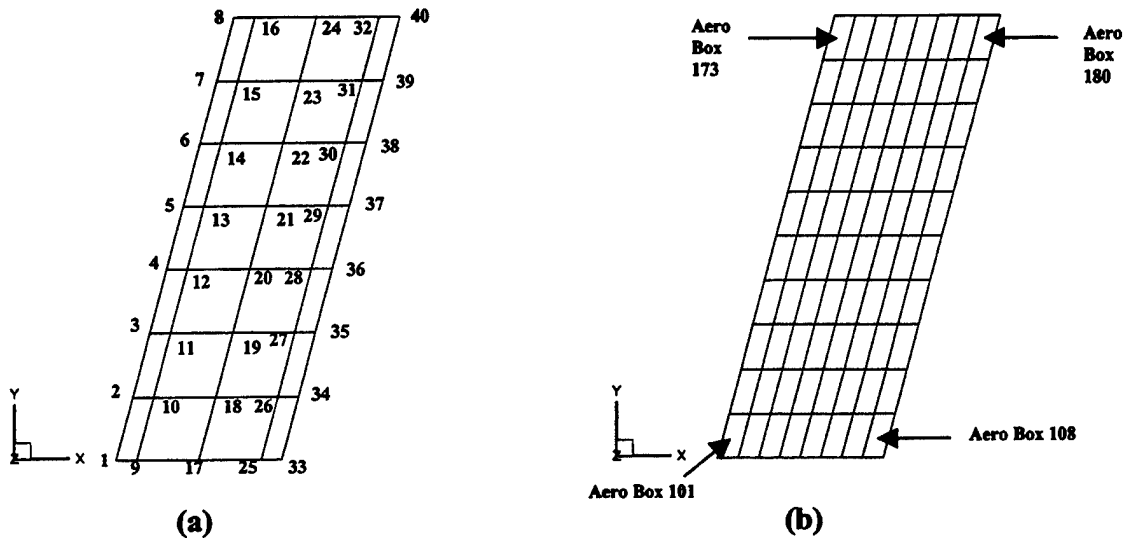


Figure 2.1.1 15 Degree Sweptback Wing (a) Structural Model and (b) Aerodynamic Model.

#### - Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies  $SPC = 1$  that selects the single-point constraints for grid points,  $REDUCE = 25$  that selects the analysis set degrees of freedom, and  $METHOD = 10$  that selects the eigenvalue extraction method to be used.

#### - Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 for a description of the structural model.

### *- Aerodynamic Parameters / Flight Conditions*

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.1092E-07 slinches (sea level density) and reference length of 2.07055 inches are used.

The **MKAEROZ** bulk data card specifies a freestream Mach number of 0.45 and 10 reduced frequencies from 0.0001 to 0.20.

### *- Aerodynamic Model*

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x- and y- coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

### *- Spline*

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by SETK = 101 and a **SET1** bulk data card by SETG = 100. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with WID of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.1 for **SET1 GRID** point id's and Fig 2.1.1.a).

### *- Flutter*

A **FLUTTER** bulk data card with SETID=30 requests that the P-K and K methods be used (METHOD entry set to PKK). The DENS entry refers to an **FLFACT** bulk data card with SID=1 that lists the density ratios for this case. The IDMK=1000 entry refers to the **MKAEROZ** bulk data card for this flutter case establishing the Mach number and reduced frequencies to be used. Finally, the VEL entry refers to an **FLFACT** bulk data card that lists the velocities to be used by the P-K flutter analysis method.

### *• Description of Output:*

Two disciplines were performed in this ASTROS\* run – a modal analysis and flutter analysis. The structural natural frequencies and generalized mass for the first four modes generated by the ASTROS\* modal analysis is shown in Table 2.1.1 along with the MSC/NASTRAN results.

**Table 2.1.1 Natural Frequencies and Generalized Mass of Case HA145E.**

Mode No.	ASTROS*		MSC/NASTRAN	
	Natural Frequency (Hz)	Generalized Mass	Natural Frequency (Hz)	Generalized Mass
1	34.7220	2.4861E-05	34.3439	2.4855E-05
2	211.469	8.7983E-06	210.000	9.0881E-06
3	260.147	8.6338E-06	260.429	8.5232E-06
4	645.657	7.4457E-06	634.761	7.9439E-06

The flutter results using ZONA6 aerodynamics of ASTROS\* by both the P-K and K methods are compared with that of MSC/NASTRAN using DLM with the KE method (see Fig 2.1.2).

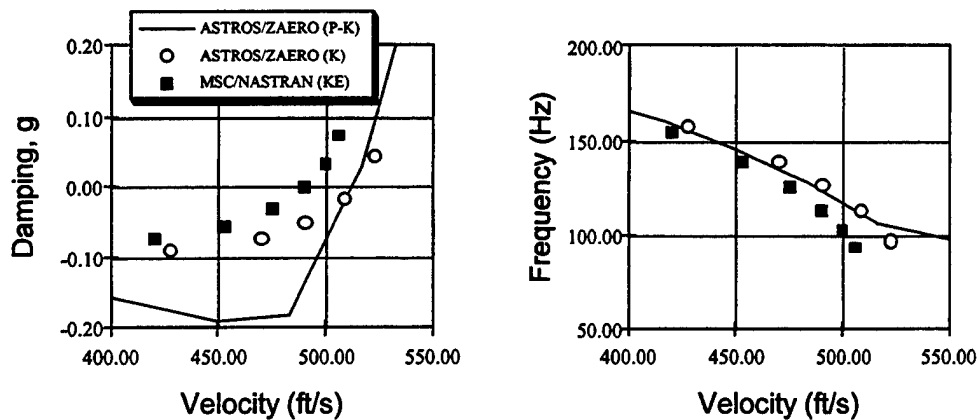


Figure 2.1.2 Flutter Results of Case HA145E, M=0.45.

Excellent agreement in terms of flutter speed at zero damping between the ASTROS\* P-K and K methods is obtained validating the K method. However, a small difference of flutter speed is observed between ASTROS\* and MSC/NASTRAN. This difference is most likely caused by the differences in the data obtained from the dynamic analyses (Table 2.1.1).

• **Input Data Listing:**

**Listing 2.1 Input Data for the 15 Degree Sweptback Wing (HA145E).**

```

ASSIGN DATABASE ICWCU3 PASS NEW DELETE
SOLUTION
TITLE = ZAERO FLUTTER CASE (HA145E): HALF SPAN 15-DEG SWEPT UNTAPERED WING
SUBTIT = PK & K-METHOD OF FLUTTER ANALYSIS
ANALYZE
  PRINT ROOTS = ALL
  BOUNDARY SPC = 1, REDUCE = 25, METHOD = 10
  LABEL = MODAL ANALYSIS
  MODES
  FLUTTER (FLCOND=30)
  LABEL = SUBSONIC CASE M=0.45
END
BEGIN BULK
$. . . 1 . . . 2 . . . 3 . . . 4 . . . 5 . . . 6 . . . 7 . . . 8 . . . 9 . . . 10 . .
GRID 1      0.0      0.0      0.0
GRID 2      .211491 .7893      0.0
GRID 3      .422983 1.5786      0.0
GRID 4      .634474 2.3679      0.0
GRID 5      .845966 3.1572      0.0
GRID 6      1.05746 3.9465      0.0
GRID 7      1.26895 4.7358      0.0
GRID 8      1.48044 5.5251      0.0
GRID 9      .259819 0.0         0.0
GRID 10     .47031  .7893      0.0
GRID 11     .681802 1.5786      0.0
GRID 12     .893293 2.3679      0.0
GRID 13     1.10478 3.1572      0.0
GRID 14     1.31628 3.9465      0.0
GRID 15     1.52777 4.7358      0.0
GRID 16     1.73926 5.5251      0.0
GRID 17     1.03528 0.0         0.0
GRID 18     1.24677 .7893      0.0
GRID 19     1.45826 1.5786      0.0
GRID 20     1.66975 2.3679      0.0
GRID 21     1.88124 3.1572      0.0
GRID 22     2.09273 3.9465      0.0
GRID 23     2.30422 4.7358      0.0
GRID 24     2.51572 5.5251      0.0
GRID 25     1.81173 0.0         0.0
GRID 26     2.02322 .7893      0.0
GRID 27     2.23471 1.5786      0.0
GRID 28     2.44621 2.3679      0.0

```

```

GRID 29      2.6577 3.1572 0.0
GRID 30      2.86919 3.9465 0.0
GRID 31      3.08068 4.7358 0.0
GRID 32      3.29217 5.5251 0.0
GRID 33      2.07055 0.0 0.0
GRID 34      2.28204 .7893 0.0
GRID 35      2.49353 1.5786 0.0
GRID 36      2.70502 2.3679 0.0
GRID 37      2.91652 3.1572 0.0
GRID 38      3.12801 3.9465 0.0
GRID 39      3.3395 4.7358 0.0
GRID 40      3.55099 5.5251 0.0
$
CQUAD4 1 1 1 2 10 9 $
+M00000 .001 .001 .041 .041 +M00000
CQUAD4 2 1 2 3 11 10 +M00001
+M00001 .001 .001 .041 .041
CQUAD4 3 1 3 4 12 11 +M00002
+M00002 .001 .001 .041 .041
CQUAD4 4 1 4 5 13 12 +M00003
+M00003 .001 .001 .041 .041
CQUAD4 5 1 5 6 14 13 +M00004
+M00004 .001 .001 .041 .041
CQUAD4 6 1 6 7 15 14 +M00005
+M00005 .001 .001 .041 .041
CQUAD4 7 1 7 8 16 15 +M00006
+M00006 .001 .001 .041 .041
CQUAD4 8 1 9 10 18 17
CQUAD4 9 1 10 11 19 18
CQUAD4 10 1 11 12 20 19
CQUAD4 11 1 12 13 21 20
CQUAD4 12 1 13 14 22 21
CQUAD4 13 1 14 15 23 22
CQUAD4 14 1 15 16 24 23
CQUAD4 15 1 17 18 26 25
CQUAD4 16 1 18 19 27 26
CQUAD4 17 1 19 20 28 27
CQUAD4 18 1 20 21 29 28
CQUAD4 19 1 21 22 30 29
CQUAD4 20 1 22 23 31 30
CQUAD4 21 1 23 24 32 31
CQUAD4 22 1 25 26 34 33 +M00007
+M00007 .041 .041 .001 .001
CQUAD4 23 1 26 27 35 34 +M00008
+M00008 .041 .041 .001 .001
CQUAD4 24 1 27 28 36 35 +M00009
+M00009 .041 .041 .001 .001
CQUAD4 25 1 28 29 37 36 +M00010
+M00010 .041 .041 .001 .001
CQUAD4 26 1 29 30 38 37 +M00011
+M00011 .041 .041 .001 .001
CQUAD4 27 1 30 31 39 38 +M00012
+M00012 .041 .041 .001 .001
CQUAD4 28 1 31 32 40 39 +M00013
+M00013 .041 .041 .001 .001
$
PSHELL 1 1 .041 1 1 $
$
CONVERT MASS .0025901 $
$
MFORM COUPLED $
$
MAT1 1 9.2418+63.4993+6 0.097464 $
$
SPC1 1 12345 9 $
SPC1 1 12345 25 $
SPC1 1 6 1 THRU 40 $
$
ASET1 25 3 1 THRU 8 $
ASET1 25 3 10 THRU 24 $
ASET1 25 3 26 THRU 40 $
$
EIGR 10 MGIV 4 $
+ER MAX +ER
$
$ ***** $
$ Z A E R O I N P U T $
$ ***** $
$ THIS CASE DEMONSTRATES A SINGLE WING, SUBSONIC FLUTTER CASE USING $
$ THE PK AND K FLUTTER SOLUTION METHODS. $
$ $
$...1...2...3...4...5...6...7...8...9...10... $
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS * $
$ $
$ ACSID XZSYM RHOREF REFC REFB REFS GREF $
AEROZ 0 YES 1.1092-72.07055 1. 1. $
$
$ IDMK MACH METHOD IDFLT SAVE <---FILENAME--> PRINT $
MKAEROZ 1000 .45 0 0 $
$ FREQ1 FREQ2 ETC $
+MK1 0.001 0.05 0.10 0.11 0.12 0.13 0.14 0.16 +MK2

```

```

+MK2      0.18      0.20
$
$
$          * WING MACROELEMENT *
$
$
$      WID      LABEL  ACOORD  NSPAN  NCHORD  LSPAN  ZTAIC  PAFOIL7
CAERO7    101      WING      0       11       9
$      XRL      YRL      ZRL      RCH      LRCHD  ATTCHR
+CA101     .0       .0       .0      2.07055  0       0
$      XRT      YRT      ZRT      TCH      LTCHD  ATTCHT
+CA102    1.48044  5.52510  0.0     2.07055  0       0
$
$
$          * SURFACE SPLINE FIT ON THE WING *
$
$
$      EID      MODEL  CP      SETK      SETG      DZ      EPS
SPLINE1   100      WING
$      SETID    MACROID BOX1      BOX2      ETC
PANLST2   101      101      101      THRU      180
$
$      SID      G1      G2      ETC
SET1      100      2       4       6       8       9       11      13
+S1       15      18      20      22      24      25      27      29
+S2       31      34      36      38      40
$
$
$          * FLUTTER ANALYSIS *
$
$
$      SETID    METHOD  DENS      IDMK      VEL      MLIST      KLISTE  EFFID
FLUTTER    30      PKK      1       1000      3
$      SYMXZ    SYMXY  EPS      CURVEFIT PRINT
+FL1       +1
$
$      SID      F1      F2      ETC
FLFACT     1      0.967
FLFACT     3      4000.   5000.   6000.   7000.   8000.   9000.   10000.
$
$
ENDDATA

```

## 2.2 Case 2: Low Supersonic ( $M=1.3$ ) Flutter Analysis of a 15-Degree Sweptback Wing (HA145FB) With and Without Thickness Effect

- **Purpose:** Demonstrate a wing only low supersonic flutter case with and without thickness effects using the P-K and K methods.

- **Description of Input:**

The same 15 degree sweptback wing presented in Case 1 is considered here. It is a modified sample test case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 (case HA145FB). Both the structural and aerodynamic models for this case were shown in Fig 2.1.1.

This case presents both the flat plate results (ZONA7 aerodynamics) and the wing with supersonic thickness effect results (ZONA7U aerodynamics) of a hexagonal wing cross section (Tuovila, W.J., NACA RM L55E11, 1955). The wing planform and cross section are shown in Fig 2.2.1.

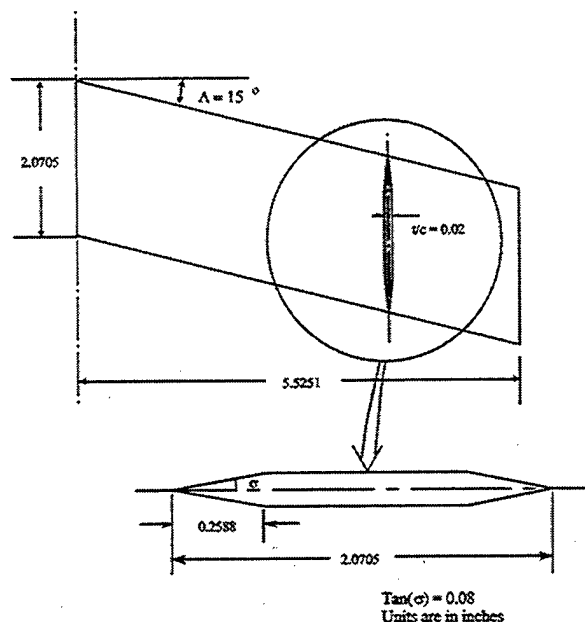


Figure 2.2.1 15 Degree Sweptback Planform and Cross Section (Tuovila, W.J., NACA RM L55E11, 1955).

### - Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 1 that selects the single-point constraints for grid points, REDUCE = 25 that selects the analysis set degrees of freedom, and METHOD = 10 that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first FLCOND = 30 selects the flutter case with no thickness effect and the second FLCOND = 40 selects the flutter case with the supersonic thickness effect.

### *- Structural Model*

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 for a description of the structural model.

### *- Aerodynamic Parameters / Flight Conditions*

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.145E-07 slinches (sea level density) and reference length of 2.07055 inches are used.

Two **MKAEROZ** bulk data cards are used to specify a freestream Mach number of 1.3 and 8 reduced frequencies ranging from 0.0001 to 0.08. Although both **MKAEROZ** bulk data cards have the same Mach number and reduced frequency input, two cards are required to compute both Aerodynamic Influence Coefficient (AIC) matrices using the linear aerodynamics method (ZONA7) and the nonlinear aerodynamics method (ZONA7U) which includes the supersonic thickness effect.

### *- Aerodynamic Model*

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x- and y- coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

A **PAFOIL7** bulk data card is used to define the 2% thick hexagonal airfoil section. The ITAX entry refers to an **AEFACT** bulk data card that specifies four x-coordinate points in percentage of the airfoil chord length. ITAX is a negative integer to request that linear interpolation be used between the airfoil points. The ITHR/T and ICAMR/T entries refer to **AEFACT** bulk data cards that specify the airfoil wing root and tip half thickness and cambers, respectively, at each x-coordinate.

### *- Spline*

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the SETK = 101 entry and a **SET1** bulk data card by the SETG = 100 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with WID of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.2 for **SET1 GRID** point id's and Fig 2.1.1).

### *- Flutter*

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses; one without thickness effects (IDMK=1000 entry refers to the **MKAEROZ** bulk data card employing the linear ZONA7 method at Mach 1.3) and one with the wing thickness effects (IDMK=2000 entry refers to the **MKAEROZ** bulk data card employing the nonlinear ZONA7U method at Mach 1.3). Both **FLUTTER** cards request that the P-K and K methods be used (METHOD entry set to PKK) and use



the same density ratio and velocities specified in the FLFACT bulk data cards with SID=1 and 3, respectively.

### • Description of Output:

The flutter results using ZONA7 aerodynamics of ASTROS\* are compared with results from the ZONA51 method of MSC/NASTRAN (i.e. Aero Option II). Excellent agreement between the two methods are obtained (see Table 2.2.1). This is expected since the lifting surface part of ZONA7 is identical to that of ZONA51.

**Table 2.2.1 Flutter Results of Case HA145FB (M = 1.3,  $\sigma = 0.20606$ ).**

	$V_f$ (ft/s)	$f_f$ (Hz)
Test	1280	102
W.P. Rodden	1405	129
<i>MSC/NASTRAN</i> P-K Method		
MSC/NASTRAN (ZONA51)	1576	132
<i>ASTROS*</i> K Method / P-K Method		
ZONA7 (no thickness)	1583 / 1601	132 / 130
ZONA7U (thickness effect)	1415 / 1426	123 / 122

$\sigma$  = Density Ratio =  $\rho / \rho_{sl}$

### • Input Data Listing:

**Listing 2.2 Input Data for the 15 Degree Sweptback Wing With and Without Thickness (HA145FB).**

```

ASSIGN DATABASE ICWCU3 PASS NEW DELETE
SOLUTION
TITLE = ZAERO FLUTTER CASE (HA145FB): HALF SPAN 15-DEG SWEPT UNTAPERED WING
SUBTIT = PK & K-METHOD OF FLUTTER ANALYSIS, ZONA7 + ZONA7U
ANALYZE
  PRINT ROOTS-ALL
  BOUNDARY SPC = 1, REDUCE = 25, METHOD = 10
  LABEL = MODAL ANALYSIS
  MODES
  FLUTTER (FLCOND=30)
  LABEL = WITHOUT THICKNESS
  FLUTTER (FLCOND=40)
  LABEL = WITH THICKNESS
END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
GRID 1 0.0 0.0 0.0
GRID 2 .211491 .7893 0.0
GRID 3 .422983 1.5786 0.0
GRID 4 .634474 2.3679 0.0
GRID 5 .845966 3.1572 0.0
GRID 6 1.05746 3.9465 0.0
GRID 7 1.26895 4.7358 0.0
GRID 8 1.48044 5.5251 0.0
GRID 9 .258819 0.0 0.0
GRID 10 .47031 .7893 0.0
GRID 11 .681802 1.5786 0.0
GRID 12 .893293 2.3679 0.0
GRID 13 1.10478 3.1572 0.0
GRID 14 1.31628 3.9465 0.0
GRID 15 1.52777 4.7358 0.0
GRID 16 1.73926 5.5251 0.0
GRID 17 1.03528 0.0 0.0
GRID 18 1.24677 .7893 0.0
GRID 19 1.45826 1.5786 0.0
GRID 20 1.66975 2.3679 0.0
GRID 21 1.88124 3.1572 0.0
GRID 22 2.09273 3.9465 0.0
GRID 23 2.30422 4.7358 0.0
GRID 24 2.51572 5.5251 0.0
GRID 25 1.81173 0.0 0.0
GRID 26 2.02322 .7893 0.0

```

```

GRID 27 2.23471 1.5786 0.0
GRID 28 2.44621 2.3679 0.0
GRID 29 2.6577 3.1572 0.0
GRID 30 2.86919 3.9465 0.0
GRID 31 3.08068 4.7358 0.0
GRID 32 3.29217 5.5251 0.0
GRID 33 2.07055 0.0 0.0
GRID 34 2.28204 .7893 0.0
GRID 35 2.49353 1.5786 0.0
GRID 36 2.70502 2.3679 0.0
GRID 37 2.91652 3.1572 0.0
GRID 38 3.12801 3.9465 0.0
GRID 39 3.3395 4.7358 0.0
GRID 40 3.55099 5.5251 0.0
$
CQUAD4 1 1 1 2 10 9 $+M00000
+M00000 .001 .001 .041 .041
CQUAD4 2 1 2 3 11 10 $+M00001
+M00001 .001 .001 .041 .041
CQUAD4 3 1 3 4 12 11 $+M00002
+M00002 .001 .001 .041 .041
CQUAD4 4 1 4 5 13 12 $+M00003
+M00003 .001 .001 .041 .041
CQUAD4 5 1 5 6 14 13 $+M00004
+M00004 .001 .001 .041 .041
CQUAD4 6 1 6 7 15 14 $+M00005
+M00005 .001 .001 .041 .041
CQUAD4 7 1 7 8 16 15 $+M00006
+M00006 .001 .001 .041 .041
CQUAD4 8 1 9 10 18 17
CQUAD4 9 1 10 11 19 18
CQUAD4 10 1 11 12 20 19
CQUAD4 11 1 12 13 21 20
CQUAD4 12 1 13 14 22 21
CQUAD4 13 1 14 15 23 22
CQUAD4 14 1 15 16 24 23
CQUAD4 15 1 17 18 26 25
CQUAD4 16 1 18 19 27 26
CQUAD4 17 1 19 20 28 27
CQUAD4 18 1 20 21 29 28
CQUAD4 19 1 21 22 30 29
CQUAD4 20 1 22 23 31 30
CQUAD4 21 1 23 24 32 31
CQUAD4 22 1 25 26 34 33 $+M00007
+M00007 .041 .041 .001 .001
CQUAD4 23 1 26 27 35 34 $+M00008
+M00008 .041 .041 .001 .001
CQUAD4 24 1 27 28 36 35 $+M00009
+M00009 .041 .041 .001 .001
CQUAD4 25 1 28 29 37 36 $+M00010
+M00010 .041 .041 .001 .001
CQUAD4 26 1 29 30 38 37 $+M00011
+M00011 .041 .041 .001 .001
CQUAD4 27 1 30 31 39 38 $+M00012
+M00012 .041 .041 .001 .001
CQUAD4 28 1 31 32 40 39 $+M00013
+M00013 .041 .041 .001 .001
$
PSHELL 1 1 .041 1 1 $
$
CONVERT MASS .0025901 $
$
MFORM COUPLED $
$
MAT1 1 9.2418+63.4993+6 0.097464 $
$
SPC1 1 12345 9 $
SPC1 1 12345 25 $
SPC1 1 6 1 THRU 40 $
$
ASET1 25 3 1 THRU 8 $
ASET1 25 3 10 THRU 24 $
ASET1 25 3 26 THRU 40 $
$
EIGR 10 MGIV 6 $+ER
+ER MAX
$
$ ***** $
$
$ Z A E R O I N P U T $
$
$ ***** $
$
$ THIS CASE DEMONSTRATES A SINGLE WING, LOW SUPERSONIC FLUTTER CASE $
$ WITH AND WITHOUT WING THICKNESS EFFECTS (I.E. ZONA7 AND ZONA7U $
$ METHODS, RESPECTIVELY) USING THE PK AND K FLUTTER SOLUTION METHODS. $
$
$...1...|...2...|...3...|...4...|...5...|...6...|...7...|...8...|...9...|...10...|
$
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS * $
$
$ ACSID XZSYM RHOREF REFC REFB REFS GREF $
$ AEROZ 0 YES 1.145-7 2.07055 1. 1. $
$
$

```

\$ TWO MKAEROZ BULK DATA CARDS ARE USED. THE FIRST MKAEROZ ACTIVATES THE \$  
 \$ LINEAR METHOD (ZONA7) AND THE SECOND THE NONLINEAR METHOD (ZONA7U) \$  
 \$ VIA THE METHOD FLAG. EACH MKAEROZ CARD IS REFERENCED BY A FLUTTER \$  
 \$ CARD BELOW. \$  
 \$ \$  
 \$ IDMK MACH METHOD IDFLT SAVE <--FILENAME--> PRINT \$  
 MKAEROZ 1000 1.3 0 0 0.05 0.06 0.07 0.08 +MK1 \$  
 \$ FREQ1 FREQ2 ETC \$  
 +MK1 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 \$  
 \$ \$  
 MKAEROZ 2000 1.3 1 0 0.05 0.06 0.07 0.08 +MK2 \$  
 +MK2 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 \$  
 \$ \$  
 \$ \* WING MACROELEMENT \* \$  
 \$ \$  
 \$ WID LABEL ACOORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7 \$  
 CAERO7 101 WING 0 11 9 100 +CA101 \$  
 \$ XRL YRL ZRL RCH LRCHD ATTCHR \$  
 +CA101 0.0 0.0 0.0 2.07055 0 0 +CA102 \$  
 \$ XRT YRT ZRT TCH LTCHD ATTCHT \$  
 +CA102 1.48044 5.52510 0.0 2.07055 0 0 \$  
 \$ \$  
 \$ THE PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL THICKNESS ALLOWING \$  
 \$ FOR THE INPUT OF HALF THICKNESS, CAMBER AND LEADING EDGE RADII AT \$  
 \$ THE WING ROOT AND TIP. THICKNESS AND CAMBER DISTRIBUTIONS BETWEEN \$  
 \$ THE WING ROOT AND TIP ARE INTERPOLATED. FOR THIS CASE, A 2% THICK \$  
 \$ HEXAGONAL AIRFOIL SECTION IS DEFINED. A NEGATIVE VALUE OF ITAX \$  
 \$ REQUESTS THAT A LINEAR INTERPOLATION BE USED FOR THICKNESS AND \$  
 \$ CAMBER DISTRIBUTIONS (POSITIVE VALUE IS FOR CUBIC INTERPOLATION). \$  
 \$ THICKNESS AND CAMBER DISTRIBUTIONS ARE USED ONLY FOR SUPERSONIC \$  
 \$ THICKNESS EFFECTS (ZONA7U) WHEN THE 'METHOD' ENTRY IS ACTIVE IN \$  
 \$ MKAEROZ BULK DATA CARD. \$  
 \$ \$  
 \$ ID ITAX ITHR ICAMR RADR ITHT ICAMT RADT \$  
 PAFOIL7 100 -101 102 103 0.0 102 103 0.0 \$  
 \$ \$  
 \$ SID D1 D2 ETC \$  
 AEFACT 101 0.0 12.5 87.5 100. \$  
 AEFACT 102 0.0 1.0 1.0 0.0 \$  
 AEFACT 103 0.0 0.0 0.0 0.0 \$  
 \$ \$  
 \$ \* SURFACE SPLINE FIT ON THE WING \* \$  
 \$ \$  
 \$ EID MODEL CP SETK SETG DZ EPS \$  
 SPLINE1 100 WING 101 100 0.0 \$  
 \$ \$  
 \$ SETID MACROID BOX1 BOX2 ETC \$  
 PANLST2 101 101 101 THRU 180 \$  
 \$ \$  
 \$ SID G1 G2 ETC \$  
 SET1 100 2 4 6 8 9 11 13 +S1 \$  
 +S1 15 18 20 22 24 25 27 29 +S2 \$  
 +S2 31 34 36 38 40 \$  
 \$ \$  
 \$ \$  
 \$ \*\* FLUTTER ANALYSIS \*\* \$  
 \$ \$  
 \$ THE FLUTTER BULK DATA CARDS EMPLOY THE PK AND K FLUTTER SOLUTION \$  
 \$ METHODS. EACH FLUTTER CARD REFERS TO A DIFFERENT MKAEROZ BULK DATA \$  
 \$ CARD. THE FIRST FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH AN IDMK \$  
 \$ OF 1000 (WING WITHOUT THICKNESS CASE - ZONA7 AERODYNAMICS). THE \$  
 \$ SECOND FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH IDMK = 2000 \$  
 \$ (WING WITH THICKNESS CASE - ZONA7U AERODYNAMICS). \$  
 \$ \$  
 \$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID \$  
 FLUTTER 30 PKK 1 1000 3 +FL1 \$  
 \$ SYMXZ SYMXY EPS CURVEFIT PRINT \$  
 +FL1 1 \$  
 \$ \$  
 FLUTTER 40 PKK 1 2000 3 +FL2 \$  
 +FL2 1 \$  
 \$ \$  
 \$ SID F1 F2 ETC \$  
 FLFACT 1 .20606 \$  
 FLFACT 3 14400. 15600. 16800. 18000. 19200. 20400. \$  
 ENDDATA \$

### 2.3 Case 3: High Supersonic ( $M=3.0$ ) Flutter Analysis of a 15-Degree Sweptback Wing (HA145G) With and Without Thickness Effect

- **Purpose:** Demonstrate a wing only, with and without thickness effect, high supersonic flutter case using the P-K and K methods.
- **Description of Input:**

The same 15 degree sweptback wing presented in Case 1 is considered. It is a modified sample test case from the MSC/NASTRAN Aeroelastic Analysis User's Guide (case HA145G). Both the structural and aerodynamic models were shown in Fig 2.1.1.

This case presents both the flat plate result (ZONA7 aerodynamics) and the wing with supersonic thickness effect result (ZONA7U aerodynamics) of a hexagonal wing cross section (Tuovila, W.J., NACA RM L55E11, 1955). The wing planform and cross section were shown in Fig 2.2.1.

There are two differences between the present case and Case 2. First, the Mach number for the present case is 3.0, whereas, Case 2 was 1.3. Second, the material properties (i.e. **MAT1** bulk data card) of the wing are different than that of Case 2. The wing of Case 2 was made of aluminum while the wing of Case 3 is made of magnesium. The nominal properties of magnesium include a moduli of elasticity  $E = 6.0 \times 10^6$  and  $G = 2.4 \times 10^6$  psi, with a density of  $0.064 \text{ lb/in}^3$ . These moduli and density were adjusted to match experimental data. The adjusted values, used in the present **MAT1** card, are  $E = 6.3604 \times 10^6$ ,  $G = 2.5442 \times 10^6$  psi and a density of  $0.0626202 \text{ lb/in}^3$ .

#### - Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies  $SPC = 1$  that selects the single-point constraints for grid points,  $REDUCE = 25$  that selects the analysis set degrees of freedom, and  $METHOD = 10$  that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first  $FLCOND = 30$  selects the flutter case with no thickness effect and the second  $FLCOND = 40$  selects the flutter case with the supersonic thickness effect.

#### - Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis Guide for a description of the structural model.

#### - Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of  $1.145E-07$  slinches (sea level density) and reference length of 2.07055 inches are used.

Two **MKAEROZ** bulk data cards are used to specify a freestream Mach number of 3.0 and 8 reduced frequencies ranging from 0.0001 to 0.08. Although both **MKAEROZ** bulk data cards

have the same Mach number and reduced frequency input, two cards are required to compute both Aerodynamic Influence Coefficient (AIC) matrices using the linear aerodynamics method (ZONA7) and the nonlinear aerodynamics method (ZONA7U) which includes the supersonic thickness effect.

#### *- Aerodynamic Model*

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x and y coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

A **PAFOIL7** bulk data card is used to define the 2% thick hexagonal airfoil section. The **ITAX** entry refers to an **AEFACT** bulk data card that specifies four x-coordinate points in percentage of the airfoil chord length. **ITAX** is a negative integer to request that linear interpolation be used between the airfoil points. The **ITHR/T** and **ICAMR/T** entries refer to **AEFACT** bulk data cards that specify the airfoil wing root and tip half thickness and cambers, respectively, at each x-coordinate.

#### *- Spline*

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the **SETK = 101** entry and a **SET1** bulk data card by the **SETG = 100** entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with **WID** of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.3 for **SET1 GRID** point id's and Fig 2.1.1).

#### *- Flutter*

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses; one without thickness effects (**IDMK=1000** entry refers to the **MKAEROZ** bulk data card employing the linear ZONA7 method at Mach 3.0) and one with the wing thickness effects (**IDMK=2000** entry refers to the **MKAEROZ** bulk data card employing the nonlinear ZONA7U method at Mach 3.0). Both **FLUTTER** cards request that the P-K and K methods be used (**METHOD** entry set to **PKK**) and use the same density ratio and velocities specified in the **FLFACT** bulk data cards with **SID=1** and **3**, respectively.

#### **• Description of Output:**

The flutter results using ZONA7 aerodynamics of ASTROS\* are compared with results from the ZONA51 method of MSC/NASTRAN (i.e. Aero Option II). Excellent agreement between the two methods are obtained (see Table 2.3.1). This is expected since the lifting surface part of ZONA7 is identical to that of ZONA51.

**Table 2.3.1 Flutter Results of Case HA145FB (M = 3.0,  $\sigma = 0.391$ ).**

	$V_f$ (ft/s)	$f_f$ (Hz)
Test	2030	146
W.P. Rodden	2077	149
<i>ASTROS*</i> K Method / P-K Method		
ZONA7 (no thickness)	2369 / 2448	158 / 154
ZONA7U (thickness effect)	1897 / 1923	154 / 152

$\sigma$  = Density Ratio =  $\rho / \rho_{sl}$

• **Input Data Listing:**

**Listing 2.3 Input Data for the 15 Degree Sweptback Wing With and Without Thickness (HA145G).**

```

ASSIGN DATABASE ICWCU3 PASS NEW DELETE
SOLUTION
TITLE = ZAERO FLUTTER CASE (HA145G): HALF SPAN 15-DEG SWEPT UNTAPERED WING
SUBTIT = PK & K METHOD OF FLUTTER ANALYSIS, ZONA7 + ZONA7U
ANALYZE
  PRINT ROOTS=ALL
  BOUNDARY SPC = 1, REDUCE = 25, METHOD = 10
  LABEL = MODAL ANALYSIS
  MODES
  LABEL = WITHOUT THICKNESS
  FLUTTER (FLCOND=30)
  LABEL = WITH THICKNESS
  FLUTTER (FLCOND=40)
END
BEGIN BULK
$. . . 1 . . . 2 . . . 3 . . . 4 . . . 5 . . . 6 . . . 7 . . . 8 . . . 9 . . . 10 . .
GRID 1      0.0      0.0      0.0
GRID 2      .211491 .7893      0.0
GRID 3      .422983 1.5786      0.0
GRID 4      .634474 2.3679      0.0
GRID 5      .845966 3.1572      0.0
GRID 6      1.05746 3.9465      0.0
GRID 7      1.26895 4.7358      0.0
GRID 8      1.48044 5.5251      0.0
GRID 9      .258819 0.0        0.0
GRID 10     .47031  .7893      0.0
GRID 11     .681802 1.5786      0.0
GRID 12     .893293 2.3679      0.0
GRID 13     1.10478 3.1572      0.0
GRID 14     1.31628 3.9465      0.0
GRID 15     1.52777 4.7358      0.0
GRID 16     1.73926 5.5251      0.0
GRID 17     1.03528 0.0        0.0
GRID 18     1.24677 .7893      0.0
GRID 19     1.45826 1.5786      0.0
GRID 20     1.66975 2.3679      0.0
GRID 21     1.88124 3.1572      0.0
GRID 22     2.09273 3.9465      0.0
GRID 23     2.30422 4.7358      0.0
GRID 24     2.51572 5.5251      0.0
GRID 25     1.81173 0.0        0.0
GRID 26     2.02322 .7893      0.0
GRID 27     2.23471 1.5786      0.0
GRID 28     2.44621 2.3679      0.0
GRID 29     2.6577  3.1572      0.0
GRID 30     2.86919 3.9465      0.0
GRID 31     3.08068 4.7358      0.0
GRID 32     3.29217 5.5251      0.0
GRID 33     2.07055 0.0        0.0
GRID 34     2.28204 .7893      0.0
GRID 35     2.49353 1.5786      0.0
GRID 36     2.70502 2.3679      0.0
GRID 37     2.91652 3.1572      0.0
GRID 38     3.12801 3.9465      0.0
GRID 39     3.3395  4.7358      0.0
GRID 40     3.55099 5.5251      0.0
$
CQUAD4 1      1      1      2      10      9
+M00000      .001      .001      .041      .041
CQUAD4 2      1      2      3      11      10
+M00001      .001      .001      .041      .041
CQUAD4 3      1      3      4      12      11
+M00002      .001      .001      .041      .041
CQUAD4 4      1      4      5      13      12
+M00003      .001      .001      .041      .041

```

```

CQUAD4 5 1 5 6 14 13 +M00004
+M00004 .001 .001 .041 .041
CQUAD4 6 1 6 7 15 14 +M00005
+M00005 .001 .001 .041 .041
CQUAD4 7 1 7 8 16 15 +M00006
+M00006 .001 .001 .041 .041
CQUAD4 8 1 9 10 18 17
CQUAD4 9 1 10 11 19 18
CQUAD4 10 1 11 12 20 19
CQUAD4 11 1 12 13 21 20
CQUAD4 12 1 13 14 22 21
CQUAD4 13 1 14 15 23 22
CQUAD4 14 1 15 16 24 23
CQUAD4 15 1 17 18 26 25
CQUAD4 16 1 18 19 27 26
CQUAD4 17 1 19 20 28 27
CQUAD4 18 1 20 21 29 28
CQUAD4 19 1 21 22 30 29
CQUAD4 20 1 22 23 31 30
CQUAD4 21 1 23 24 32 31
CQUAD4 22 1 25 26 34 33 +M00007
+M00007 .041 .041 .001 .001
CQUAD4 23 1 26 27 35 34 +M00008
+M00008 .041 .041 .001 .001
CQUAD4 24 1 27 28 36 35 +M00009
+M00009 .041 .041 .001 .001
CQUAD4 25 1 28 29 37 36 +M00010
+M00010 .041 .041 .001 .001
CQUAD4 26 1 29 30 38 37 +M00011
+M00011 .041 .041 .001 .001
CQUAD4 27 1 30 31 39 38 +M00012
+M00012 .041 .041 .001 .001
CQUAD4 28 1 31 32 40 39 +M00013
+M00013 .041 .041 .001 .001
$
FSHELL 1 1 .041 1 1 $
$
CONVERT MASS .0025901 $
$
MFORM COUPLED $
$
MAT1 1 6.3604+62.5442+6 .0626202 $
$
SPC1 1 12345 9 $
SPC1 1 12345 25 $
SPC1 1 6 1 THRU 40 $
$
ASET1 25 3 1 THRU 8 $
ASET1 25 3 10 THRU 24 $
ASET1 25 3 26 THRU 40 $
$
EIGR 10 MGIV 8 $ +ER
+ER MAX
$
$ ***** $
$
$ Z A E R O I N P U T $
$
$ ***** $
$
$ THIS CASE DEMONSTRATES A SINGLE WING, HIGH SUPERSONIC FLUTTER CASE $
$ WITH AND WITHOUT WING THICKNESS EFFECTS (I.E. ZONA7 AND ZONA7U) $
$ METHODS, RESPECTIVELY) USING THE PK AND K FLUTTER SOLUTION METHODS. $
$
$...1...2...3...4...5...6...7...8...9...10...|
$
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS * $
$
$ ACSID XZSYM RHOREF REFC REFB REFS GREF $
AEROZ 0 YES 1.145-7 2.07055 1. 1. $
$
$ TWO MKAEROZ BULK DATA CARDS ARE USED. THE FIRST MKAEROZ ACTIVATES THE $
$ LINEAR METHOD (ZONA7) AND THE SECOND THE NONLINEAR METHOD (ZONA7U) $
$ VIA THE METHOD FLAG. EACH MKAEROZ CARD IS REFERENCED BY A FLUTTER $
$ CARD BELOW. $
$
$ IDMK MACH METHOD IDFLT SAVE <---FILENAME---> PRINT $
MKAEROZ 1000 3.0 0 $ +MK1
$ FREQ1 FREQ2 ETC
+MK1 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 $
$
MKAEROZ 2000 3.0 1 $ +MK2
+MK2 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 $
$
$ * WING MACROELEMENT * $
$
$ WID LABEL ACOORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7 $
CAERO7 101 WING 0 11 9 100 +CA101
$ XRL YRL ZRL RCH LRCHD ATTCHR $
+CA101 0.0 0.0 0.0 2.07055 0 0 +CA102
$ XRT YRT ZRT TCH LTCHD ATTCHT $
+CA102 1.48044 5.52510 0.0 2.07055 0 0

```

```

$
$ THE PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL THICKNESS ALLOWING
$ FOR THE INPUT OF HALF THICKNESS, CAMBER AND LEADING EDGE RADII AT
$ THE WING ROOT AND TIP. THICKNESS AND CAMBER DISTRIBUTIONS BETWEEN
$ THE WING ROOT AND TIP ARE INTERPOLATED. FOR THIS CASE, A 2% THICK
$ HEXAGONAL AIRFOIL SECTION IS DEFINED. A NEGATIVE VALUE OF ITAX
$ REQUESTS THAT A LINEAR INTERPOLATION BE USED FOR THICKNESS AND
$ CAMBER DISTRIBUTIONS (POSITIVE VALUE IS FOR CUBIC INTERPOLATION).
$ THICKNESS AND CAMBER DISTRIBUTIONS ARE USED ONLY FOR SUPERSONIC
$ THICKNESS EFFECTS (ZONA7U) WHEN THE 'METHOD' ENTRY IS ACTIVE IN
$ MKAEROZ BULK DATA CARD.
$
$
$ ID      ITAX  ITHR  ICAMR  RADR  ITHT  ICAMT  RADT
PAFOIL7 100  -101  102   103   0.0   102   103   0.0
$
$      SID  D1    D2    ETC
AEFACT 101  0.0   12.5  87.5  100.
AEFACT 102  0.0   1.0   1.0   0.0
AEFACT 103  0.0   0.0   0.0   0.0
$
$
$          * SURFACE SPLINE FIT ON THE WING *
$
$      EID  MODEL  CP      SETK  SETG  DZ      EPS
SPLINE1 100  WING      101    100   0.0
$
$      SETID  MACROID BOX1  BOX2  ETC
PANLST2 101  101    101  THRU  180
$
$      SID  G1    G2    ETC
SET1 100  2     4     6     8     9     11    13
+S1  15  18    20    22    24    25    27    29
+S2  31  34    36    38    40
$
$
$          * * FLUTTER ANALYSIS * *
$
$ THE FLUTTER BULK DATA CARDS EMPLOY THE PK AND K FLUTTER SOLUTION
$ METHODS. EACH FLUTTER CARD REFERS TO A DIFFERENT MKAEROZ BULK DATA
$ CARD. THE FIRST FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH AN IDMK
$ OF 1000 (WING WITHOUT THICKNESS CASE - ZONA7 AERODYNAMICS). THE
$ SECOND FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH IDMK = 2000
$ (WING WITH THICKNESS CASE - ZONA7U AERODYNAMICS).
$
$
$      SETID  METHOD  DENS  IDMK  VEL  MLIST  KLIST  EFFID
FLUTTER 30  PKK    1     1000  3
$      SYMXZ  SYMXY  EPS   CURVFIT PRINT
+FL1  1
$
$      FLUTTER 40  PKK    1     2000  3
+FL2  1
$
$      SID  F1    F2    ETC
FLFACT 1  .391
FLFACT 3  20000. 22000. 24000. 28000. 32000. 34000.
ENDDATA

```



## 2.4 Case 4: Sample Wing-Body-Tiptank Flutter Analysis

- **Purpose:** Demonstrate a subsonic and supersonic wing-body-tiptank flutter analysis case using the P-K and K methods.

- **Description of Input:**

A wing-body-tiptank configuration is considered for the present case. The aerodynamic model of this configuration is shown in Fig 2.4.1.

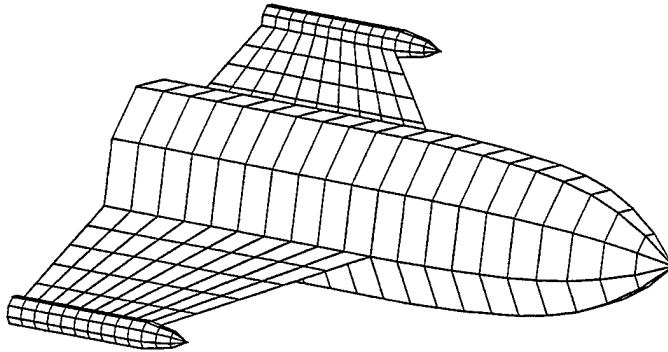


Figure 2.4.1 Aerodynamic Model of Sample Wing-Body-Tiptank Case.

### - Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 10 that selects the single-point constraints for grid points, REDUCE = 30 that selects the analysis set degrees of freedom, and METHOD = 20 that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first FLCOND = 99 selects the subsonic ( $M = 0.8$ ) flutter case and the second FLCOND = 100 selects the supersonic ( $M = 1.2$ ) flutter case.

### - Structural Model

A cropped delta wing with leading edge sweptback angle of  $35.54^\circ$  is used. The wing half-span and the root chord lengths are 70 inches and 100 inches, respectively. The wing is made of aluminum with a uniform thickness of 1.5 inches and is supported by an actuator at one third of the wing root. The aluminum wing is discretized into nine CQUAD4 elements. The actuator is idealized by a CBAR element. Thus, the total number of grid points is seventeen. The CBAR is clamped at the grid point 20000, which is constrained for all six degrees of freedom. The cropped delta wing structural finite element (FEM) model is shown in Fig 2.4.2.

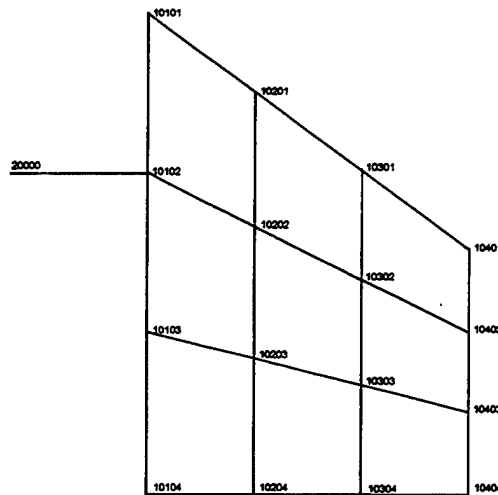


Figure 2.4.2 Cropped Delta Wing Structural Finite Element Model.

No structural FEM modeling is included for the body or tiptank in the present case. Spline of the tiptank to the wing is done via the **ATTACH** bulk data card, in which the rotational and displacement degrees of freedom are translated from a single grid point (i.e. grid no. 10402) to the entire tiptank. The fuselage, represented by a **BODY7** bulk data card, is not splined and, therefore, does not undergo any unsteady motion in this flutter analysis. However, body aerodynamics and wing-body aerodynamic interference (set via the **ATTCHR/ATTCHT** entries of the **CAERO7** bulk data card) are computed and accounted for in the analysis.

#### - Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.145E-07 slinches (sea level density) and reference length of 100.0 inches are used.

Two **MKAEROZ** bulk data cards with **IDMK**'s of 10 and 20 are used to specify freestream Mach numbers of 0.8 and 1.2, respectively. Eleven reduced frequencies are input ranging from 0.0001 to 0.55.

#### - Aerodynamic Model

One **CAERO7** wing macroelement is defined with 11 chordwise and 6 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are 100 and 50 inches, respectively, with a 100 inch semispan length. The wing root is attached to the fuselage body with the **ATTCHR** entry set to the fuselage **BODY7** bulk data card id (**BID**) of 201 to ensure proper treatment of the wing-body aerodynamic interference effects. Likewise, the wing tip is attached to the tiptank with the **ATTCHT** entry set to the tiptank **BODY7** bulk data card id (**BID**) of 401. Using the attachment option will avoid the wing root and tip from being treated as "free lifting surface edges" which will lead to incorrect unsteady pressure results in these regions.

The fuselage is defined by a **BODY7** macroelement with 5 circumferential and 21 axial cuts. The **BODY7** coordinates are specified within a local coordinate system defined by an **ACOORD** bulk data card with an **ID** of 20 located at (-100.0, 0.0, 0.0) that references the basic system (0.0, 0.0,

0.0). Fuselage cross-sections are specified through the body-of-revolution type of input (ITYPEi = 1 of the **SEGMESH** bulk data card) with camber and cross-sectional radius given at each of the 21 axial stations.

The tiptank is defined by a **BODY7** macroelement with 9 circumferential and 14 axial cuts. The **BODY7** coordinates are specified within a local coordinate system defined by an **ACORD** bulk data card with an ID of 30 located at (35.0, 105.0, 0.0) that references the basic system (0.0, 0.0, 0.0). Fuselage cross-sections are specified through the body-of-revolution type of input (ITYPEi = 1 of the **SEGMESH** bulk data card) with camber and cross-sectional radius given at each of the 14 axial stations.

Note that the selection of wing and body macroelement id's (WID and BID) is not completely arbitrary. These integers must be selected so that no duplicate grid and/or aerodynamic box id's occur. For example, if a wing macroelement is set up with an id of 11 that has 10 x 10 aero box cuts and another wing macroelement is used with an id of 51, then duplicate grid and aero box id's will occur. This is because ZAERO establishes internal aero grid and box id's with starting values based on the macroelement id. Therefore, an aero box and grid with an id of 51 will already exist from the first macroelement (see the ASTROS\* User's Manual for detailed description). In the present case, the first body macroelement (BID = 201) has 5 radial and 21 axial cuts. This will generate internally 105 (i.e. 21 x 5) aerodynamic grid points and 80 (i.e. (21-1) x (5-1)) aerodynamic boxes. Therefore, the next available macroelement id would be 307 (i.e. 201 + 105 + 1).

#### *- Spline*

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the SETK = 102 entry and a **SET1** bulk data card by the SETG = 103 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with WID of 101), and splines all of the wing aerodynamic boxes (101 through 150) to the structural grid points listed in the **SET1** bulk data card.

An **ATTACH** bulk data card is used to transfer the displacement and rotational motion of a reference **GRID** point (REFGRID = 10402) located at the wing tip to the tiptank. A **PANLST2** bulk data card is referenced by the SETK = 402 entry splines all of the tiptank aerodynamic boxes (401 through 540) to the reference grid point.

#### *- Flutter*

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses. The first **FLUTTER** bulk data card (SETID=99) refers to an **MKAEROZ** bulk data card (IDMK=10) with a Mach number of 0.8. The second **FLUTTER** bulk data card (SETID=100) refers to an **MKAEROZ** bulk data card (IDMK=20) with a Mach number of 1.2. The referenced **FLFACT** bulk data cards in entries DENS and VEL specify the density ratios and velocities for the P-K method, respectively. Both **FLUTTER** bulk data cards request that the P-K and K methods be used (METHOD entry set to PKK).

• **Description of Output:**

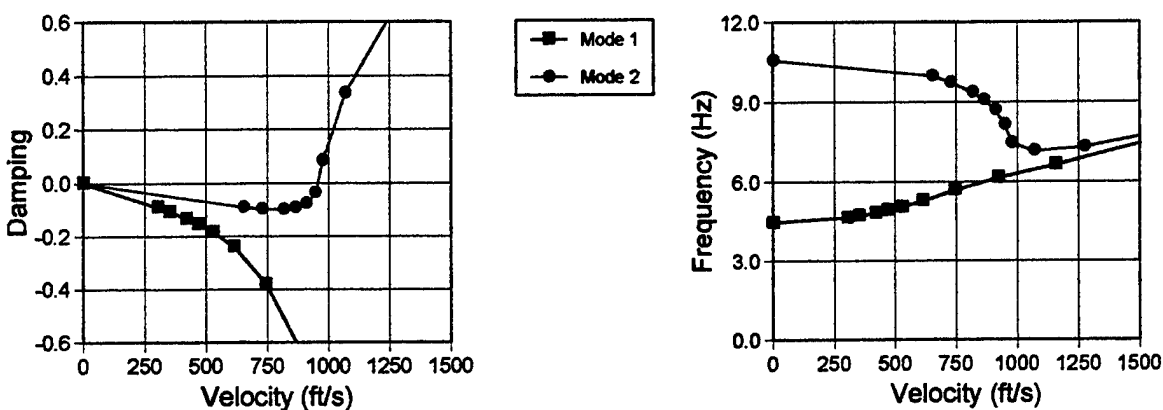
The structural natural frequencies and generalized mass for the first five modes generated by the ASTROS\* modal analysis is shown in Table 2.4.1.

**Table 2.4.1 Natural Frequencies and Generalized Mass of the Wing-Body-Tiptank Case.**

Mode No.	ASTROS*	
	Natural Frequency (Hz)	Generalized Mass
1	4.461	4.36703E-01
2	10.556	3.02312E-01
3	29.392	2.70375E-01
4	32.566	9.04735E-02
5	50.038	4.82148E-01

• **Subsonic Flutter Results ( $M=0.8$ )**

K-method flutter results of damping and frequency versus velocity for the first two modes are shown in Fig 2.4.3. The flutter crossing occur at  $V_f = 956$  ft/s and  $\omega_f = 7.92$  Hz.



**Figure 2.4.3 K-Method Flutter Curves of Wing-Body-Tiptank Case ( $M=0.8$ , Sea Level Density).**

P-K method flutter results for this same case are shown in Fig 2.4.4. Flutter crossings occur at  $V_f = 959$  ft/s and  $\omega_f = 7.83$  Hz.

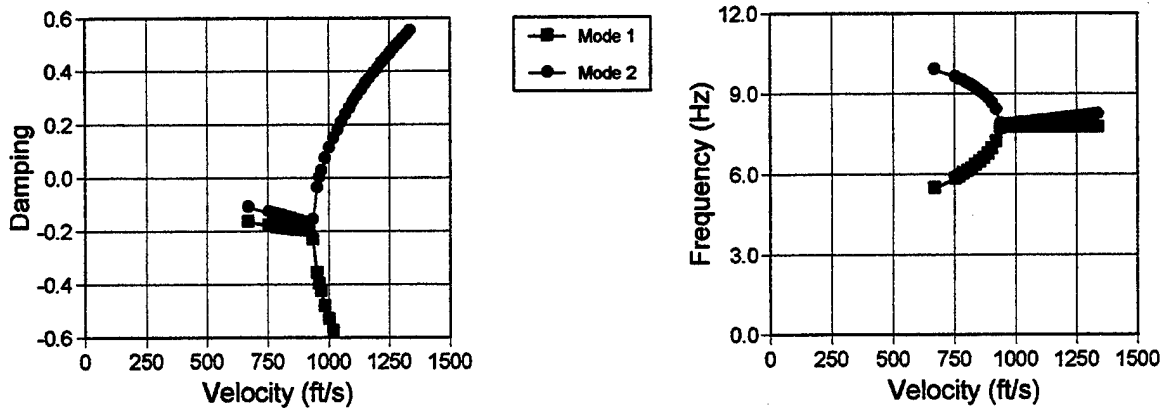


Figure 2.4.4 P-K Method Flutter Curves of Wing-Body-Tiptank Case ( $M=0.8$ , Sea Level Density).

### • *Supersonic Flutter Results ( $M=1.2$ )*

K-method flutter results of damping and frequency versus velocity for the first two modes are shown in Fig 2.4.5. The flutter crossing occur at  $V_f = 1014$  ft/s and  $\omega_f = 8.35$  Hz.

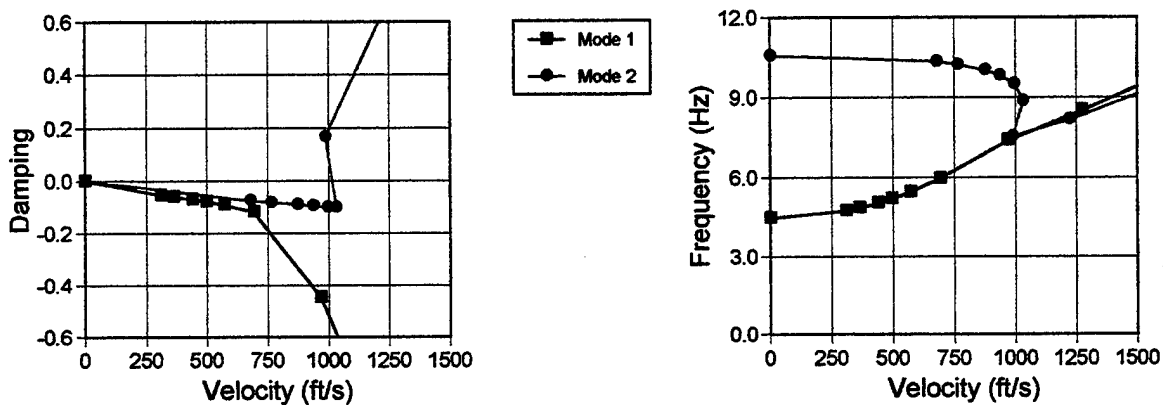


Figure 2.4.5 K-Method Flutter Curves of Wing-Body-Tiptank Case ( $M=1.2$ , Sea Level Density).

P-K method flutter results for this same case are shown in Fig 2.4.6. Flutter crossings occur at  $V_f = 966$  ft/s and  $\omega_f = 7.63$  Hz.

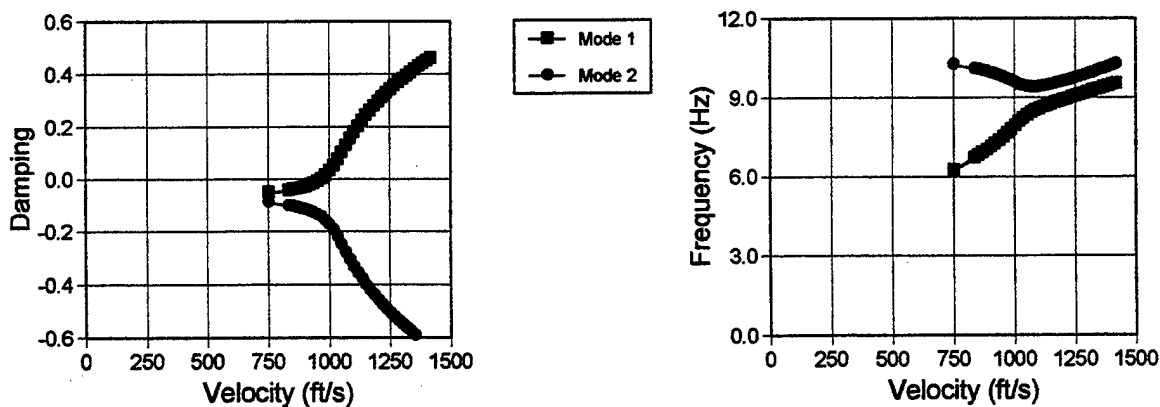


Figure 2.4.6 P-K Method Flutter Curves of Wing-Body-Tiptank Case ( $M=1.2$ , Sea Level Density).

Good agreement between the P-K and K-flutter methods are obtained for both Mach numbers. The larger discrepancy between the two methods for the supersonic case is due to the abrupt flutter point crossing in the K-method results (see Fig 2.4.5). Improved correlation can be obtained by increasing the number of reduced frequencies listed in the MKAEROZ bulk data card with IDMK=20 at the flutter point crossing (i.e. between  $k=0.2$  and  $0.225$ ).

• *Input Data Listing:*

**Listing 2.4 Input Data for the Wing-Body-Tiptank Case.**

```

ASSIGN DATABASE CROP PASS NEW DELETE
SOLUTION
  TITLE = SAMPLE WING-BODY-TIPTANK CASE
  ANALYZE
    BOUNDARY SPC=10, REDUCE=30, METHOD=20
    MODES
      PRINT ROOT = ALL
      LABEL = MODAL ANALYSIS
      FLUTTER (FLCOND=99)
      PRINT ROOT = ALL
      LABEL = SUBSONIC FLUTTER ANALYSIS
      FLUTTER (FLCOND=100)
      PRINT ROOT = ALL
      LABEL = SUPERSONIC FLUTTER ANALYSIS
END
$
BEGIN BULK
$. . . 1 . . . 2 . . . 3 . . . 4 . . . 5 . . . 6 . . . 7 . . . 8 . . . 9 . . . 10 . .
ASET1 30 3 10101 THRU 10104
ASET1 30 3 10201 THRU 10204
ASET1 30 3 10301 THRU 10304
ASET1 30 3 10401 THRU 10404
ASET1 30 45 10402
CBAR 1010 1010 10102 20000 10101
CQUAD4 1001 1000 10101 10102 10202 10201
CQUAD4 1002 1000 10102 10103 10203 10202
CQUAD4 1003 1000 10103 10104 10204 10203
CQUAD4 1004 1000 10201 10202 10302 10301
CQUAD4 1005 1000 10202 10203 10303 10302
CQUAD4 1006 1000 10203 10204 10304 10303
CQUAD4 1007 1000 10301 10302 10402 10401
CQUAD4 1008 1000 10302 10303 10403 10402
CQUAD4 1009 1000 10303 10304 10404 10403
EIGR 20 MGIV 5.0 5 +ABC
+ABC MAX
GRID 10101 0.0 30.000 0.0
GRID 10102 33.333 30.000 0.0
GRID 10103 66.667 30.000 0.0
GRID 10104 100.000 30.000 0.0
GRID 10201 16.667 53.333 0.0
GRID 10202 44.444 53.333 0.0
GRID 10203 72.222 53.333 0.0
GRID 10204 100.000 53.333 0.0
GRID 10301 33.333 76.667 0.0
GRID 10302 55.555 76.667 0.0
GRID 10303 77.778 76.667 0.0
GRID 10304 100.000 76.667 0.0
GRID 10401 50.000 100.000 0.0
GRID 10402 66.667 100.000 0.0
GRID 10403 83.333 100.000 0.0
GRID 10404 100.000 100.000 0.0
GRID 20000 33.333 0.0 0.0
MAT1 1100 1.E+07 .3 .1
CONVERT MASS .00259
PBAR 1010 1100 100. .1E+04 .1E+04 .05E+04
PSHELL 1000 1100 1.5 1100
SPC1 10 6 10101 THRU 10104
SPC1 10 6 10201 THRU 10204
SPC1 10 6 10301 THRU 10304
SPC1 10 6 10401 THRU 10404
SPC 10 20000 123456
$
$ * * * * *
$
$ Z A E R O I N P U T
$
$ * * * * *
$
$ THIS CASE DEMONSTRATES A SUBSONIC + SUPERSONIC WING-BODY-TIPTANK
$ FLUTTER ANALYSIS CASE USING THE PK AND K FLUTTER SOLUTION METHODS.
$
$. . . 1 . . . 2 . . . 3 . . . 4 . . . 5 . . . 6 . . . 7 . . . 8 . . . 9 . . . 10 . .
$

```

* AERO PARAMETERS / FLIGHT CONDITIONS *									
ACSID	XZSYM	RHOREF	REFC	REFB	REFS	REFG			
AEROZ	YES	1.145-07100.							
\$ TWO MKAEROZ CARDS ARE USED. THE FIRST ACTIVATES THE SUBSONIC METHOD (ZONA6) AND THE SECOND THE SUPERSONIC METHOD (ZONA7) - BASED ON THE \$ INPUT MACH NUMBER.									
MKAEROZ	IDMK	MACH	METHOD	IDFLT	SAVE	ACQUIRE	FILENAME	PRINT	
10	10	0.8	0		0.225	CROPAIC			
FREQ1	FREQ2	ETC			0.2				
0.001	0.1	0.15	0.175		0.225	0.25	0.275		
0.3	0.35	0.4							
MKAEROZ	20	1.2	0		0.2	CROPAIC			
0.001	0.1	0.15	0.175		0.225	0.25	0.275		
0.3	0.35	0.4							
* WING MACROELEMENT *									
CAERO7	WID	LABEL	ACCORD	NSPAN	NCHORD	LSPAN	ZTAIC	PAFOIL7	
101	WING		6	11					
XRL	YRL	ZRL	RCH	LRCHD	ATTCHR				
0.0	30.0	0.0	100.0	0	201				
XRT	YRT	ZRT	TCH	LTCHD	ATTCHT				
50.0	100.0	0.0	50.0	0	401				
* BODY MACROELEMENT *									
( FUSELAGE )									
\$ TWO BODY7 BULK DATA CARDS ARE USED TO DEFINE THE FUSELAGE AND TIPTANK \$ MACROELEMENTS. EACH BODY7 COORDINATES ARE BASED ON A LOCAL COORDINATE \$ SYSTEM SPECIFIED BY THE ACCORD BULK DATA ENTRIES. THE BODY-OF- \$ REVOLUTION TYPE OF INPUT IS USED FOR BOTH THE FUSELAGE AND TIPTANK \$ TO SPECIFY THE CROSS-SECTIONAL RADIUS AND CAMBER (SEGMENT BULK DATA \$ CARD).									
COORDINATE SYSTEM FOR FUSELAGE									
ACCORD	ID	XORIGN	YORIGN	ZORIGN	DELTA	THETA			
20	-100.	0.0	0.0	0.0	0.0				
BODY7	BID	LABEL	IPBODY7	ACCORD	NSEG	IDMESH1	IDMESH2	ETC	
201	FUSELAGE		20	1	201				
SEGMENT	IDMESH	NAXIS	NRAD						
201	21	5							
ITYPE	X1	CAM1	YR1	ZR1	IDY1	IDZ1			
1	0.0	0.0	0.0						
1	10.0	0.0	10.0						
1	20.0	0.0	17.0						
1	30.0	0.0	22.0						
1	40.0	0.0	25.0						
1	50.0	0.0	27.0						
1	60.0	0.0	28.0						
1	70.0	0.0	29.0						
1	80.0	0.0	29.5						
1	90.0	0.0	30.0						
1	100.0	0.0	30.0						
1	110.0	0.0	30.0						
1	120.0	0.0	30.0						
1	130.0	0.0	30.0						
1	140.0	0.0	30.0						
1	150.0	0.0	30.0						
1	160.0	0.0	30.0						
1	170.0	0.0	30.0						
1	180.0	0.0	30.0						
1	190.0	0.0	30.0						
1	200.0	0.0	30.0						
* BODY MACROELEMENT *									
( TIPTANK )									
COORDINATE SYSTEM FOR TIPTANK									
ACCORD	ID	XORIGN	YORIGN	ZORIGN	DELTA	THETA			
30	35.0	105.0	0.0	0.0	0.0				
BODY7	BID	LABEL	IPBODY7	ACCORD	NSEG	IDMESH1	IDMESH2	ETC	
401	TIPTANK		30	1	401				
SEGMENT	IDMESH	NAXIS	NRAD						
401	14	9							
ITYPE	X								





## 2.5 Case 5: AGARD Standard 445.6 Wing – Transonic Flutter Analysis

- **Purpose:** Demonstrate a transonic wing flutter analysis case using the ZTAIC method with steady pressure input provided by CFD.
- **Description of Input:**

The AGARD Standard 445.6 Weakened (modified AGARD Test Case from the ASTROS Application Manual (AFWAL-TR-88-3028), also AGARD Report No. 765, and NASA TN D-1616) is considered in the present case for both subsonic and transonic Mach numbers ( $M=0.678, 0.90, 0.95$ ). The wing is a 45 degree swept-back wing of aspect ratio 6 with a NASA 64A004 airfoil section. The ZONA6 (linear) and ZTAIC (nonlinear) method flutter results are compared with wind tunnel measurement data. The ZTAIC method (ZAERO's transonic method) wing sectional steady pressure input used in the present analysis are obtained by two Computational Fluid Dynamics (CFD) codes: the CAPTSD (2D Euler) and ENSAERO (3D Navier-Stokes) codes. Similar to the AGARD Test Case presented in the ASTROS Applications Manual, the structural finite element model of this wing is replaced by the input of mode shapes, generalized mass and stiffness matrices of the first five modes via the Direct Matrix Input (DMI) bulk data. The aerodynamic model of the AGARD Standard 445.6 Wing is shown in Fig 2.5.1.

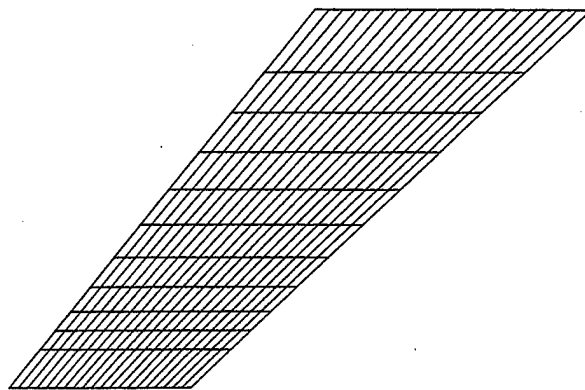
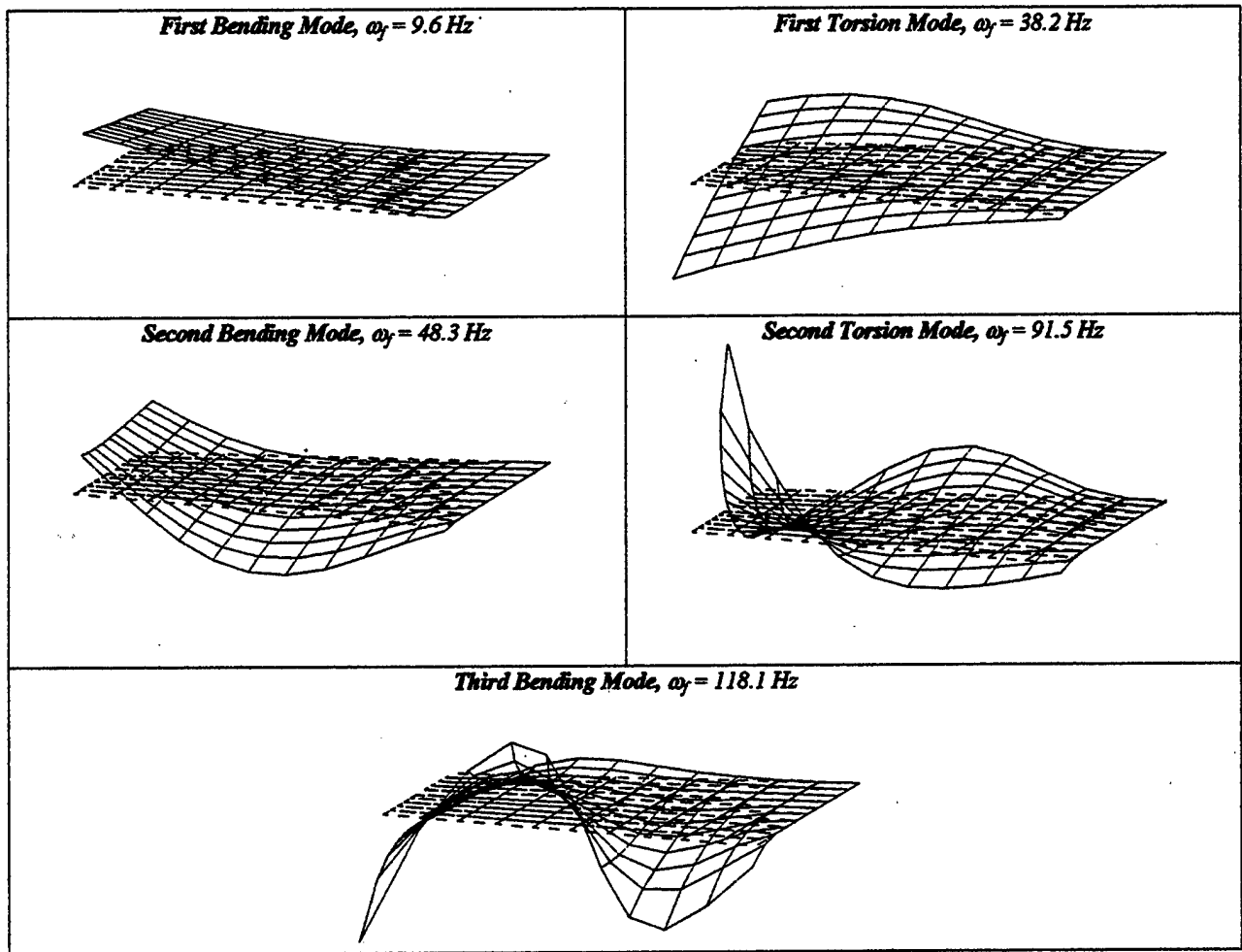


Figure 2.5.1 Aerodynamic Model of the AGARD Standard 445.6 Wing.

The natural frequencies and mode shapes of the weakened wing structure are presented in Fig 2.5.2. The dashed line wings represent the undeformed wing structure.



**Figure 2.5.2 AGARD Standard 445.6 Weakened Wing Natural Frequencies and Mode Shapes (1<sup>st</sup> 5 modes).**

For the present test case, wing sectional steady pressure input data is provided for all three Mach numbers. Steady pressure can be obtained by physical flight test data, wind tunnel data or by computational means (such as CFD). Accuracy of the ZTAIC method flutter results depends on the accuracy of the steady pressure input (i.e. ideal steady pressure input would come from flight test or wind tunnel measurement).

Differences in steady pressure input obtained by different sources (in this case 2 CFD codes) is shown in the following figure. The ZTAIC steady pressure input for Mach 0.95 and Angle-of-Attack ( $\alpha$ ) = 0°, used in the present case, as computed by the CAPTSD (Euler) and ENSAERO (Navier-Stokes) codes at 6 spanwise stations is shown in Fig 2.5.3.

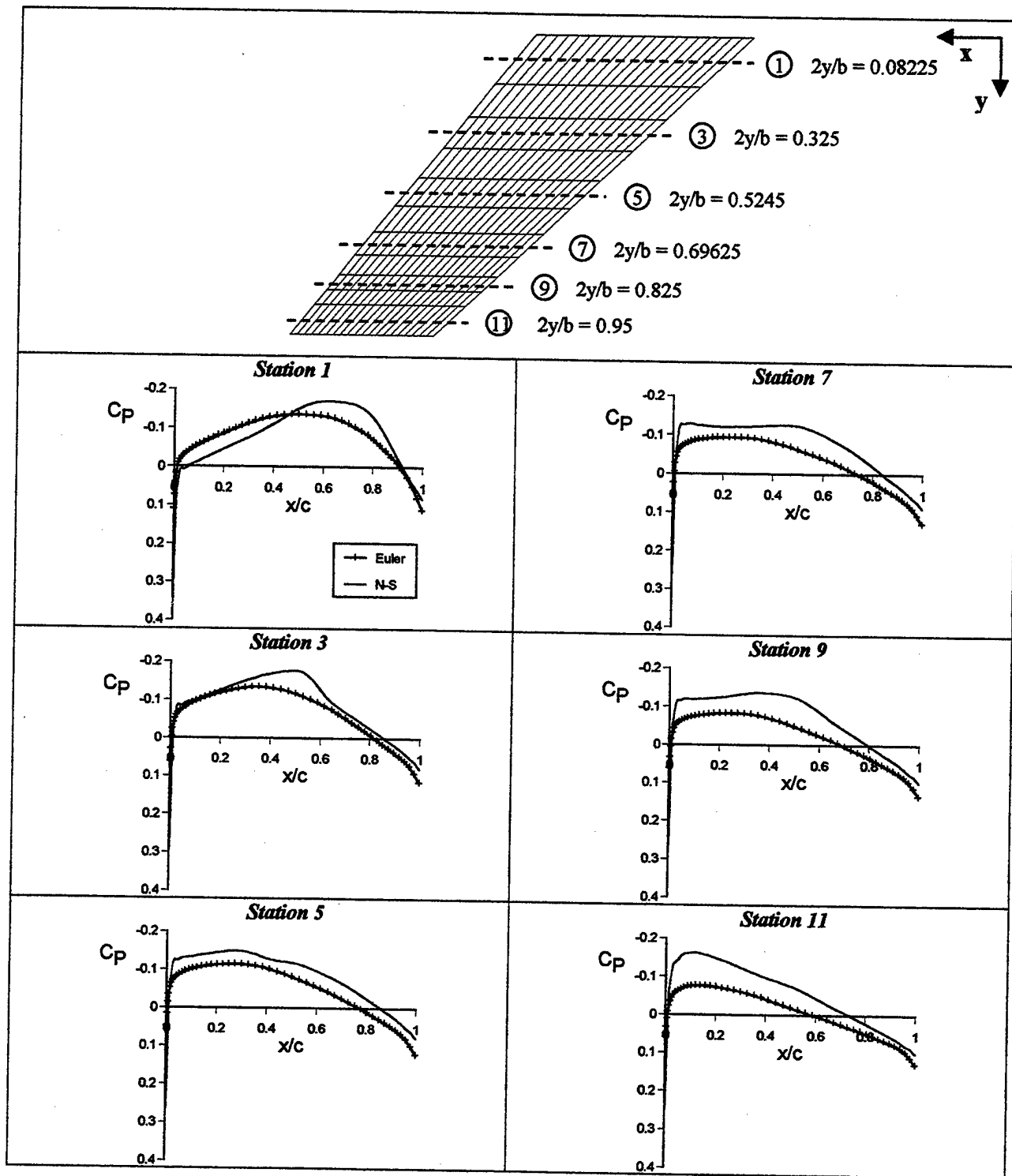


Figure 2.5.3 AGARD Standard 445.6 Weakened Wing CAPTSD (Euler) and ENSAERO (Navier-Stokes = N-S) Steady Pressure Results ( $M=0.95, \alpha=0.0^\circ$ ).

Differences in terms of shock strength and location is seen between the Euler and Navier-Stokes results. The effect of these differences on the ZTAIC method flutter results is shown in the Description of Output section of the present case.

### *- Solution Control*

Substantial modification to the ASTROS\* standard Matrix Analysis Problem Oriented Language (MAPOL) sequence is implemented through the EDIT command. The optimization and global matrix assembly phases are deleted from the sequence. A modified flutter analysis routine is inserted omitting the dynamic matrix assembly to replace the standard flutter sequence.

An analysis is performed with six flutter subcases. The first case performs a ZTAIC (nonlinear) flutter analysis and the second a ZONA6 (linear) flutter analysis. This is repeated three times for each Mach number ( $M = 0.678, 0.90, 0.95$ ).

### *- Structural Model*

Structural model processing is replaced in this case by the mode shape, stiffness matrix and mass matrix input via the Direct Matrix Input (DMI) bulk data. Therefore, the ASTROS\* structural input consists only of 121 grid points, all constrained in 5 degrees-of-freedom (DOF) with the 6<sup>th</sup> DOF (i.e. the z-translation) left free. This corresponds to 121 DOF for each mode. Five modes with corresponding natural frequencies are input by DMI's. The mass matrix is a 5 x 5 identity matrix while the stiffness matrix is a diagonal matrix whose nonzero entries are the input eigenvalues.

### *- Aerodynamic Parameters / Flight Conditions*

The AEROZ bulk data card specifies a symmetric model about the x-z plane. A reference density of  $1.145\text{E-}07$  slinches (sea level density) and reference length of 21.96 inches are used.

Six MKAEROZ bulk data cards are used to specify freestream Mach numbers of 0.678, 0.90 and 0.95 for both the linear (ZONA6) on nonlinear (ZTAIC) aerodynamic methods. Identical reduced frequencies ranging from 0.0001 to 0.5 are computed for all MKAEROZ.

The Aerodynamic Influence Coefficient (AIC) matrices associated with each MKAEROZ bulk data card are saved in filenames specified in the FILENAME entries. Mnemonic notation used for filenames consist of: Wing Name + Mach Number + Method Used. For example, 'AGARD678ZT' would be the AGARD wing at Mach 0.678 with the ZTAIC method used (i.e. METHOD entry set to 1 = nonlinear method).

### *- Aerodynamic Model*

One wing macroelement is used to define the wing planform. 20 chordwise (evenly cut) and 11 spanwise (cuts specified in AEFAC bulk data card with SID=10) aerodynamic boxes are used. For the ZTAIC method to be "active" for this wing macroelement, the ZTAIC entry is set to 1001, which refers to a ZTAIC bulk data card that establishes the steady pressure input to be used on this wing.

### *- Spline*

The infinite plate spline method (**SPLINE1**) is used to spline all of the wing aerodynamic boxes to the structural grid points. A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the **SETK** = 10 entry and a **SET1** bulk data card by the **SETG** = 603 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with **WID** of 1001), and splines all of the wing aerodynamic boxes (1001 through 1220) to the structural grid points listed in the **SET1** bulk data card (grids 1 through 121).

### *- Flutter*

Six **FLUTTER** bulk data cards are input corresponding to each **FLUTTER** subcase specified in the solution control. The P-K and K methods of flutter solution are requested for all cases (**METHOD** entry set to **PKK**). Density ratios specified in the **DENS** entries refer to **FLFACT** bulk data cards which list density ratios that encompass the flutter matched point altitudes. **IDMK** entries refer to **MKAEROZ** bulk data cards that specify the Mach number/reduced frequencies for the flutter analysis. The same velocities for the P-K method are used for all flutter analyses (velocities listed in **FLFACT** bulk data card with **SID**=40).

### *- ZTAIC Method Steady Pressure Input*

Transonic data for the **ZTAIC** method is input via the **ZTAIC**, **MACHCP** and **CHORDCP** bulk data entries. Only one set of steady pressure input can be used per **ASTROS\*** run (i.e. either from wind tunnel measurement, Euler Code, N-S Code, etc.). Therefore, the **CHORDCP** bulk data used to input the steady pressure for all three Mach numbers of this case are saved in two separate files ('tsdcp.inp' for **CAPTSD**/Euler and 'nscp.inp' for **ENSAERO**/Navier-Stokes steady pressure) and are included in the bulk data input via the **ASTROS INCLUDE** statement (see **ASTROS User's Manual** for details on the **INCLUDE** statement). The user can select the desired pressure input by uncommenting the corresponding **INCLUDE** statement (by removing the \$).

The **ZTAIC** bulk data card refers to 3 **MACHCP** bulk data cards that establish the Mach number and steady pressure input relations. Span locations and corresponding steady pressure for each section are specified by the **SPANID** and **CHDCP** entries, respectively.

For example, the **MACHCP** with ID of 1001 specifies a Mach number of 0.678. This Mach number must identically exist in on the the **MKAEROZ** bulk data cards with the nonlinear method "active" (i.e. **METHOD** entry set to 1). The spanwise station indicies (**SPANID** entries) correspond to the wing macroelement span division centerline locations. In this case an **AEFACT** bulk data card with ID=10 was used to specify the spanwise wing macroelement cuts. Therefore, the **SPANID**=1 refers to the wing span location of 8.22% (  $[0.0+16.45]/2$  ), **SPANID**=2 refers to the wing span location of 21.85% (  $[16.45+27.25]/2$  ), and so on.

**CHORDCP** entries in the 'tsdcp.inp' and 'nscp.inp' files contain the x-location of the pressure in percent chord length (**X** entries), the upper surface steady pressure coefficients (**CPU** entries), and the lower surface steady pressure coefficients (**CPL** entries).

• **Description of Output:**

A matched point flutter analysis is performed to compare with wind tunnel data provided in the following reference, Yates, E.C., Jr., Land, M.S. and Foughner, J.T., Jr., "Measured and Calculated Subsonic and Transonic Flutter Characteristics of a 45° Sweptback Wing Planform in Air and Freon-12 in the Langley Transonic Dynamics Tunnel," NASA TN D-1616, March 1963.

The weakened wing model (model 3) is considered for this case with a span of 2.5 feet. The measured modal frequencies and panel mass for this wing are given in Table 2.5.1

**Table 2.5.1 Measured Modal Frequencies and Panel Mass of the AGARD Standard 445.6 Weakened Wing Model.**

Model Description				Frequency (Hz)					Panel mass, slugs
Panel span, ft	Mounting	Structure	Model	$f_{h,1}$	$f_{h,2}$	$f_{t,1}$	$f_{t,2}$	$f_{\alpha}$	m
2.50	Wall	Weakened	3	9.60	50.70	38.10	98.50	38.09	0.12764

Table 2.5.2 presents the computed matched point density and mass ratios for the present case. The flutter matched point is found by varying the ASTROS\* density ratios (specified in the FLFACT bulk data cards SID's=301-306) so that the computed speed of sound (i.e. computed flutter velocity divided by the input Mach number) matches that of the wind tunnel test results.

**Table 2.5.2 Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.**

	ZONA6		ZTAIC(TSD)		ZTAIC (N-S)		Experiment	
Mach	$\rho/\rho_{SL}$	$\mu$	$\rho/\rho_{SL}$	$\mu$	$\rho/\rho_{SL}$	$\mu$	$\rho/\rho_{SL}$	$\mu$
0.678	0.184	61.52	0.190	63.53	0.186	62.85	0.170	68.75
0.90	0.084	146.12	0.080	139.16	0.074	157.96	0.081	143.92
0.95	0.066	198.13	0.059	177.12	0.052	224.80	0.052	225.82

$\rho/\rho_{SL}$ =density ratio,  $\rho_{SL}$ =sea level density,  $\mu$  = mass ratio, Experimental data from NASA TN D-1616 (March 1963)

The mass ratio  $\mu = m / (\rho V)$  is defined as the mass of the wing divided by the mass of air contained within the volume of a conical frustum having the streamwise root chord as the lower base diameter, streamwise tip chord as the upper base diameter, and wing panel span as the height.

Table 2.5.3 presents the flutter frequency ratios and flutter speed coefficients for the present case.

Table 2.5.3 Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.

	ZONA6		ZTAIC(TSD)		ZTAIC (N-S)		Experiment	
Mach	$\frac{\omega}{\omega_\alpha}$	$\frac{U}{b_s \omega_\alpha \sqrt{\mu}}$	$\frac{\omega}{\omega_\alpha}$	$\frac{U}{b_s \omega_\alpha \sqrt{\mu}}$	$\frac{\omega}{\omega_\alpha}$	$\frac{U}{b_s \omega_\alpha \sqrt{\mu}}$	$\frac{\omega}{\omega_\alpha}$	$\frac{U}{b_s \omega_\alpha \sqrt{\mu}}$
0.678	0.5280	0.4343	0.5340	0.4399	0.5314	0.4363	0.4712	0.4174
0.90	0.4297	0.3754	0.4240	0.3666	0.4136	0.3522	0.4216	0.3700
0.95	0.3945	0.3460	0.3840	0.3276	0.3697	0.3068	0.3673	0.3059

Experimental data from NASA TN D-1616 (March 1963)

where  $\omega$  is the flutter frequency,  $\omega_\alpha$  is the natural circular frequency of the wing in first uncoupled torsion mode ( $2\pi f_\alpha$ ),  $U$  is the flutter velocity and  $b_s$  is the streamwise semichord measured at the wing root ( $b_s=0.9165$  feet).

Figure 2.5.4 presents the flutter speed coefficients and frequency ratios of Table 2.5.3. At the subsonic Mach number of 0.678, the ZTAIC results are in close agreement with those of ZONA6, as expected, since transonic effects (such as shock wave) are minimum or nonexistent. At transonic Mach numbers, the ZTAIC results predicts a pronounced transonic dip that is not observed in the linear (ZONA6) results. Better correlation of flutter speed coefficient with experimental results is seen at Mach 0.95 for the ZTAIC case with Navier-Stokes (N-S) pressure input. This is expected since the N-S results account for fluid viscosity, thereby giving better predictions of shock position and strength.

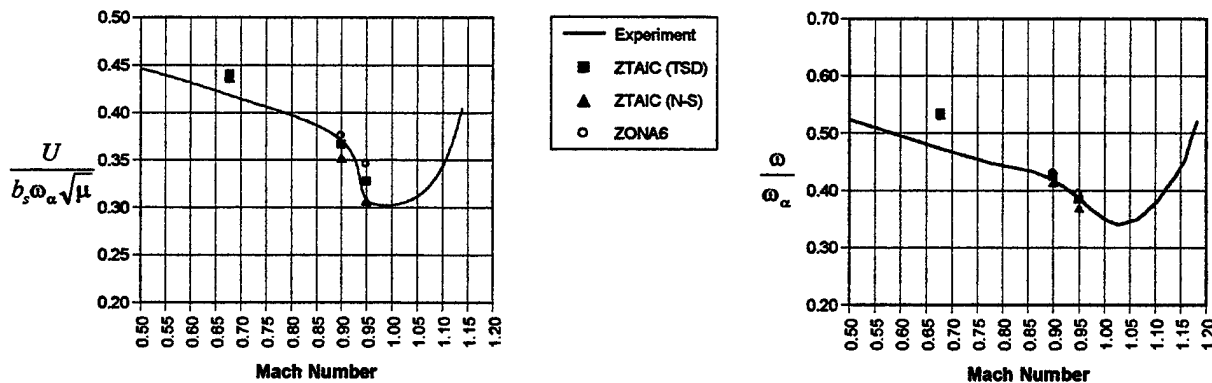


Figure 2.5.4 Plots of Flutter Speed Coefficients and Frequency Ratios of the AGARD Standard 445.6 Weakened Wing (matched point analysis).

### • Input Data Listing:

#### Listing 2.5 Input Data for the AGARD Standard 445.6 Wing (Weakened Model).

```

ASSIGN DATABASE AGARD PASS NEW DELETE
EDIT NOLIST
INSERT 3
$ ***
*** EDIT: (MAPOLSEQ VERSION 11.1)
*** TESTCASE DEMONSTRATING FLUTTER ANALYSIS WITH
*** DIRECT-INPUT OF MODE SHAPES AND FREQUENCIES.

```

```

***
MATRIX [MODES], [KFLUT];
REPLACE 371,1958
$ ***
*** EDIT:
*** DELETE OPTIMIZATION PHASE.
***
REPLACE 1974,1975
$ ***
*** EDIT:
*** DELETE GLOBAL MATRIX ASSEMBLY (EMA2).
***
REPLACE 2018,2746
$ ***
*** EDIT:
*** REPLACE MATRIX REDUCTIONS, ANALYSIS SEGMENT AND DATA RECOVERY
*** WITH SPECIAL FLUTTER ANALYSIS
*** OMITTING DYNAMIC MATRIX ASSEMBLY (FLUTDMA).
***
CALL NREDUCE ( , [UGTKG], [PNSF(BC)], , , , [UGTKA] );
PRINT("LOG=(' >>>DISCIPLINE: NORMAL MODES')");
CALL REIG ( , BC, USET(BC), [KAA], [MAA], , , LAMBDA,
[PHIA], [MII], HSIZE(BC) );
PRINT("LOG=(' >>>DISCIPLINE: FLUTTER')");
CALL FLUTQHHZ ( , BC, SUB, ESIZE(BC), PSIZE(BC), [AJK],
[SKJ], [UGTKA], [MODES], USET(BC),
[TMN(BC)], [GSUBO(BC)], NGDR, AECOMPU, GEOMUA,
[PHIKH], [QHHLFL(BC,SUB)], OAGRDDSP );
PRINT("LOG=(' >>>DISCIPLINE: FLUTTRAZ '");
PRINT("LOG=(' >>>DISCIPLINE: FLUTTRAZ '");
CALL FLUTTRAZ ( , BC, SUB, [QHHLFL(BC,SUB)], LAMBDA, HSIZE(BC),
ESIZE(BC), [MAA], [BHHFL(BC,SUB)],
[KFLUT], CLAMBDA, ,AEROZ );

SOLUTION
TITLE = AGARD STANDARD 445.6 WING TEST CASE USING THE ZTAIC (TRANSONIC) METHOD
SUBTITLE = WEAKENED WING (MODEL 3) - AGARD RPT. NO. 765
ANALYZE
PRINT (MODE = ALL) ROOT = ALL
BOUNDARY METHOD = 10
MODES
LABEL = WEAKENED MODES
FLUTTER (FLCOND = 1)
LABEL = ZTAIC (M=0.678) FLUTTER RESULTS
FLUTTER (FLCOND = 2)
LABEL = ZONA6 (M=0.678) FLUTTER RESULTS
FLUTTER (FLCOND = 3)
LABEL = ZTAIC (M=0.9) FLUTTER RESULTS
FLUTTER (FLCOND = 4)
LABEL = ZONA6 (M=0.9) FLUTTER RESULTS
FLUTTER (FLCOND = 5)
LABEL = ZTAIC (M=0.95) FLUTTER RESULTS
FLUTTER (FLCOND = 6)
LABEL = ZONA6 (M=0.95) FLUTTER RESULTS

END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
$
GRID 1 0.0 0.0 0.0 12456
GRID 2 2.196 0.0 0.0 12456
GRID 3 4.392 0.0 0.0 12456
GRID 4 6.588 0.0 0.0 12456
GRID 5 8.784 0.0 0.0 12456
GRID 6 10.75 0.0 0.0 12456
GRID 7 13.17 0.0 0.0 12456
GRID 8 15.37 0.0 0.0 12456
GRID 9 17.56 0.0 0.0 12456
GRID 10 19.76 0.0 0.0 12456
GRID 11 21.96 0.0 0.0 12456
$
GRID 12 3.1866 3.0 0.0 12456
GRID 13 5.3079 3.0 0.0 12456
GRID 14 7.4293 3.0 0.0 12456
GRID 15 9.5506 3.0 0.0 12456
GRID 16 11.672 3.0 0.0 12456
GRID 17 13.650 3.0 0.0 12456
GRID 18 15.914 3.0 0.0 12456
GRID 19 18.036 3.0 0.0 12456
GRID 20 20.157 3.0 0.0 12456
GRID 21 22.278 3.0 0.0 12456
GRID 22 24.400 3.0 0.0 12456
$
GRID 23 6.3732 6.0 0.0 12456
GRID 24 8.4199 6.0 0.0 12456
GRID 25 10.466 6.0 0.0 12456
GRID 26 12.513 6.0 0.0 12456
GRID 27 14.560 6.0 0.0 12456
GRID 28 16.600 6.0 0.0 12456
GRID 29 18.653 6.0 0.0 12456
GRID 30 20.700 6.0 0.0 12456
GRID 31 22.744 6.0 0.0 12456
GRID 32 24.793 6.0 0.0 12456
GRID 33 26.840 6.0 0.0 12456
$
GRID 34 9.5598 9.0 0.0 12456
GRID 35 11.531 9.0 0.0 12456
GRID 36 13.504 9.0 0.0 12456
GRID 37 15.476 9.0 0.0 12456

```



33

+1T14	0.113	0.166	0.225	0.306	0.402	0.538	0.697	0.914	M1T22
+1T22	0.195	0.317	0.462	0.628	0.816	1.03	1.27	1.56	M1T30
+1T30	1.88	2.25	2.68	0.815	1.08	1.38	1.70	2.05	M1T38
+1T38	2.45	2.86	3.32	3.84	4.41	5.03	2.01	2.42	M1T46
+1T46	2.87	3.35	3.86	4.43	5.00	5.63	6.30	7.03	M1T54
+1T54	7.80	3.80	4.36	4.95	5.57	6.22	6.97	7.63	M1T62
+1T62	8.39	9.19	10.0	10.9	6.16	6.85	7.56	8.29	M1T70
+1T70	9.06	9.96	10.7	11.5	12.4	13.3	14.3	9.05	M1T78
+1T78	9.82	10.6	11.4	12.3	13.3	14.0	14.9	15.9	M1T86
+1T86	16.9	17.9	12.4	13.2	14.0	14.9	15.8	16.8	M1T94
+1T94	17.6	18.5	19.5	20.5	21.5	16.0	16.8	17.7	M1T102
+1T102	18.6	19.5	20.6	21.3	22.2	23.2	24.2	25.1	M1T110
+1T110	19.8	20.6	21.5	22.4	23.2	24.4	25.0	26.0	M1T118
+1T118	26.9	27.8	28.8	2	1	-0.351	-0.128	0.00	M2T3
+2T3	0.0	0.0	0.0	0.0	0.0	0.0	-0.686	-2.28	M2T11
+2T11	0.137	0.335	0.514	0.668	0.767	0.778	0.636	0.238	M2T19
+2T19	-0.719	-2.35	-4.79	1.62	2.16	2.59	2.83	2.83	M2T27
+2T27	2.50	1.74	0.444	-1.50	-4.11	-7.53	5.22	5.84	M2T35
+2T35	6.13	6.03	5.48	4.35	2.76	0.476	-2.47	-6.10	M2T43
+2T43	-10.6	10.5	10.7	10.4	9.51	8.05	5.90	3.28	M2T51
+2T51	-0.074	-4.09	-8.80	-14.4	16.5	15.8	14.4	12.5	M2T59
+2T59	9.91	6.41	2.86	-1.61	-6.72	-12.5	-19.2	22.0	M2T67
+2T67	20.0	17.4	14.3	10.5	5.47	1.16	-4.39	-10.5	M2T75
+2T75	-17.3	-24.9	25.9	22.6	18.70	14.3	9.40	3.17	M2T83
+2T83	-2.01	-8.48	-15.5	-23.0	-31.30	27.40	22.90	17.9	M2T91
+2T91	12.40	6.52	-0.653	-6.50	-13.60	-21.2	-29.2	-37.9	M2T99
+2T99	26.30	20.70	14.80	8.64	2.11	-6.59	-11.9	-19.4	M2T107
+2T107	-27.3	-35.6	-44.50	22.6	16.50	10.2	3.58	-3.28	M2T115
+2T115	-12.4	-17.8	-25.6	-33.7	-42.3	-52.6	3	1	M3T0
+3T0	0.083	0.028	0.0	0.0	0.0	0.0	0.0	0.0	M3T8
+3T8	0.0	-0.566	-2.30	0.004	-0.034	-0.092	-0.196	-0.371	M3T16
+3T16	-0.631	-1.12	-1.95	-3.60	-6.19	-10.3	-1.62	-0.366	M3T24
+3T24	-0.694	-1.20	-1.95	-3.06	-4.68	-6.99	-10.2	-14.30	M3T32
+3T32	-20.0	-1.714	-1.25	-2.02	-3.13	-4.64	-6.76	-9.32	M3T40
+3T40	-12.7	-16.80	-21.90	-28.4	-1.45	-2.36	-3.62	-5.29	M3T48
+3T48	-7.44	-10.20	-13.4	-17.2	-21.7	-26.90	-33.20	-1.70	M3T56
+3T56	-2.93	-4.55	-6.59	-9.06	-12.2	-15.3	-19.1	-23.3	M3T64
+3T64	-27.9	-33.4	-0.549	-1.96	-3.72	-5.83	-8.27	-11.4	M3T72
+3T72	-14.1	-17.4	-20.8	-24.5	-28.7	2.87	1.46	-0.219	M3T80
+3T80	-2.15	-4.31	-6.98	-9.13	-11.7	-14.3	-16.8	-19.6	M3T88
+3T88	9.08	7.77	6.27	4.61	2.83	0.748	-0.857	-2.67	M3T96
+3T96	-4.39	-5.96	-7.42	17.9	16.6	15.3	13.9	12.4	M3T104
+3T104	10.7	9.73	8.52	7.48	6.67	6.20	28.2	26.9	M3T112
+3T112	25.7	24.5	23.4	22.1	21.4	20.7	20.3	20.2	M3T120
+3T120	21.0	4	1	-1.08	-0.416	0.0	0.0	0.0	M4T5
+4T5	0.0	0.0	0.0	0.0	-1.42	-5.22	0.482	1.01	M4T13
+4T13	1.43	1.73	1.85	1.77	1.34	-0.436	-1.56	-4.92	M4T21
+4T21	-10.7	4.61	5.67	6.33	6.46	6.01	4.90	3.04	M4T29
+4T29	0.289	-3.49	-8.37	-15.5	12.80	13.2	12.9	11.7	M4T37
+4T37	9.63	6.71	3.29	-0.953	-5.84	-11.4	-18.8	21.7	M4T45
+4T45	20.1	17.6	14.4	10.5	5.98	1.43	-3.46	-8.44	M4T53
+4T53	-13.4	-19.6	26.5	22.3	17.6	12.6	7.55	2.16	M4T61
+4T61	-2.14	-6.40	-10.1	-13.0	-16.0	23.7	17.6	11.8	M4T69
+4T69	6.36	1.49	-3.13	-5.83	-7.94	-8.79	-8.18	-6.13	M4T77
+4T77	13.0	6.90	1.72	-2.42	-5.38	-7.16	-7.28	-5.93	M4T85
+4T85	-2.81	2.36	10.5	-2.49	-6.48	-9.10	-10.3	-9.97	M4T93
+4T93	-7.71	-4.51	0.890	8.34	18.2	32.5	-17.3	-17.6	M4T101
+4T101	-16.5	-14.10	-10.1	-2.75	2.83	12.1	23.7	38.2	M4T109
+4T109	58.3	-26.2	-22.9	-18.6	-13.0	-5.87	5.57	13.6	M4T117
+4T117	26.7	42.8	63.6	104.0	5	1	-0.053	-0.03	M5T2
+5T2	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-2.72	M5T10
+5T10	-12.1	0.087	0.130	0.118	-0.006	-0.302	-0.821	-1.92	M5T18
+5T18	-4.00	-8.76	-17.0	-35.0	0.674	0.589	0.213	-0.596	M5T26
+5T26	-2.0	-4.24	-7.70	-12.9	-20.4	-30.7	-50.1	1.88	M5T34
+5T34	1.26	0.099	-1.75	-4.41	-8.14	-12.6	-18.2	-24.7	M5T42
+5T42	-32.1	-44.6	3.88	2.49	0.521	-2.04	-5.10	-8.63	M5T50
+5T50	-12.0	-15.2	-17.6	-18.7	-19.1	6.74	4.64	2.28	M5T58
+5T58	-0.164	-2.42	-4.27	-4.97	-4.35	-1.70	3.76	14.5	M5T66
+5T66	9.50	7.07	4.97	3.43	2.75	3.43	5.25	9.13	M5T74
+5T74	15.3	24.3	40.1	10.0	7.77	6.38	6.00	6.79	M5T82
+5T82	9.30	12.4	17.4	23.9	32.1	45.4	5.49	3.89	M5T90
+5T90	3.33	3.82	5.31	8.10	10.9	14.6	18.5	22.5	M5T98
+5T98	27.8	-5.57	-6.15	-5.98	-5.15	-3.85	-1.94	-0.901	M5T106
+5T106	0.032	-0.069	-1.91	-6.70	-21.1	-20.7	-20.2	-19.5	M5T114
+5T114	-18.9	-19.0	-19.7	-22.3	-27.4	-37.5	-70.9		
\$									
EIGR	10	GIV	5.	200.		5			+EI
+EI	MASS								
\$									\$
\$									\$
\$									\$
\$									\$
\$									\$
DMI	MAA	RDP	DIAG	5	5				+D3
+D3	1	1	1.	2	2	1.	3	3	+D4
+D4	1.	4	4	1.	5	5	1.		
\$									\$
\$									\$
\$									\$
\$									\$
DMI	KAA	RDP	DIAG	5	5				+D1
+D1	1	1	3637.72	2	2	57502.973		3	+D2
+D2	92282.714		4	330846.95		5	550752.7		
\$									\$
\$									\$
\$									\$
\$									\$
\$									\$
DMI	KFLUT	CDP	DIAG	5	5				+D5

```

+D5 1 1 3637.72 0. 2 2 57502.970. +D6
+D6 3 3 92282.710. 4 4 330846.90. +D7
+D7 5 5 550752.70.
$
$
$ *****
$
$ Z A E R O I N P U T
$
$ *****
$
$ THIS CASE DEMONSTRATES THE USE OF THE TRANSONIC (ZTAIC) AND SUBSONIC
$ (ZONA6) METHODS FOR FLUTTER ANALYSIS OF THE AGARD STANDARD 445.6 WING
$ (WEAKENED WING MODEL) WITH THE P-K AND K FLUTTER METHODS.
$
$...1...2...3...4...5...6...7...8...9...10...
$
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS *
$
$ AERO MODEL SYMMETRY IS REQUESTED ABOUT THE X-Z PLANE. A REFERENCE
$ DENSITY OF 1.145E-07 SLINCHES (SEA LEVEL) AND REFERENCE CHORD OF
$ 21.96 INCHES IS SPECIFIED.
$
$ ACSID XZSYM RHOREF REFC REFB REFS GREF
AEROZ YES 1.145-7 21.96
$
$ 6 MKAEROZ BULK DATA CARDS ARE SPECIFIED FOR AIC'S TO BE COMPUTED FOR
$ 3 MACH NUMBERS (0.678, 0.9 AND 0.95) AND FOR TWO METHODS. THE FIRST
$ METHOD IS THE NONLINEAR (ZTAIC) AERODYNAMICS METHOD REQUESTED BY
$ SETTING THE METHOD FLAG = 1. THE SECOND METHOD IS FOR LINEAR (ZONA6)
$ AERODYNAMICS WITH THE METHOD FLAG SET TO 0. ALL AIC'S ARE SAVED IN
$ FILES FOR RESTART RUN CAPABILITY. FILENAMES INCLUDE THE MACH NUMBER
$ AND METHOD NAME ACRONYM (ZT=ZTAIC AND Z6=ZONA6). REDUCED FREQUENCY
$ INPUT ARE THE SAME FOR ALL MKAEROZ CARDS.
$
$ * * * MACH = 0.678 * * *
$
$ IDMK MACH METHOD IDFLT SAVE <--FILENAME--> PRINT
MKAEROZ 10 0.678 1 0 SAVE AGARD678ZT +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$ MKAEROZ 20 0.678 0 0 SAVE AGARD678Z6 +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$ * * * MACH = 0.900 * * *
$
$ MKAEROZ 30 0.90 1 0 SAVE AGARD90ZT +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$ MKAEROZ 40 0.90 0 0 SAVE AGARD90Z6 +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$ * * * MACH = 0.950 * * *
$
$ MKAEROZ 50 0.95 1 0 SAVE AGARD95ZT +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$ MKAEROZ 60 0.95 0 0 SAVE AGARD95Z6 +MK1
+MK1 0.001 .025 .05 0.075 0.09 0.09333 0.095 0.09666 +MK2
+MK2 0.10 .15 .2 .25 .3 .35 .4 .5
$
$
$ * WING MACROELEMENTS *
$
$ AGARD STANDARD 445.6 WING (20 CHORDWISE AERO BOXES EVENLY CUT AND
$ 11 SPANWISE AERO BOXES WITH CUTS BASED ON SPAN LOCATIONS
$ SPECIFIED IN PERCENTAGE OF SPAN LENGTH IN AN AEFAC BULK DATA
$ CARD WITH SID OF 10). THE ZTAIC ENTRY REFERS TO A ZTAIC BULK DATA
$ CARD WITH AN ID OF 1001 THAT ESTABLISHES THE STEADY PRESSURE INPUT
$ FOR THIS WING MACROELEMENT.
$
$ WID LABEL ACOORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7
CAERO7 1001 WING 12 21 10 1001
$ XRL YRL ZRL RCH LRCHD ATTCHR
+CA1 0.0 0.0 0.0 21.96 0 0
$ XRT YRT ZRT TCH LTCHD ATTCHT
+CA2 31.866 30.0 0.0 14.496 0 0
$
$ SID D1 D2 ETC
AEFACT 10 0.0 16.45 27.25 37.75 47.75 57.15 65.75
+AE1 73.5 80. 85. 90. 100.
$
$
$ * SURFACE SPLINE FIT ON THE WING *
$
$ THE INFINITE PLATE SPLINE METHOD IS USED TO SPLINE THE WING AERO

```

```

$ BOXES TO THE WING STRUCTURE GRIDS. THE SETK BULK DATA CARD REFERS $
$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES $
$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=60) BULK DATA CARD. $
$ $ $ $ $ $ $ $ $ $ $
$ EID MODEL CP SETK SETG DZ EPS $
$ SPLINE1 10 WING 10 60 $
$ $ $ $ $ $ $ $ $ $ $
$ SETID MACROID BOX1 BOX2 $
$ PANLST1 10 1001 1220 $
$ $ $ $ $ $ $ $ $ $ $
$ SID G1 G2 ETC $
$ SET1 60 1 THRU 121 $
$ $ $ $ $ $ $ $ $ $ $
$ $ $ $ $ $ $ $ $ $ $
$ * * FLUTTER ANALYSIS * * $
$ $ $ $ $ $ $ $ $ $ $
$ SIX FLUTTER CARDS ARE USED. EACH FLUTTER CARD REFERS TO A SPECIFIC $
$ MKAEROZ BULK DATA CARD THAT SPECIFIES THE MACH NUMBER, REDUCED $
$ FREQUENCIES AND METHOD USED (I.E. LINEAR OR NONLINEAR) IN THE $
$ ANALYSIS. ALL FLUTTER CARDS REQUEST BOTH THE P-K AND K FLUTTER $
$ SOLUTION METHODS AND REFERENCE THE SAME FLFACT CARD (SID=40) WHICH $
$ LISTS THE VELOCITIES USED BY THE P-K METHOD. EACH FLUTTER BULK DATA $
$ CARD SPECIFIES DIFFERENT DENSITY RATIOS (VIA THE DENS ENTRY) TO $
$ PERFORM A MATCHPOINT ANALYSIS. AIR DENSITY VALUES ARE COMPUTED FROM: $
$ DENSITY RATIO X RHOREF (WHERE RHOREF IS SPECIFIED BY THE AEROZ BULK $
$ DATA CARD). $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.678 - ZTAIC FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID $
$ FLUTTER 1 PKK 301 10 40 +FL1
$ SYMXZ SYMXY EPS CURVFIT PRINT $
$ +FL1 1 $
$ $ $ $ $ $ $ $ $ $ $
$ SID F1 F2 ETC $
$ FLFACT 40 8000. 8400. 9600. 10800. 12000. 13200. 14400. $
$ FLFACT 301 .17 .18 .19 .20 .22 $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.678 - ZONA6 FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ FLUTTER 2 PKK 302 20 40 +FL1
$ +FL1 1 $
$ FLFACT 302 .18 .182 .184 .186 .188 $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.9 - ZTAIC FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ FLUTTER 3 PKK 303 30 40 +FL1
$ +FL1 1 $
$ FLFACT 303 .07 .075 .08 .0825 .085 .0875 .09 $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.9 - ZONA6 FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ FLUTTER 4 PKK 304 40 40 +FL1
$ +FL1 1 $
$ FLFACT 304 .082 .084 .085 .086 .088 $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.95 - ZTAIC FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ FLUTTER 5 PKK 305 50 40 +FL1
$ +FL1 1 $
$ FLFACT 305 .052 .054 .055 .056 .058 .059 $
$ $ $ $ $ $ $ $ $ $ $
$ * MACH 0.95 - ZONA6 FLUTTER CASE * $
$ $ $ $ $ $ $ $ $ $ $
$ FLUTTER 6 PKK 306 60 40 +FL1
$ +FL1 1 $
$ FLFACT 306 .065 .066 .067 .068 .069 $
$ $ $ $ $ $ $ $ $ $ $
$ $ $ $ $ $ $ $ $ $ $
$ * * TRANSONIC DATA FOR ZTAIC METHOD * * $
$ $ $ $ $ $ $ $ $ $ $
$ THE ZTAIC BULK DATA CARD IS REFERRED TO BY THE ZTAIC ENTRY OF THE $
$ CAERO7 (WING MACROELEMENT) BULK DATA CARD. THE ZTAIC CARD REFERS $
$ TO 3 MACHCP BULK DATA CARDS THAT ESTABLISH THE MACH NUMBER AND $
$ STEADY INPUT PRESSURE RELATIONS. SPAN LOCATION AND CORRESPONDING $
$ STEADY PRESSURE FOR THAT SECTION ARE SPECIFIED BY THE SPANID AND $
$ CHDCP ENTRIES, RESPECTIVELY. FOR EXAMPLE: $
$ THE STEADY PRESSURE INPUT FOR MACH 0.678 AT WING SPANWISE STATIONS 1 $
$ THRU 11 IS ESTABLISHED BY THE MACHCP CARD WITH ID=1001. TO ESTABLISH $
$ CORRESPONDENCE WITH AIC DATA, THIS STEADY PRESSURE MACH NUMBER OF $
$ 0.678 MUST IDENTICALLY EXIST IN ONE OF THE MKAEROZ BULK DATA CARDS $
$ WITH THE NONLINEAR METHOD ACTIVE (IN THIS CASE MKAEROZ WITH IDMK=10). $
$ THE SPANWISE STATION INDICIES CORRESPOND TO THE WING MACROELEMENT $
$ SPAN DIVISIONS CENTERLINE LOCATIONS. IN THIS CASE AN AEFAC BULK $
$ DATA CARD WITH SID=10 IS USED TO SPECIFY THE SPANWISE WING MACRO- $
$ ELEMENT CUTS. THEREFORE, SPANID=1 REFERS TO THE WING SPAN LOCATION $
$ OF 8.225%, SPANID=2 REFERS TO THE WING SPAN LOCATION OF 21.85%, ETC. $
$ THE CHORDWISE STRIP STEADY PRESSURE AT MACH 0.678 AT 8.225% IS GIVEN $
$ IN A CHORDCP BULK DATA CARD WITH ID=1001, AT 21.85% IS GIVEN IN A $
$ CHORDCP BULK DATA CARD WITH ID=1002, ETC. $
$ $ $ $ $ $ $ $ $ $ $
$ NOTE: THE CHORDCP BULK DATA CARDS ARE IN THE INCLUDE FILES (SEE BELOW)$

```

```

$
$ ZTAIC 1001 NFLAP MACHCP MACHCP ETC
1001 1001 1002 1003
$
$ ID MACH IGRID INDICA SPANID CHDCP SPANID CHDCP
MACHCP 1001 0.678 0 0 1 1001 2 2001 +MC1
$ SPANID CHDCP ETC
+MC1 3 3001 4 4001 5 5001 6 6001 +MC2
+MC2 7 7001 8 8001 9 9001 10 10001 +MC3
+MC3 11 11001
$
MACHCP 1002 0.9 0 0 1 1002 2 2002 +MC1
+MC1 3 3002 4 4002 5 5002 6 6002 +MC2
+MC2 7 7002 8 8002 9 9002 10 10002 +MC3
+MC3 11 11002
$
MACHCP 1003 0.95 0 0 1 1003 2 2003 +MC1
+MC1 3 3003 4 4003 5 5003 6 6003 +MC2
+MC2 7 7003 8 8003 9 9003 10 10003 +MC3
+MC3 11 11003
$
$ TWO SETS OF STEADY PRESSURE INPUT DATA ARE USED IN THE PRESENT
$ ANALYSIS (TRANSONIC SMALL DISTURBANCE [FROM CAPTSD CODE] AND
$ NAVIER-STOKES [FROM ENSAERO CODE]). AN INCLUDE STATEMENT IS USED
$ TO REQUEST THE DESIRED PRESSURE TO BE USED. ONLY ONE STEADY PRESSURE
$ INPUT CAN BE USED AT A TIME. THE USER IS INSTRUCTED TO UNCOMMENT THE
$ DESIRED INCLUDE FILE CONTAINING THE DESIRED STEADY PRESSURE INPUT.
$ NOTE THAT STEADY PRESSURE INPUT FOR ALL 3 MACH NUMBERS
$ (0.678,0.9,0.95) ARE INCLUDED IN EACH FILE.
$
$ INCLUDE tsdcp.inp
$ INCLUDE nscp.inp
$
$
$ ENDDATA

```

### 3.0 STATIC AEROELASTICITY (TRIM CASES)

#### 3.1 Case 1: Forward Swept Wing in Level Flight (HA144A)

- **Purpose:** Demonstrate a wing + canard configuration symmetric trim case at subsonic (ZONA6 method) and supersonic (ZONA7 method) Mach numbers.

- **Description of Input:**

A Forward Swept Wing (FSW) + canard airplane (modified HA144A case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68) is considered for the present case. The structural and aerodynamic models are shown in Fig 3.1.1.

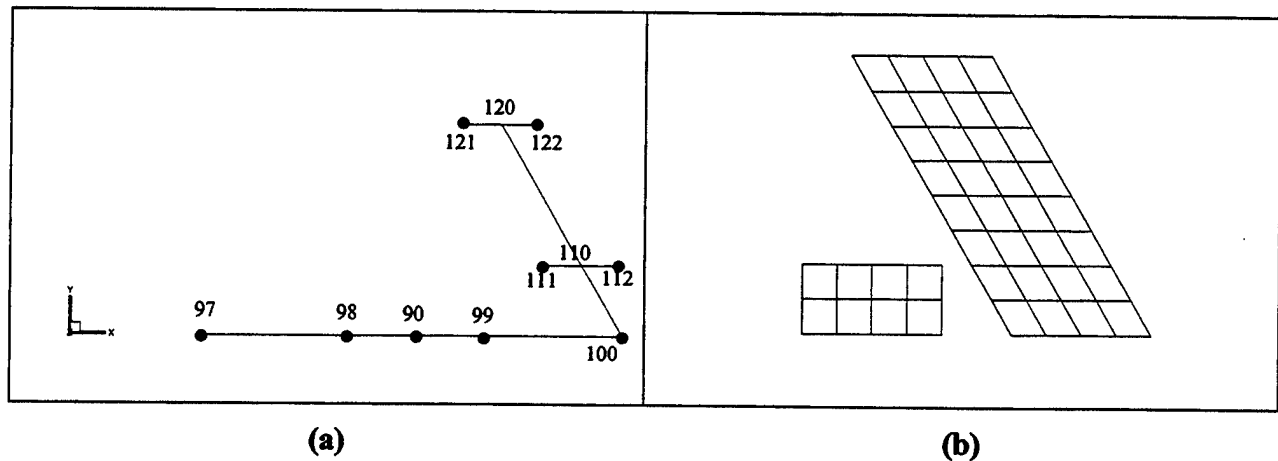


Figure 3.1.1 Forward Swept Wing (FSW) (a) Structural Model and (b) Aerodynamic Model.

#### - Solution Control

Three symmetric static aeroelastic (SZAERO) analyses are requested for each of the desired flight Mach numbers and dynamic pressures. The boundary conditions are as follows: MPC=100 (Multipoint Constraints) of the rigid bar element connections of the wing structure; SPC=1 (Single Point Constraints) constraining all degrees of freedom of GRID's 90, 97, 98, 99 and 100 except the z-axis translation and rotation about the y-axis; and SUPPORT=1 (Fictitious Support) for determinant reactions along the z-axis translation and rotation about the y-axis in the free body analysis.

#### - Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide (Version 68) for a description of the structural model.

### *- Aerodynamic Parameters / Flight Conditions*

An **AEROZ** bulk data card is used to specify a symmetric model about the x-z plane. A reference chord of 10ft, reference span of 40ft and reference area of 400ft<sup>2</sup> for the full model is specified. The reference grid about which the stability derivative calculations are made is defined by GREF=90.

Two **MKAEROZ** bulk data cards are used for Mach 0.9 and 1.3. Reduced frequency input is not required for this case, since only static aeroelastic analysis is performed.

### *- Aerodynamic Model*

Two **CAERO7** bulk data cards are used to define the wing and canard wing macroelements with (chord aero boxes x span aero boxes) 4 x 8 and 4 x 2 evenly cut aerodynamic boxes, respectively. A **PAFOIL7** card is used to define the airfoil camber to simulate the incidence angle of 0.1 deg used in the corresponding MSC/NASTRAN case (HA144A). This was done to account for differences between test and theory experimental pressure data at some reference condition.

An **AESURFZ** card is used to define the entire canard as a control surface. A **COORD2R** card is used to define the y-axis hinge line of the control surface (in this case hinged at quarter chord).

### *- Spline*

The infinite plate spline method (**SPLINE1**) is used to spline all wing aerodynamic boxes to the structural grid points of the wing section. A beam spline (**SPLINE3**) is used to spline the canard to the structural grid points 98 and 99.

### *- Trim*

Three **TRIM** bulk data cards are used to specify the following three trim flight conditions: (1) M=0.9, q=40 psf; (2) M=0.9, q=1200psf; and (3) M=1.3, q=1151psf; all in 1-G level flight. Trim parameters imposed for all three trim flight conditions are: no pitch rate (QRATE=0.0), 1-G load factor (NZ=32.2), and zero pitch acceleration (QACCEL=0.0). Aircraft angle-of-attack (ALPHA) and control surface rotation (ELEV) are set to FREE to be determined by the trim analysis.

### *• Description of Output:*

The three flight conditions considered in this case are: Mach 0.9 at dynamic pressures equal to 40psf and 1200psf as well as Mach 1.3 at a dynamic pressure of 1151psf. Table 3.1.1 shows the longitudinal aerodynamic stability derivatives of the rigid and flexible aircraft at Mach 0.9. Excellent agreement can be seen between the ASTROS\* results and those of MSC/NASTRAN. Also, good agreement is obtained for the final trim results. Similarly, good agreement for the Mach 1.3 case can be seen in Table 3.1.2 for both stability derivatives and trim results.

**Table 3.1.1 Longitudinal Stability Derivatives of FSW Aircraft at Mach 0.9.**

Derivative	ASTROS* Results			MSC/NASTRAN Results		
	Value for Rigid Airplane	Unrestrained Value q=40 psf	Unrestrained Value q=1200 psf	Value for Rigid Airplane	Unrestrained Value q=40 psf	Unrestrained Value q=1200 psf
$C_{Z_0}$	0.0084	0.0085	0.0127	0.0084	0.0085	0.0127
$C_{M_0}$	-0.0064	-0.0065	-0.0096	-0.006	-0.0061	-0.0087
$C_{Z_\alpha}$	5.098	5.155	7.7412	5.071	5.127	7.772
$C_{M_\alpha}$	-3.131	-3.173	-5.063	-2.871	-2.907	-4.557
$C_{Z_q}$	12.516	12.606	16.604	12.074	12.158	16.100
$C_{M_q}$	-10.875	-10.941	-13.874	-9.954	-10.007	-12.499
$C_{Z_{\delta_e}}$	0.2551	0.2597	0.4680	0.2461	0.2520	0.5219
$C_{M_{\delta_e}}$	0.5671	0.5638	0.4143	0.5715	0.5678	0.3956

Note: Units are (1/rad).

Trim Results (flexible aircraft):

	ASTROS* Results		MSC/NASTRAN Results		
	q=40 psf	q=1200 psf	q=40 psf	q=1200 psf	
Pitch Rate	0.00	0.00	0.00	0.00	(User Input)
Load Factor	32.20	32.20	32.20	32.20	(User Input)
Pitch Acceleration	0.00	0.00	0.00	0.00	(User Input)
Angle of Attack	9.54	0.177	9.69	0.079	(Computed)
Control Surface Rotation	31.48	1.156	28.22	1.107	(Computed)

Note: Units in degrees.

**Table 3.1.2 Longitudinal Stability Derivatives of FSW Aircraft at Mach 1.3.**

Derivative	ASTROS* Results		MSC/NASTRAN Results	
	Value for Rigid Airplane	Unrestrained Value q=1151 psf	Value for Rigid Airplane	Unrestrained Value q=1151 psf
$C_{Z_0}$	0.0074	0.0087	0.0074	0.0086
$C_{M_0}$	-0.0072	-0.0085	-0.0072	-0.0083
$C_{Z_\alpha}$	4.8473	5.8156	4.847	5.783
$C_{M_\alpha}$	-3.8845	-4.800	-3.885	-4.728
$C_{Z_q}$	9.5399	9.9148	9.055	9.305
$C_{M_q}$	-10.5375	-10.8857	-10.149	-10.360
$C_{Z_{\delta_e}}$	0.6346	0.8467	0.6346	0.8802
$C_{M_{\delta_e}}$	0.2378	0.0348	0.2378	0.0105

Note: Units are (1/rad).



## Trim Results (flexible aircraft):

	ASTROS* Result	NASTRAN	
Pitch Rate	0.00	0.00	(User Input)
Load Factor	32.20	32.20	(User Input)
Pitch Acceleration	0.00	0.00	(User Input)
Angle of Attack	0.1025	-0.003	(Computed)
Control Surface Rotation	1.649	1.734	(Computed)

Note: Units in degrees.

## • Input Data Listing:

### Listing 2.6 Input Data for the Forward Swept Wing in Level Flight (HA144A).

```

ASSIGN DATABASE HA144A PASS NEW DELETE
SOLUTION
TITLE = ZAERO TRIM CASE (HA144A): FORWARD SWEEP WING IN LEVEL FLIGHT
SUBTITLE = SUBSONIC (M=0.9) AND SUPERSONIC (M=1.2) STABILITY DERIVATIVES
ANALYZE
  BOUNDARY MPC = 100, SPC = 1, SUPPORT = 90
  LABEL = SYMMETRIC FLIGHT CONDITIONS, ZAERO MODULE AERODYNAMICS
  SAERO SYMMETRIC ( TRIM = 1 )
  PRINT TRIM
  LABEL = TRIM CASE #1 - M = 0.9, Q = 40 PSF
  SAERO SYMMETRIC ( TRIM = 2 )
  PRINT TRIM
  LABEL = TRIM CASE #2 - M = 0.9, Q = 1200 PSF
  SAERO SYMMETRIC ( TRIM = 3 )
  PRINT TRIM
  LABEL = TRIM CASE #3 - M = 1.3, Q = 1151 PSF
END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
GRID 90      15.    0.    0.
GRID 97      0.    0.    0.
GRID 98      10.    0.    0.
GRID 99      20.    0.    0.
GRID 100     30.    0.    0.
ASET 999     3      90
$
$          * WING GRIDS *
$
$ ID      CP      X1      X2      X3      CD      PS      SEID
$ GRID 111      24.61325 +5.    0.
$ GRID 110      27.11325 +5.    0.
$ GRID 112      29.61325 +5.    0.
$ GRID 121      18.83975 +15.    0.
$ GRID 120      21.33975 +15.    0.
$ GRID 122      23.83975 +15.    0.
$
$          * * STRUCTURAL STIFFNESS PROPERTIES * *
$
$          * FUSELAGE STRUCTURE *
$
$ EID      PID      GA      GB      X1,GO      X2      X3
$ CBAR 101      100      97      98      0.    0.    1.
$ CBAR 102      100      98      90      0.    0.    1.
$ CBAR 100      100      90      99      0.    0.    1.
$ CBAR 103      100      99      100     0.    0.    1.
$
$
$ PID      MID      A      I1      I2      J      NSM
$ PBAR 100      1      2.0    .173611 0.15 0.5
$ C1      C2      D1      D2      E1      E2      F1      F2
$ +PB1 1.0      1.0      1.0    -1.0   -1.0  1.0   -1.0   -1.0
$ K1      K2      I12
$ +PB2 0.0
$
$          * WING STRUCTURE *
$
$ EID      PID      GA      GB      X1,GO      X2      X3
$ CBAR 110      101      100      110      0.    0.    1.
$ CBAR 120      101      110      120      0.    0.    1.
$
$
$ SETID     EID      GA      GB      CNA      CNB      CMA      CMB
$ RBAR 100      111      110      111      123456
$ RBAR 100      112      110      112      123456
$ RBAR 100      121      120      121      123456
$ RBAR 100      122      120      122      123456
$
$ PID      MID      A      I1      I2      J      NSM

```

```

PBAR 101 1 1.5 0.173611+2.0 0.462963 +PB3
$ C1 C2 D1 D2 E1 E2 F1 F2 $
+PB3 0.5 3.0 0.5 -3.0 -0.5 3.0 -0.5 -3.0 +PB4
$ K1 K2 I12 $
+PB4 0.0 $
$ MID E G NU RHO A TREF GE $
MAT1 1 1.44+9 5.40+8 $
$
$ * * MASS AND INERTIA PROPERTIES * *
$
$ * FUSELAGE MASSES *
$
$ EID G CID M X1 X2 X3 $
CONM2 97 97 0 46.6215
CONM2 98 98 0 46.6215
CONM2 99 99 0 46.6215
CONM2 100 100 0 46.6215
$
$ * WING MASSES *
$
$ CONM2 111 111 0 18.648
CONM2 112 112 0 12.4324
CONM2 121 121 0 18.648
CONM2 122 122 0 12.4324
$
$
$ * * STRUCTURAL CONSTRAINTS * *
$
$ SID C G1 G2 G3 G4 $
SPC1 1 1246 90
SPC1 1 246 97 98 99 100
$
$ SETID ID C $
SUPORT 90 90 35
$
$
$ * * * * *
$
$ Z A E R O I N P U T
$
$ * * * * *
$
$ THIS CASE DEMONSTRATES A FORWARD SWEPT WING + CANARD CONFIGURATION
$ UNDER STEADY AERO TRIM CASES AT SUBSONIC AND SUPERSONIC MACH NUMBERS
$
$ ...1...2...3...4...5...6...7...8...9...10...
$
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS *
$
$ THE REFERENCE GRID FOR STABILITY DERIVATIVE CALCULATIONS IS DEFINED
$ BY GREF=90 WHICH IS LOCATED AT X=15, Y=0.0 AND Z=0.0. THE REFERENCE
$ CHORD IS CHOSEN AS 10FT, REFERENCE SPAN IS CHOSEN AS 40FT AND THE
$ REFERENCE AREA IS 400 SQ FT FOR THE FULL MODEL.
$
$ ACSID XZSYM RHOREF REFC REFB REFS GREF
AEROZ 0 YES 1.0 10.0 40.0 400.0 90
$
$ MKAEROZ BULK DATA CARDS MUST EXIST FOR STEADY AERODYNAMICS AS WELL
$ AS UNSTEADY AERODYNAMICS. IN THIS CASE TWO MACH NUMBERS ARE
$ COMPUTED FOR M=0.9 AND M=3.0. NO REDUCED FREQUENCIES ARE INPUT
$ BECAUSE A TRIM RATHER THAN FLUTTER ANALYSIS IS DESIRED.
$ NOTE: BOTH TRIM AND FLUTTER DISCIPLINES MAY REFERENCE ONE MKAEROZ
$ BULK DATA CARD.
$
$ IDMK MACH METHOD IDFLT SAVE <---FILENAME--> PRINT
MKAEROZ 1000 0.9
MKAEROZ 2000 1.3
$
$
$ * WING MACROELEMENTS *
$
$ FORWARD SWEPT WING - 4 x 8 AERO BOXES EVENLY CUT
$ WID LABEL ACOORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7
CAERO7 1100 WING 9 5 0 1101 +CA1
$ XRL YRL ZRL RCH LRCHD ATTCHR
+CA1 25. 0. 0. 10. 0 0 +CA2
$ XRT YRT ZRT TCH LTCHD ATTCHT
+CA2 13.4529920. 0. 10. 0 0
$
$ A PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL CROSS-SECTION FOR THE
$ ZONA7U METHOD. LIKE THE DMI INPUT USED IN THE HA144A OF THE
$ MSC/NASTRAN AEROELASTIC USER GUIDE, THE PAFOIL7 WILL ACCOUNT FOR THE
$ DIFFERENCES BETWEEN TEST AND THEORY (WING CAMBER EFFECTS).
$
$ ID ITAX ITHR ICAMR RADR ITHT ICAMT RADT
PAFOIL7 1101 1102 1103 1104 0.0 1103 1104 0.0
AEFACT 1102 0.0 50.0 100.0
AEFACT 1103 0.0 0.0 0.0
$ AEFACT TO DESCRIBE THE AIRFOIL CAMBER (0.1 DEG INCIDENCE)
AEFACT 1104 0.0 -0.0872 -0.1744
$
$ CANARD - 4 x 2 AERO BOXES EVENLY CUT
CAERO7 1000 CANARD 3 5 0 +CA1
+CA1 10. 0.0 0.0 10. 0 0 +CA2
+CA2 10. 5.0 0.0 10. 0 0

```

```

$
$ THE ENTIRE CANARD IS DEFINED AS A CONTROL SURFACE BY AN AESURFZ BULK $
$ DATA CARD. THE AESURFZ CARD REFERS TO A PANLST2 BULK DATA CARD WHICH $
$ SPECIFIES THAT AERO BOXES 1000 THROUGH 1007 BE USED AS THE CONTROL $
$ SURFACE. THE AESURFZ CARD REFERENCES A RECTANGULAR COORDINATE SYSTEM $
$ (COORD2R) THAT DEFINES THE Y-AXIS OF THE CONTROL SURFACE HINGE LINE. $
$ THE CONTROL SURFACE IS HINGED ABOUT ITS QUARTER-CHORD. $
$
$ LABEL TYPE CID SETK SETG $
AESURFZ ELEV SYM 1 1000 $
$
$ SETID MACROID BOX1 BOX2 ETC $
PANLST2 1000 1000 1001 1002 1003 1004 1005 +P1 $
+P1 1006 1007 $
$
$ CID RID A1 A2 A3 B1 B2 B3 $
CORD2R 1 0 12.5 0.0 0.0 12.5 0.0 10.0 +CRD2 $
$ C1 C2 C3 $
+CRD2 20.0 0.0 10.0 $
$
$ * SURFACE SPLINE FIT ON THE WING * $
$
$ THE INFINITE PLATE SPLINE METHOD IS USED TO SPLINE THE WING AERO $
$ BOXES TO THE WING STRUCTURE GRIDS. THE SETK BULK DATA CARD REFERS $
$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES $
$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=1105) BULK DATA CARD. $
$
$ EID MODEL CP SETK SETG DZ EPS $
SPLINE1 1601 WING 1100 1105 0.0 $
$
$ SETID MACROID BOX1 BOX2 $
PANLST1 1100 1100 1100 1131 $
$
$ SID G1 G2 ETC $
SET1 1105 100 110 111 112 120 121 122 $
$
$ THE BEAM SPLINE METHOD IS USED ON THE CANARD. THE SETK ENTRY REFERS $
$ TO THE PANLST2 BULK DATA CARD PREVIOUSLY DEFINED FOR THE AESURFZ BULK $
$ DATA CARD LISTING ALL AERO BOXES LOCATED ON THE CANARD. $
$
$ EID MODEL SETK SETG DZ DTOR CID DTHX $
SPLINE2 1501 CANARD 1000 1000 0.0 1.0 1 -1.0 +SP1 $
$ DTHY $
+SP1 -1.0 $
$
$ SID G1 G2 ETC $
SET1 1000 98 99 $
$
$ * TRIM CONDITIONS * $
$
$ THREE TRIM CONDITIONS (ALL AT 1G LEVEL FLIGHT) ARE CONSIDERED FOR $
$ THIS CASE. 1) M=0.9, Q=40.0 PSF, 2) M=0.9, Q=1200.0 PSF AND $
$ 3) M=1.3, Q=1151 PSF. IDMK ENTRIES REFER TO MKAEROZ CARDS THAT $
$ SPECIFY THE MACH NUMBER FOR EACH TRIM CASE. DYNAMIC PRESSURES OF $
$ 40.0, 1200.0, AND 1151.0 ARE SPECIFIED IN THE QDP ENTRIES. A TRIM $
$ TYPE OF PITCH IS SPECIFIED FOR SYMMETRIC TRIM OF LIFT AND PITCHING $
$ MOMENT (2 DOF). TRIM FLIGHT CONDITIONS IMPOSED ARE NO PITCH RATE $
$ (QRATE=0.0) ONE G LOAD FACTOR (NZ=32.2) AND ZERO PITCH ACCELERATION $
$ (QACCEL=0.0). THE ANGLE-OF-ATTACK (ALPHA) AND CANARD SURFACE $
$ ROTATION (ELEV) ARE SET TO FREE TO BE DETERMINED BY THE TRIM ANALYSIS. $
$
$ TRIM CONDITION 1: 1 G LEVEL FLIGHT AT LOW SPEED $
$
$ TRIMID IDMK QDP TRMTYP EFFID VO PRINT $
TRIM 1 1000 40.0 PITCH 1.0 -2 +TR1 $
$ LABEL1 VAL1 LABEL2 VAL2 ETC $
+TR1 QRATE 0.0 NZ 32.2 QACCEL 0.0 ALPHA FREE +TR2 $
+TR2 ELEV FREE $
$
$ TRIM CONDITION 2: 1 G LEVEL FLIGHT AT HIGH SUBSONIC SPEED $
$
$ TRIM 2 1000 1200.0 PITCH 1.0 -2 +TR3 $
+TR3 QRATE 0.0 NZ 32.2 QACCEL 0.0 ALPHA FREE +TR4 $
+TR4 ELEV FREE $
$
$ TRIM CONDITION 3: 1 G LEVEL FLIGHT AT LOW SUPERSONIC SPEED $
$
$ TRIM 3 2000 1151.0 PITCH 1.0 -2 +TR5 $
+TR5 QRATE 0.0 NZ 32.2 QACCEL 0.0 ALPHA FREE +TR6 $
+TR6 ELEV FREE $
$
$ ENDDATA $

```

### 3.2 Case 2: Forward Swept Wing Airplane in Antisymmetric Maneuvers (HA144D)

- **Purpose:** Demonstrate a wing + canard + vertical tail fin configuration antisymmetric trim case at subsonic (ZONA6 method) Mach number.

- **Description of Input:**

The FSW Airplane of Case 1 (Section 3.1) is reconsidered here for its lateral-directional stability characteristics. The half-span model is modified to add a sweptback vertical tail fin and to consider the antisymmetrical motions of the aircraft. The structural and aerodynamic models of the vertical tail fin portion of the aircraft is shown in Fig 3.2.1. The wing + canard aerodynamic models remain unchanged from those of Case 1 (Section 3.1) and are shown in Fig 3.1.1.

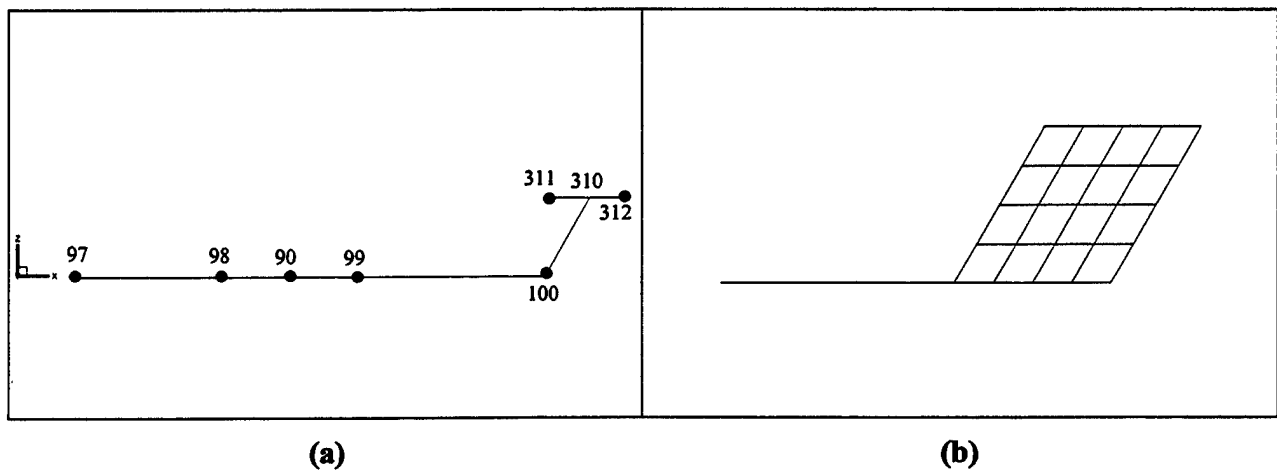


Figure 3.2.1 Side View of FSW Showing the Vertical Tail Fin (a) Structural Model and (b) Aerodynamic Model.

#### - Solution Control

Two symmetric static aeroelastic (SZAERO) analyses are requested both at Mach 0.9 and  $q=1200\text{psf}$ . The boundary conditions are as follows: MPC=100 (Multipoint Constraints) of the rigid bar element connections of the aircraft structure; SPC=2 (Single Point Constraints) constraining all degrees of freedom of GRID's 90, 97, 98, 99 and 100 except the y-axis translation (lateral motion), rotation about the x-axis (roll), and rotation about the z-axis (yaw); and SUPPORT=20 (Fictitious Support) for determinate reactions along the y-axis translation, rotations about the x- and z-axes in the free body analysis.

#### - Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide (Version 68) for a description of the structural model.

### *- Aerodynamic Parameters / Flight Conditions*

The flight conditions for this case are the same as those of Case 1 (Section 3.1), except only one **MKAEROZ** bulk data card is used for Mach 0.9

### *- Aerodynamic Model*

The aerodynamic model is the same as that of Case 1 (Section 3.1) except for the control surface definitions. Two control surfaces are defined for the present case. An aileron is defined on the wing (aerodynamic boxes 1119, 1123, 1127 and 1131) and a rudder is defined on the vertical tail fin (aerodynamic boxes 3103, 3107, 3111, 3115). **COORD2R** cards are used to define the y-axis hinge line of the control surfaces.

### *- Spline*

The spline of the aerodynamic model to the structure is the same as that of Case 1 except for the additional splining of the vertical tail fin to the tail structure. All 16 aerodynamic boxes of the vertical tail fin (3100 through 3115) are splined by the infinite plate spline method to the tail structural **GRID**'s (100, 311, 310, 312).

### *- Trim*

Two subsonic trim cases are considered. The first, **TRIM 1**, finds the steady roll solution for an aileron rotation of 25 degrees (**AILERON**), zero yaw acceleration (**RACCEL**), zero roll acceleration (**PACCEL**), zero yaw rate (**RRATE**) and no side slip acceleration (**NY**). Computed trim parameters are the yaw angle (**BETA**), rudder deflection angle (**RUDDER**) and roll rate (**PRATE**). The second trim condition, **TRIM 2**, is an abrupt roll solution with the same trim conditions imposed in the first trim case, except that roll rate (**PRATE**) is set to zero and the roll acceleration (**PACCEL**) is set to **FREE** to be computed by the trim analysis.

### *• Description of Output:*

Two trim cases (one for steady roll and one for abrupt roll) are examined at Mach 0.9 and dynamic pressure 1200psf. The results of the lateral-directional stability characteristics of **ASTROS\*** and **MSC/NASTRAN** are compared in Table 3.2.1. Excellent agreement is seen between the two sets of results.

The trim results of the first trim case is shown in Table 3.2.2 and the second in Table 3.2.3. Good agreement are obtained for both trim cases.

**Table 3.2.1 Lateral Aerodynamic Stability Derivatives of FSW Aircraft with Vertical Tail at Mach 0.9.**

Derivative	ASTROS* Results		MSC/NASTRAN Results	
	Value for Rigid Airplane	Unrestrained Value q=1200 psf	Value for Rigid Airplane	Unrestrained Value q=1200 psf
$C_{Y\beta}$	-0.7241	-0.7375	-0.7158	-0.7260
$C_{l\beta}$	0.0340	0.0276	0.0328	0.0271
$C_{n\beta}$	-0.2704	-0.2754	-0.2592	-0.2630
$C_{Yp}$	-0.0824	-0.1015	-0.07965	-0.09466
$C_{lp}$	-0.4207	-0.4364	-0.4185	-0.4448
$C_{np}$	-0.0278	-0.0348	-0.0261	-0.0314
$C_{Yr}$	-0.7461	-0.7528	-0.7233	-0.7285
$C_{lr}$	0.0453	0.0382	0.0429	0.0363
$C_{nr}$	-0.2950	-0.2974	-0.2775	-0.2794
$C_{Y\delta r}$	0.3785	0.3641	0.3491	0.3381
$C_{l\delta r}$	-0.0414	-0.0361	-0.03745	-0.03229
$C_{n\delta r}$	0.1902	0.1848	0.1707	0.1665
$C_{Y\delta a}$	-0.1214	-0.1088	-0.1082	-0.1026
$C_{l\delta a}$	-0.2993	-0.2840	-0.2748	-0.2625
$C_{n\delta a}$	-0.0458	-0.0411	-0.03948	-0.03753

Note: Units are (1/rad).

**Table 3.2.2 Trim Set 1 - Steady Roll Solution at Mach 0.9 (flexible aircraft).**

	ASTROS* Results	MSC/NASTRAN Results	
	q=1200 psf	q=1200 psf	
Control Surface Rotation (Deg)	25.00	25.00	(User Input)
Yaw Angle (Deg)	-0.79	-1.05	(Computed)
Yaw Acceleration (Rad/s/s)	0.00	0.00	(User Input)
Roll Acceleration (Rad/s/s)	0.00	0.00	(User Input)
Yaw Rate (Deg/s)	0.00	0.00	(User Input)
Control Surface Rotation (Deg)	1.29	1.18	(Computed)

Roll Rate (Deg/s)	-0.821	-0.745	(Computed)
Side-Slip Acceleration (Rad/s/s)	0.00	0.00	(User Input)

**Table 3.2.3 Trim Set 2 - Abrupt Roll Solution at Mach 0.9 (flexible aircraft).**

	ASTROS* Results	MSC/NASTRAN Results	
	q=1200 psf	q=1200 psf	
Control Surface Rotation (Deg)	25.00	25.00	(User Input)
Yaw Angle (Deg)	-3.78	-3.61	(Computed)
Yaw Acceleration (Rad/s/s)	0.00	0.00	(User Input)
Roll Acceleration (Rad/s/s)	-155	-143	(Computed)
Yaw Rate (Deg/s)	0.00	0.00	(User Input)
Control Surface Rotation (Deg)	0.61	0.63	(Computed)
Roll Rate (Deg/s)	0.00	0.00	(User Input)
Side-Slip Acceleration (Rad/s/s)	0.00	0.00	(User Input)

• **Input Data Listing:**

**Listing 2.7 Input Data for the Forward Swept Wing in Level Flight (HA144D).**

```

ASSIGN DATABASE HA144D PASS NEW DELETE
SOLUTION
TITLE = ZAERO TRIM CASE (HA144D): FORWARD SWEPT WING WITH VERTICAL TAIL
SUBTITLE = SUBSONIC (M=0.9) LATERAL STABILITY DERIVATIVES
ANALYZE
    BOUNDARY MPC=100,SPC=2,SUPPORT=20
    LABEL = ANTISYMMETRIC FLIGHT CONDITIONS, ZAERO MODULE AERODYNAMICS
    SAERO ANTISYMMETRIC ( TRIM=1 )
    PRINT TRIM
    SAERO ANTISYMMETRIC ( TRIM=2 )
    PRINT TRIM
END
BEGIN BULK
$.....2....3....4....5....6....7....8....9....10..
GRID  90      15.  0.  0.
GRID  97      0.  0.  0.
GRID  98     10.  0.  0.
GRID  99     20.  0.  0.
GRID 100     30.  0.  0.
$
$          * WING GRID *
$
$  ID      CP      X1      X2      X3      CD      PS      SEID
GRID 111      24.61325 +5.  0.
GRID 110      27.11325 +5.  0.
GRID 112      29.61325 +5.  0.
GRID 121      18.83975+15.  0.
GRID 120      21.33975+15.  0.
GRID 122      23.83975+15.  0.
$
$          * VERTICAL FIN *
$
GRID 310      32.8667      5.
GRID 311      30.3867      5.
GRID 312      35.3867      5.
$
CBAR 310      301      100      310      0.      0.      1.
$
PBAR 301      1      .75      .086806 1.      .23148
+PB2 .5      3.      .5      -3.      -.5      3.      -.5      -3.      +PB2
+PB3      0.
$
RBAR 100      311      310      311      123456
RBAR 100      312      310      312      123456

```

```

$
CONM2 311 311 0 0.93167
CONM2 312 312 0 0.62112
$
$ * * STRUCTURAL STIFFNESS PROPERTIES * *
$
$ * FUSELAGE STRUCTURE *
$
$ EID PID GA GB X1,GO X2 X3
CBAR 101 100 97 98 0. 0. 1.
CBAR 102 100 98 90 0. 0. 1.
CBAR 100 100 90 99 0. 0. 1.
CBAR 103 100 99 100 0. 0. 1.
$
$ PID MID A I1 I2 J NSM
PBAR 100 1 2.0 .173611 0.15 0.5
$ C1 C2 D1 D2 E1 E2 F1 F2
+PB1 1.0 1.0 1.0 -1.0 -1.0 1.0 -1.0 -1.0
$ K1 K2 I12
+PB2 0.0
$
$ * WING STRUCTURE *
$
$ EID PID GA GB X1,GO X2 X3
CBAR 110 101 100 110 0. 0. 1.
CBAR 120 101 110 120 0. 0. 1.
$
$ SETID EID GA GB CNA CNB CMA CMB
RBAR 100 111 110 111 123456
RBAR 100 112 110 112 123456
RBAR 100 121 120 121 123456
RBAR 100 122 120 122 123456
$
$ PID MID A I1 I2 J NSM
PBAR 101 1 1.5 0.173611+2.0 0.462963
$ C1 C2 D1 D2 E1 E2 F1 F2
+PB3 0.5 3.0 0.5 -3.0 -0.5 3.0 -0.5 -3.0
$ K1 K2 I12
+PB4 0.0
$
$ MID E G NU RHO A TREF GE
MAT1 1 1.44+9 5.40+8
$
$ * * MASS AND INERTIA PROPERTIES * *
$
$ * FUSELAGE MASSES *
$
$ EID G CID M X1 X2 X3
CONM2 97 97 0 46.6215
CONM2 98 98 0 46.6215
CONM2 99 99 0 46.6215
CONM2 100 100 0 46.6215
$
$ * WING MASSES *
$
$ CONM2 111 111 0 18.648
CONM2 112 112 0 12.4324
CONM2 121 121 0 18.648
CONM2 122 122 0 12.4324
$
$ * * STRUCTURAL CONSTRAINTS * *
$
$ SID C G1 G2 G3 G4
SPC1 2 135 90
SPC1 2 35 97 98 99 100
$
$ SETID ID C
SUPPORT 20 90 246
$
$
$ * * * * *
$
$ Z A E R O I N P U T
$
$ * * * * *
$
$ THIS CASE DEMONSTRATES A FORWARD SWEEP WING + CANARD + VERTICAL TAIL
$ CONFIGURATION UNDER STEADY AERO TRIM CASES AT SUBSONIC MACH NUMBER
$
$ ...1...2...3...4...5...6...7...8...9...10...
$
$ * AERO PARAMETERS / FLIGHT CONDITIONS *
$
$ THE REFERENCE GRID FOR STABILITY DERIVATIVE CALCULATIONS IS DEFINED
$ BY GREF=90 WHICH IS LOCATED AT X=15, Y=0.0 AND Z=0.0. THE REFERENCE
$ CHORD IS CHOSEN AS 10FT, REFERENCE SPAN IS CHOSEN AS 40FT AND THE
$ REFERENCE AREA IS 400 SQ FT FOR THE FULL MODEL.
$
$ ACSID XZSYM RHOREF REFC REFB REFS GREF
AEROZ 0 YES 1.0 10.0 40.0 400.0 90
$
$ IDMK MACH METHOD IDFLT SAVE <--FILENAME--> PRINT
MKAEROZ 90 0.9 0 0
$

```



```

$
$ * WING MACROELEMENTS *
$
$
$ FORWARD SWEEP WING - 4 x 8 AERO BOXES EVENLY CUT
$ WID LABEL ACCORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7
CAERO7 1100 WING 9 5 0 1101 +CA1
$ XRL YRL ZRL RCH LRCHD ATTCHR
+CA1 25. 0. 0. 10. 0 0 +CA2
$ XRT YRT ZRT TCH LTCHD ATTCHT
+CA2 13.4529920. 0. 10. 0 0
$
$ A PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL CROSS-SECTION FOR THE
$ ZONA7U METHOD. LIKE THE DMI INPUT USED IN THE HA144A OF THE
$ MSC/NASTRAN AEROELASTIC USER GUIDE, THE PAFOIL7 WILL ACCOUNT FOR THE
$ DIFFERENCES BETWEEN TEST AND THEORY (WING CAMBER EFFECTS).
$
$ ID ITAX ITHR ICAMR RADR ITHT ICAMT RADT
PAFOIL7 1101 1102 1103 1104 0.0 1103 1104 0.0
AEFACT 1102 0.0 50.0 100.0
AEFACT 1103 0.0 0.0 0.0
$ AEFACT TO DESCRIBE THE AIRFOIL CAMBER (0.1 DEG INCIDENCE)
AEFACT 1104 0.0 -0.0872 -0.1744
$
$ CANARD - 4 x 2 AERO BOXES EVENLY CUT
CAERO7 1000 CANARD 3 5 0
+CA1 10. 0.0 0.0 10. 0 0 +CA1
+CA2 10. 5.0 0.0 10. 0 0 +CA2
$
$ DEFINITION OF VERTICAL FIN 4 x 4 EVENLY CUT
CAERO7 3100 FIN 5 5 0
+CA1 30.7735 0. 10. 10. 0 0 +CA1
+CA2 25. 0. 0. 10. 0 0 +CA2
$
$ TWO CONTROL SURFACES ARE DEFINED: AN AILERON ON THE MAIN WING ( AERO
$ BOXES 1119, 1123, 1127 AND 1131 ) AND A RUDDER ON THE VERTICAL TAIL
$ ( AERO BOXES 3103, 3107, 3111 AND 3115). Y-AXES OF THE CONTROL SURFACES
$ HINGE LINES ARE SPECIFIED VIA THE CORD2R BULK DATA CARDS.
$
$ LABEL TYPE CID SETK SETG
AESURFZ AILERON ANTISYM 110 2000
$ SETID MACROID BOX1 BOX2 ETC
PANLST2 2000 1100 1119 1123 1127 1131
$
$ AESURFZ RUDDER ANTISYM 301 3000
$
$ PANLST2 3000 3100 3103 3107 3111 3115
$
$ CID RID A1 A2 A3 B1 B2 B3
CORD2R 110 0 26.7265 10. 0. 26.7265 10. -10. +CORD1
$ C1 C2 C3
+CORD1 36.7265 15.7735 0.
$
$ CORD2R 301 0 32.5 0. 0. 32.5 -10. 0. +CORD1
+CORD1 22.5 0. 5.7735
$
$ * SURFACE SPLINE FIT ON THE WING *
$
$
$ THE INFINITE PLATE SPLINE METHOD IS USED TO SPLINE THE WING AERO
$ BOXES TO THE WING STRUCTURE GRIDS. THE SETK BULK DATA CARD REFERS
$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES
$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=1105) BULK DATA CARD.
$
$ EID MODEL CP SETK SETG DZ EPS
SPLINE1 1601 WING 1100 1105 0.0
$
$ SETID MACROID BOX1 BOX2
PANLST1 1100 1100 1100 1131
$
$ SID G1 G2 ETC
SET1 1105 100 110 111 112 120 121 122
$
$ THE BEAM SPLINE METHOD IS USED ON THE CANARD. THE SETK ENTRY REFERS
$ TO THE PANLST2 BULK DATA CARD PREVIOUSLY DEFINED FOR THE AESURFZ BULK
$ DATA CARD LISTING ALL AERO BOXES LOCATED ON THE CANARD.
$
$ EID MODEL SETK SETG DZ DTOR CID DTHX
SPLINE2 1501 CANARD 1000 1000 0.0 1.0 1 -1.0 +SP1
$ DTHY
+SP1 -1.0
$
$ PANLST2 1000 1000 1001 1002 1003 1004 1005 +P1
+P1 1006 1007
$
$ SID G1 G2 ETC
SET1 1000 98 99
$ CORD2R DEFINES THE Y-AXIS FOR THE BEAM SPLINE
$ CID CS A1 A2 A3 B1 B2 B3
CORD2R 1 0 15. 0. 0. 15.0 0. 10. +CRD2
$ C1 C2 C3
+CRD2 20. 0. 10.
$
$ VERTICAL FIN SPLINE TO STRUCTURE GRIDS (100, 310, 311, 312)

```

```

$      EID      MODEL  CP      SETK  SETG  DZ      EPS
$      SPLINE1 1701    FIN      3100  3100  0.
$      PANLST2 3100    3100    3100  THRU  3115
$      SET1     3100    100     311   310   312
$
$
$
$      * TRIM CONDITIONS *
$
$      TRIM CONDITION 1: STEADY ROLL CONDITION
$
$*****$
$      TRIMID  IDMK  QDP      TRMTYP  EFFID  VO
$*****$
$      TRIM    1      90      1200.      1.0
$      LABEL1  VAL1  LABEL2  VAL2  LABEL3  VAL3  LABEL4  VAL4  +TR1
$+TR1  AILERON 25.0  BETA    FREE  RACCEL  0.0  PACCEL  0.0  +TR2
$+TR2  RRATE   0.    RUDDER  FREE  PRATE   FREE  NY      0.0
$*****$
$      * * *
$      TRIM CONDITION 2: ABRUPT ROLL CONDITION
$
$*****$
$      TRIMID  IDMK  QDP      TRMTYP  EFFID  VO
$*****$
$      TRIM    2      90      1200.      1.0
$      LABEL1  VAL1  LABEL2  VAL2  LABEL3  VAL3  LABEL4  VAL4  +TR1
$+TR1  AILERON 25.0  BETA    FREE  RACCEL  0.0  PACCEL  FREE  +TR2
$+TR2  RRATE   0.    RUDDER  FREE  PRATE   0.0  NY      0.0
$*****$
$      ENDDATA

```

## **VOLUME II**

### ***Analysis and Optimization Cases***

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## 4.0 ANALYSIS AND OPTIMIZATION CASES

### *GAF WING MODEL*

#### 4.1 Case 1.a: GAF (Generalized Advanced Fighter) Wing Model Analysis

- **Purpose:** To test a public domain model in static, normal modes, and flutter analysis.
- **Description of input and results:**

The GAF model was an aircraft wing model composed of skins, spars, and ribs. A leading edge flap and a trailing edge control surface were attached to the main wing box. The wing was fixed at the root. More details about the model, the test cases, and their application to this model are given in Appendix A.

##### 4.1.1 GAF Structural Configuration and Static Analysis

The structural configuration of the wing in the form of a FEM model is shown in Fig 4.1.1. Skins, spars, and ribs were modeled by CQUAD4 elements, and CELAS2 elements were used to connect the control surfaces to the wing box. A summary of the number of elements and grid points is shown in the following:

NUMBER OF GRID POINTS	288
NUMBER OF ELEMENTS	530
CROD	136
CELAS2	2
CQUAD4	371
<u>RBE2</u>	<u>21</u>

A static analysis was performed for applied static loads, distributed at given grid points, in the vertical direction, using FORCE cards. The wing was fixed as a cantilever by SPC cards. The identification number of the FORCE cards in the bulk data deck was called by a STATIC card and the ID number of the SPC cards in the bulk data deck was called by a BOUNDARY card in the case control deck. Displacements at grid points and stresses in elements were calculated, and the output print of these data was controlled by a PRINT card in the case control deck.

The weight of this structure was 671.60 lbs, and the associated weight data of the initial structure are shown in Table 4.1.1. To print out these weight data, a GPWG bulk data card was entered in the bulk data deck, and the associated ID number was called in the PRINT card of the case control deck. The six components of the displacement were printed. The maximum vertical displacement at the wing tip was 27.068 in. All stress components and the principal stresses were printed. The maximum principal stress in all elements was 64,000 psi. The data were used

later as constraints in the structural design optimizations. The deformed shape of the structure is shown in Fig 4.1.2.

#### 4.1.2 Aerodynamic Configuration and Analysis by ENSAERO

Aerodynamic analyses of the wing were performed by the CFD code, ENSAERO. The steady aerodynamic pressure coefficients calculated here were used later as input data for ZTAIC of ASTROS\*. The steady aerodynamic pressure coefficients were calculated for Euler flow and also for Navier-Stokes flow, with the results of the Euler flow, via a **RESTART** statement. For all cases, the Reynolds number was 10,000,000 and spanwise and normal viscous terms were used. For turbulence, the Baldwin-Lomax turbulence model was used, and, for correction for vortex flow, Degani-Schiff modeling was used. Iteration indices were less than  $1.0\text{E-}09$  and iteration numbers were about 500 for the Euler flow and then more than 500 additional iterations for the Navier-Stokes flow. The aerodynamic configuration of the wing is shown in Fig 4.1.3. The total number of grid points was  $151 \times 44 \times 34$  in the x-, y-, and z- directions, respectively. The number of grid points on the wing was  $61 \times 34$  on both lower and upper surfaces. The total number of iterations for Euler flow plus Navier-Stokes flow was about 1000, and the total CPU time on the CRAY computer was about 2 hours. In the transonic region belonged  $M = 0.85$ , convergence was slower than in the other regions, and more iterations were needed.

Two Mach number cases,  $M = 0.85$  and  $M = 0.90$ , and two angle-of-attack ( $\alpha$ ) cases,  $\alpha = 0.0^\circ$  and  $\alpha = 5.0^\circ$ , for a total of four cases were investigated. The results of the calculated aerodynamic pressure coefficients for Euler flow and for Navier-Stokes flow are shown in Fig 4.1.4. In Euler flow, the strength of the shock was larger than in Navier-Stokes flow. This seems to come about because of the viscous effects in the Navier-Stokes flow. The computed points were as follows:

- (1)  $M = 0.85, \alpha = 0.0^\circ$  (Navier-Stokes Flow)
- (2)  $M = 0.85, \alpha = 5.0^\circ$  (Navier-Stokes Flow)
- (3)  $M = 0.90, \alpha = 0.0^\circ$  (Navier-Stokes Flow)
- (4)  $M = 0.90, \alpha = 5.0^\circ$  (Navier-Stokes Flow)

Fig 4.1.4 shows that the flows were in the transonic regime at  $M = 0.85$  and  $M = 0.90$ .

#### 4.1.3 Normal Modes Analysis Using ASTROS\*

Natural frequencies, the associated modes shapes, and the generalized stiffness and mass matrices were calculated in the normal modes discipline. For the calculation of the eigenvalues, the INV (Inverse Power) method was used. This method was selected via the EIGR bulk data card and the ID number of this card was called by METHOD in the BOUNDARY card in the case control deck. ASET cards were used to save computing time and neglect motions other than vertical. Mode normalization was used in MASS because it was convenient that the components of the generalized mass were unity.

Normal modes data for 8 modes from the lowest mode up to 90.0 Hz were calculated. The lowest eight natural frequencies of the GAF model were 10.22, 30.97, 35.89, 49.74, 58.04, 65.51, 76.09, and 84.75 Hz. The results are shown in Table 4.1.2 and the mode shapes are presented in



Fig 4.1.5. The first and second modes were bending modes and the third mode was the first torsion mode. These data were later used in the flutter calculations. The lowest natural frequency, 10.22 Hz, was used as a constraint in normal modes design optimization.

#### 4.1.4 Flutter Analysis

Flutter analyses were performed by the K-method in ASTROS\*, the P-K method in MSC/NASTRAN, and the root-locus method outside of these codes in three aerodynamic regimes: transonic, low supersonic, and high supersonic/hypersonic. Mach numbers  $M=0.85$ , 1.15, and 3.0 were selected to calculate flutter speeds. ZONA6 and ZTAIC of ASTROS\* were used to calculate generalized unsteady aerodynamic loads at  $M=0.85$ , and ZONA7 and ZONA7U were used for  $M=1.15$  and  $M=3.0$ , respectively. The results are compared with those for MSC/NASTRAN and the root-locus method in Table 4.1.3. The generalized unsteady aerodynamic loads calculated by ASTROS\* were used in the root-locus method. Two CAERO7 cards were used: the CAERO7, 100001 card represented the wing with 15 x 11 aerodynamic boxes. The CAERO7, 200001 card represented the fuselage region with 15 x 2 aerodynamic boxes.

The generalized unsteady aerodynamic loads at  $M=0.85$  were calculated by ZONA6. There were 8 x 8 generalized aerodynamic coefficient terms,  $Q_{ij}$ , for each reduced frequency  $k$ . The plots of the real and imaginary parts of  $Q_{1j}$  and  $Q_{2j}$  ( $j = 1, 2, \dots, 8$ ) versus  $k$  are shown in Fig 4.1.6. Generalized unsteady aerodynamic loads were also approximated by the minimum-state method at  $M=0.85$ . In Fig 4.1.7, the  $Q_{1j}$  and  $Q_{2j}$  calculated by ZONA6 are shown as real part versus imaginary part by black and solid lines and the approximate  $Q_{1j}$  and  $Q_{2j}$  calculated by the minimum-state method are shown by color and dotted lines. The V-f and V-g plots for the results by ZONA6 of ASTROS\* are shown in Fig 4.1.8. The flutter speed was 17,337 in/sec and the flutter frequency was 14.3 Hz. The root-locus plot to calculate the flutter speed is shown in Fig 4.1.9. The flutter speed was 15,888 in/sec and the flutter frequency was 17.3 Hz. The plots of Figs 4.1.10 – 4.1.13 are for the results by ZTAIC at  $M=0.85$ . The flutter speed and flutter frequency were 18,172 in/sec and 18.1 Hz, respectively, by the K-method, and 16,581 in/sec and 15.6 Hz by the root-locus method. It is normally expected that the nonlinear flutter speed is lower than the linear flutter speed in the transonic regime. However, for the case of the GAF model, the nonlinear flutter speed was slightly higher than the linear flutter speed. The plots of Figs 4.1.14 – 4.1.17 are for the results by ZONA7 at  $M=1.15$ . The flutter speed and flutter frequency were 20,776 in/sec and 19.8 Hz, respectively, by the K-method, while a divergence speed 14,170 in/sec was obtained by the root-locus method. The plots of Figs 4.1.18 – 4.1.21 are for the results by ZONA7U at  $M=3.0$ . The flutter speed and flutter frequency were 31,743 in/sec and 21.1 Hz, respectively, by the K-method and 33,536 in/sec and 21.3 Hz by the root-locus method. For subsonic flow at  $M=0.85$  and supersonic flow at  $M=1.15$ , the root-locus results were close to the MSC/NASTRAN results as shown in Table 4.1.3.

Table 4.1.1 Weight Data Output of GAF Model.

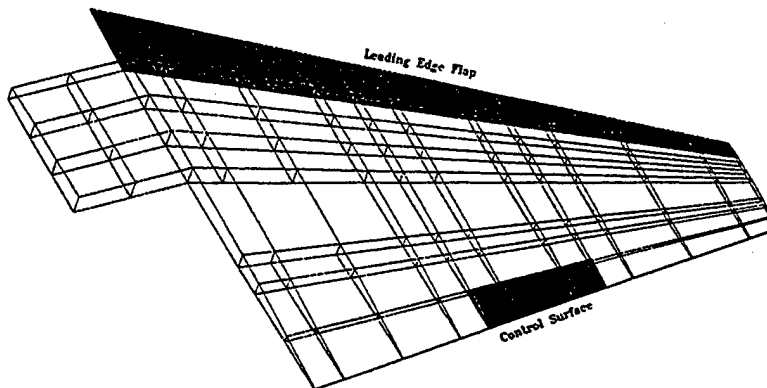
OUTPUT FROM GRID POINT WEIGHT GENERATOR  
REFERENCE POINT = 1  
XO = 3.685130E+01, YO = 0.000000E+00, ZO = 2.084700E+00  
M O  
\* 6.7160E+02 0.000E+00 0.0000E+00 0.0000E+00 -1.405E+03 -4.1995E+04 \*  
\* 0.0000E+00 6.716E+02 0.0000E+00 1.4051E+03 0.000E+00 2.8357E+04 \*  
\* 0.0000E+00 0.000E+00 6.7160E+02 4.1995E+04 -2.835E+04 0.0000E+00 \*  
\* 0.0000E+00 1.405E+03 4.1995E+04 3.6085E+06 -2.140E+06 5.7740E+04 \*  
\* -1.4051E+03 0.000E+00 -2.8357E+04 -2.1406E+06 1.635E+06 8.8539E+04 \*  
\* -4.1995E+04 2.835E+04 0.0000E+00 5.7740E+04 8.853E+04 5.2324E+06 \*  
S  
\* 1.00000E+00 0.00000E+00 0.00000E+00 \*  
\* 0.00000E+00 1.00000E+00 0.00000E+00 \*  
\* 0.00000E+00 0.00000E+00 1.00000E+00 \*  
DIRECTION  
MASS AXIS SYSTEM (S) MASS X-C.G. Y-C.G. Z-C.G.  
X 6.71602E+02 0.00000E+00 6.25301E+01 -2.09224E+00  
Y 6.71602E+02 4.22239E+01 0.00000E+00 -2.09224E+00  
Z 6.71602E+02 4.22239E+01 6.25301E+01 0.00000E+00

Table 4.1.2 Results of Normal Modes Analysis of GAF Model.

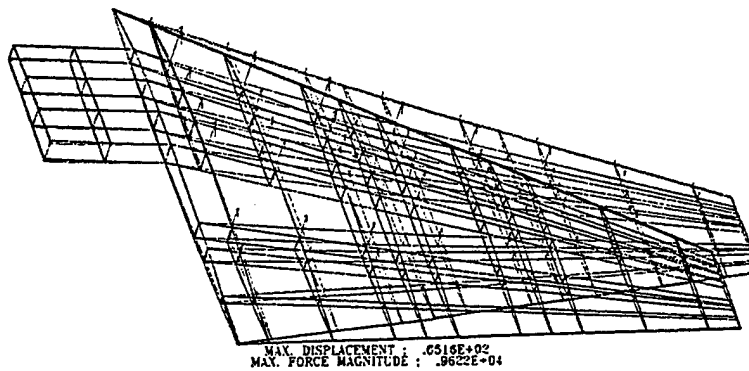
Mode	Eigenvalue ( $rad/s^2$ )	Freq. (Hz.)	Generalized Mass	Generalized Stiffness
1	4.12692E+03	1.02243E+01	1.00000E+00	4.12692E+03
2	3.78674E+04	3.09708E+01	1.00000E+00	3.78674E+04
3	5.08536E+04	3.58906E+01	1.00000E+00	5.08536E+04
4	9.76608E+04	4.97371E+01	1.00000E+00	9.76608E+04
5	1.32991E+05	5.80406E+01	1.00000E+00	1.32991E+05
6	1.69421E+05	6.55094E+01	1.00000E+00	1.69421E+05
7	2.28595E+05	7.60945E+01	1.00000E+00	2.28595E+05
8	2.83559E+05	8.47504E+01	1.00000E+00	2.83559E+05

**Table 4.1.3 Results of Flutter Analyses of GAF Model.**

No	Mach	Method	Flutter Speed (in/sec)	F. Freq. (Hz)	Remarks
1	0.85	ZONA6	17,336	14.3	
		ZTAIC	18,172	18.1	
		MSC/NASTRAN	15,800	16.7	
		Root-locus (ZONA6)	15,888	17.3	
		Root-locus (ZTAIC)	16,581	15.6	
2	1.15	ZONA7	20,776	19.8	
		MSC/NASTRAN	14,500	0.0	Divergence
		Root-locus (ZONA7)	14,170	0.0	Divergence
3	3.0	ZONA7U	31,743	21.1	
		MSC/NASTRAN	36,100	22.0	
		Root-locus (ZONA7U)	33,536	21.3	



**Figure 4.1.1 Structural Configuration of GAF Model by FEM.**



**Figure 4.1.2 Deflection Shape of GAF Model for Static Loads.**

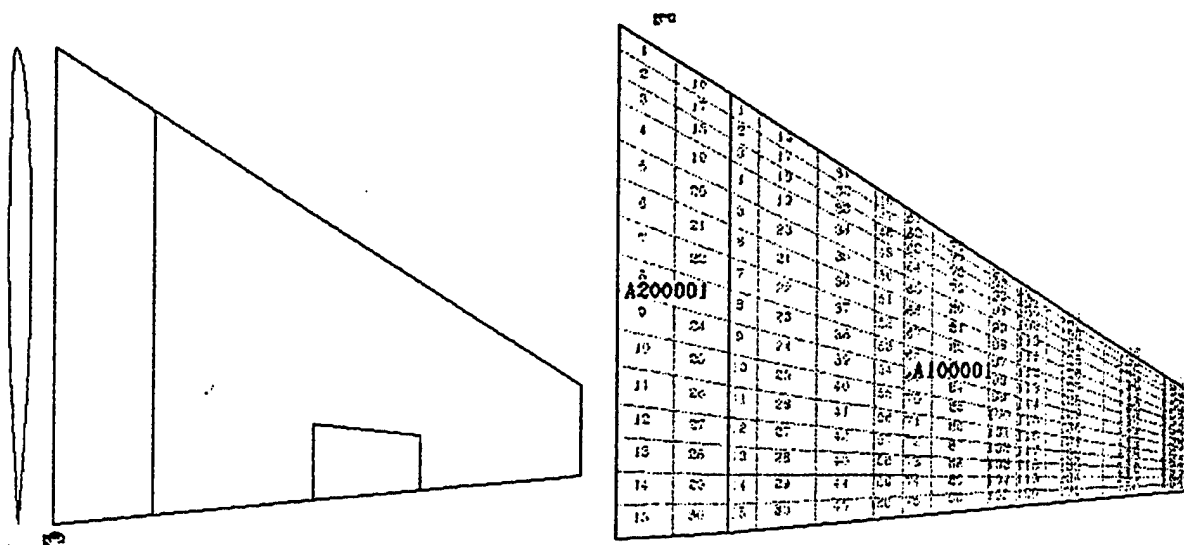


Figure 4.1.3 Aerodynamic Configuration of GAF Model and Aerodynamic Panels.

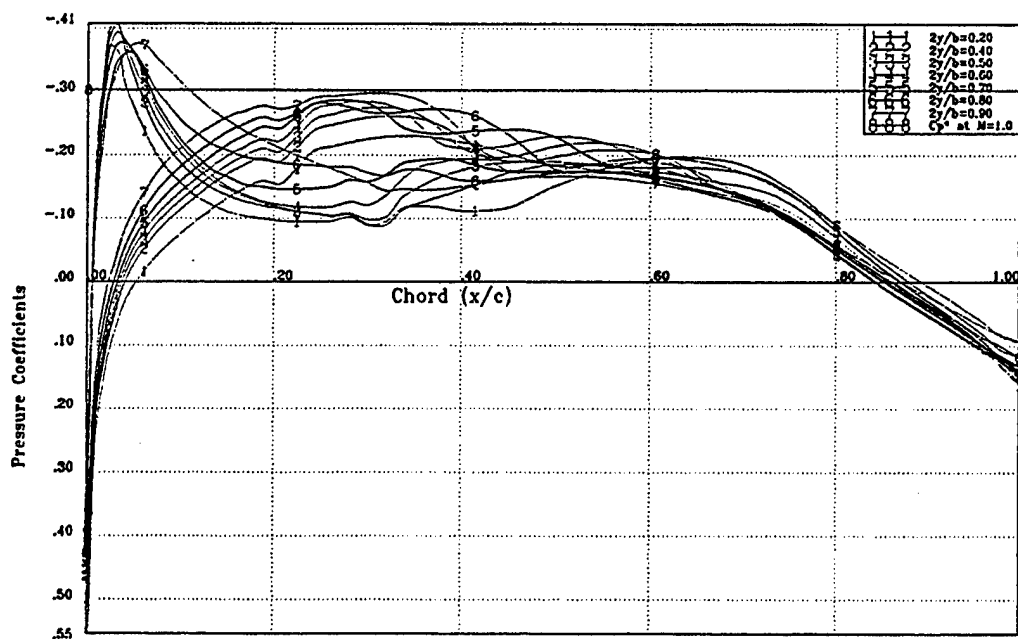


Figure 4.1.4.a Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow:  $M = 0.85$ ,  $AoA = 0.0^\circ$ , by ENSAERO.

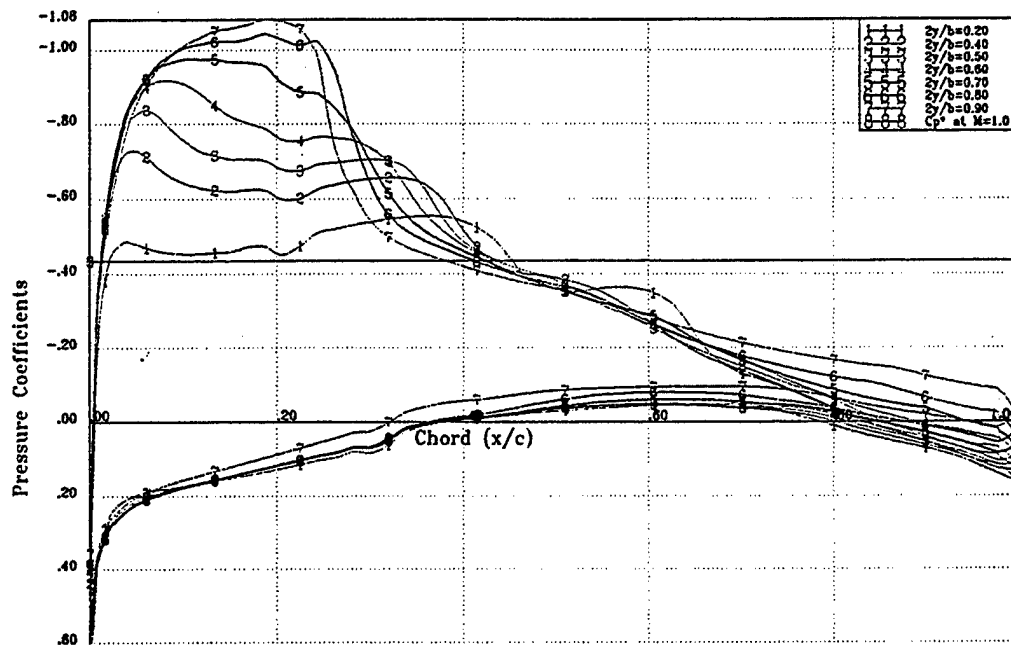


Figure 4.1.4.b Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow:  $M = 0.85$ ,  $AoA = 5.0^\circ$ , by ENSAERO.

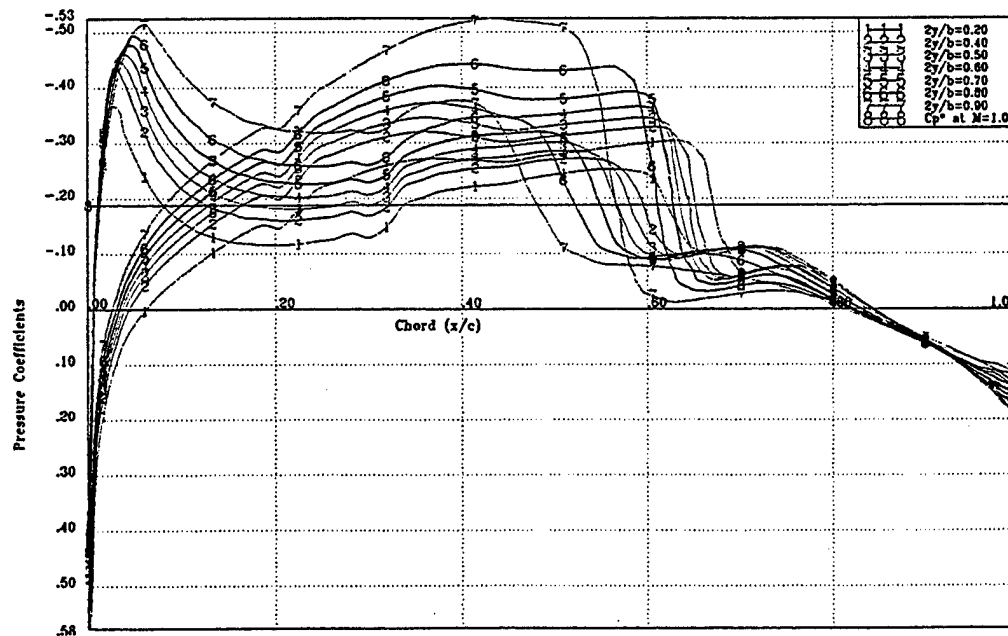


Figure 4.1.4.c Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow:  $M = 0.90$ ,  $AoA = 0.0^\circ$ , by ENSAERO.

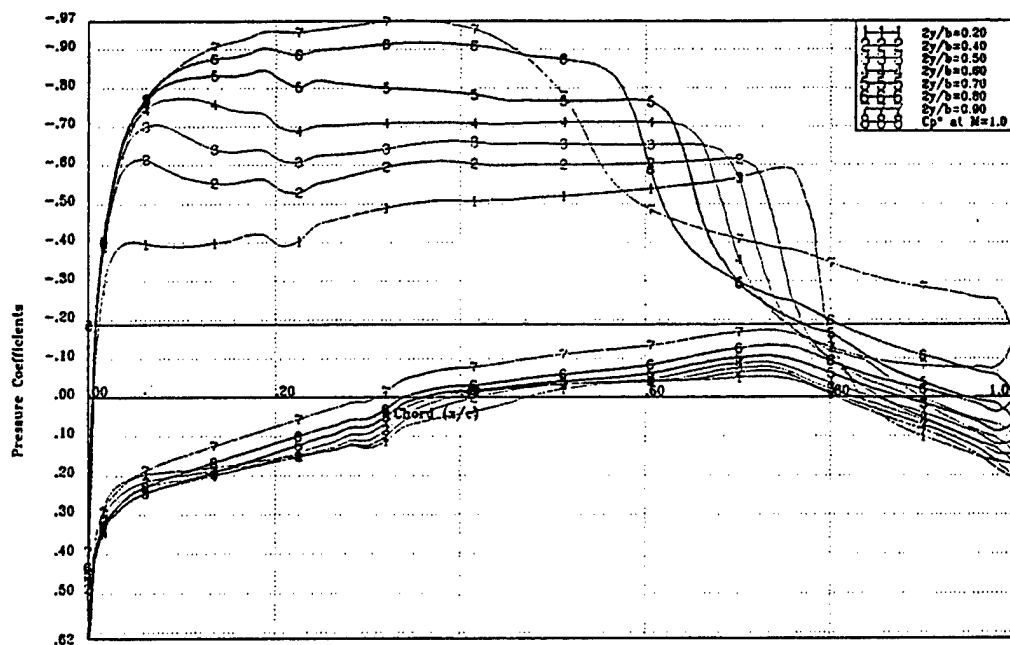


Figure 4.1.4.d Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow:  $M = 0.90$ ,  $AoA = 5.0^\circ$ , by ENSAERO.

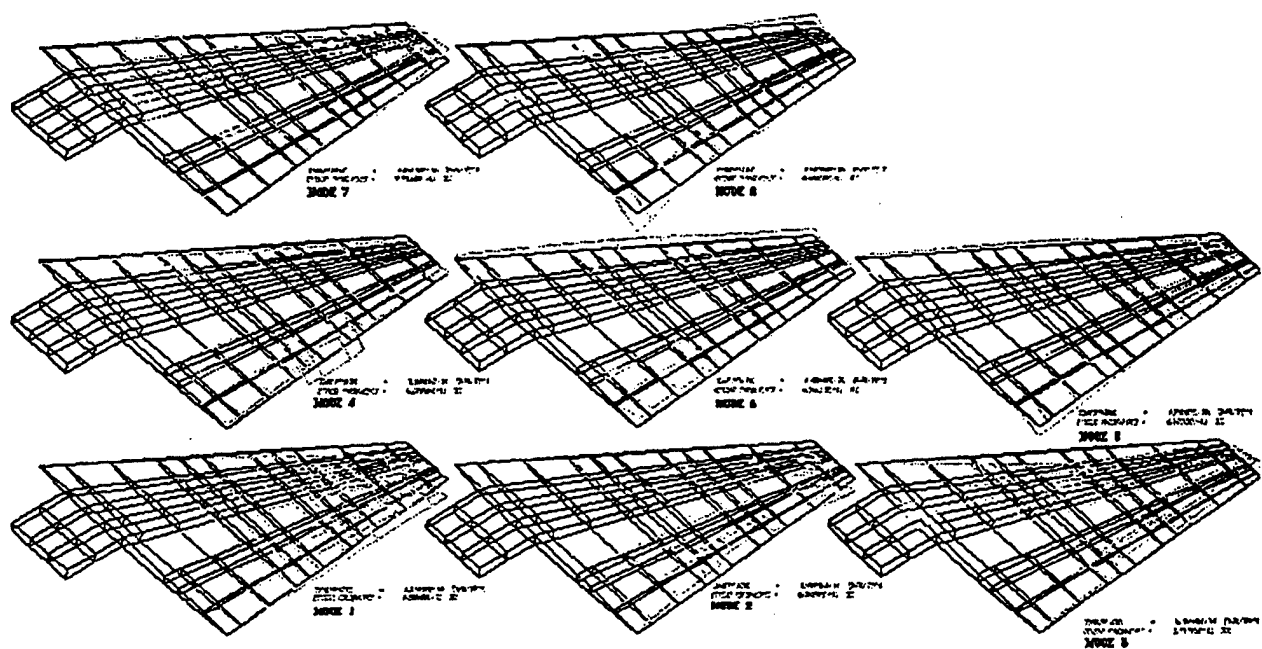


Figure 4.1.5 Normal Modes of GAF Model.

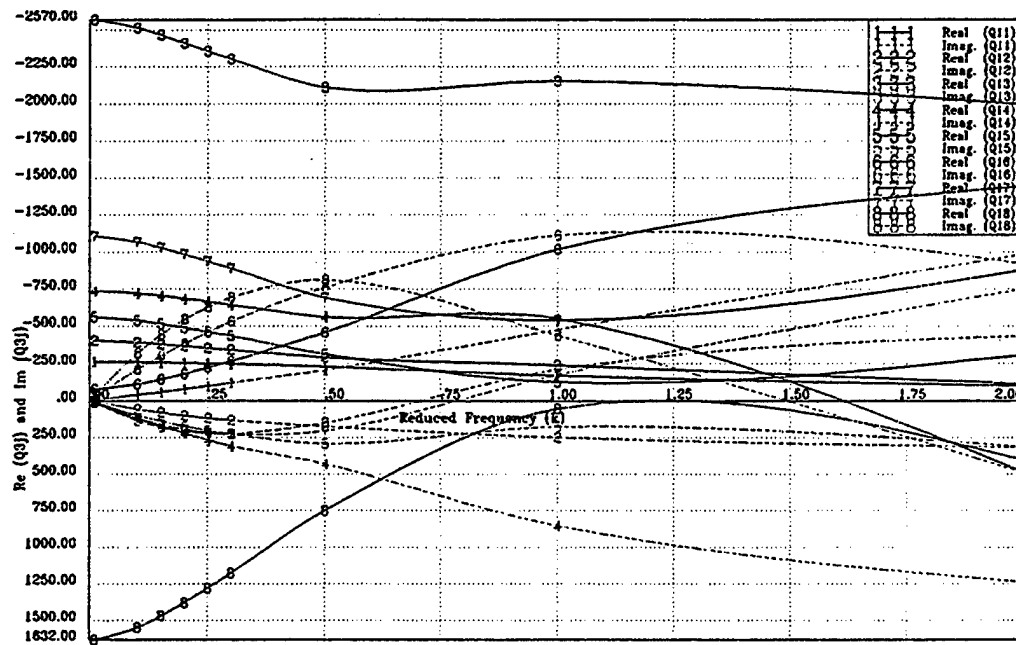


Figure 4.1.6.a Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\*.

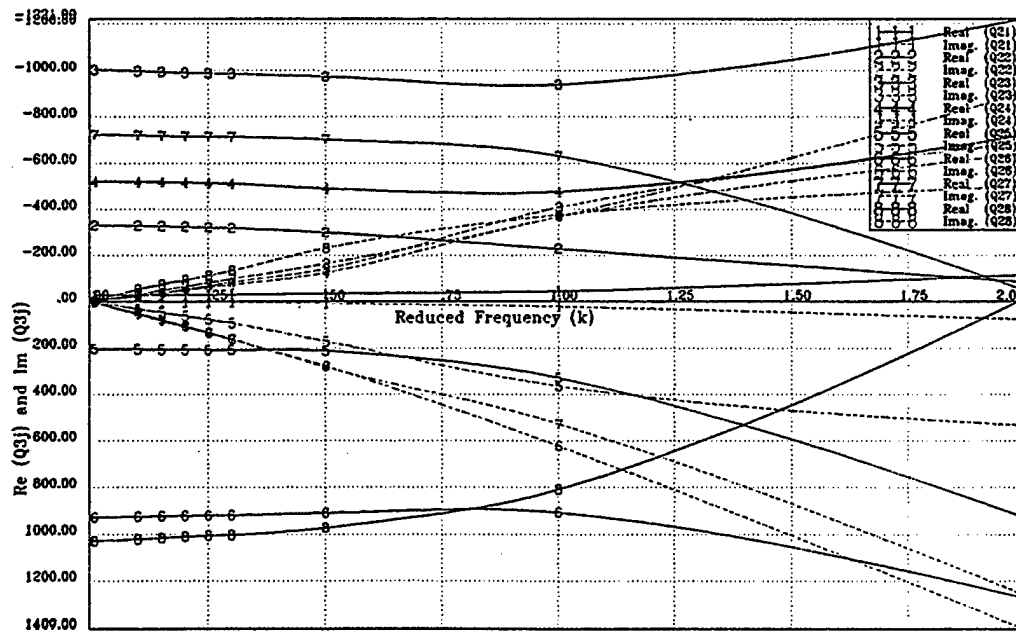


Figure 4.1.6.b Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\*.

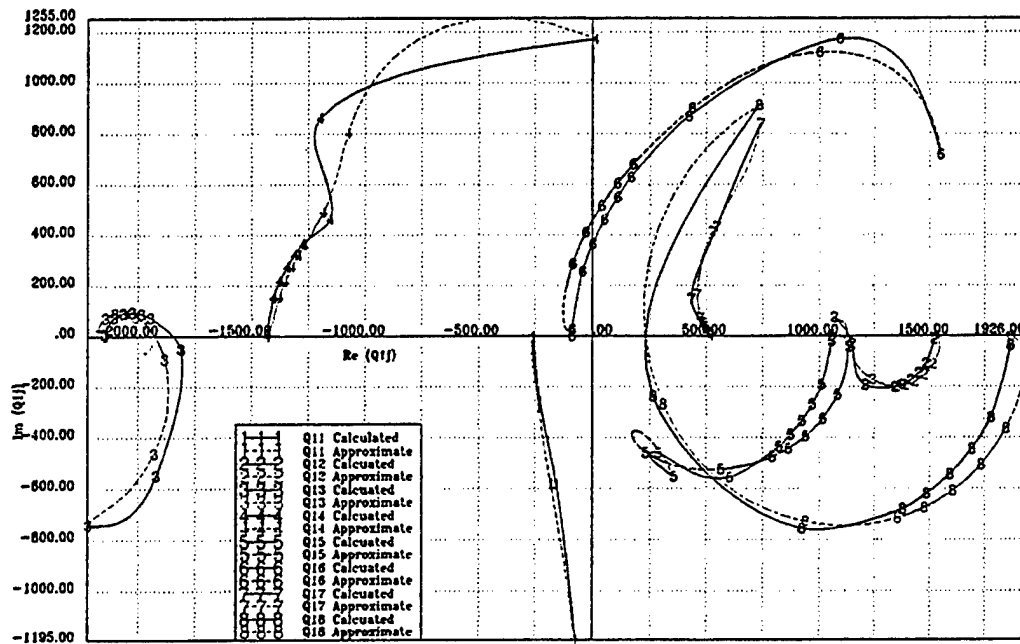


Figure 4.1.7.a Generalized Unsteady Aerodynamic Coefficients  $Q_{1j}$  of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\* and Approximated by Minimum-State Method.

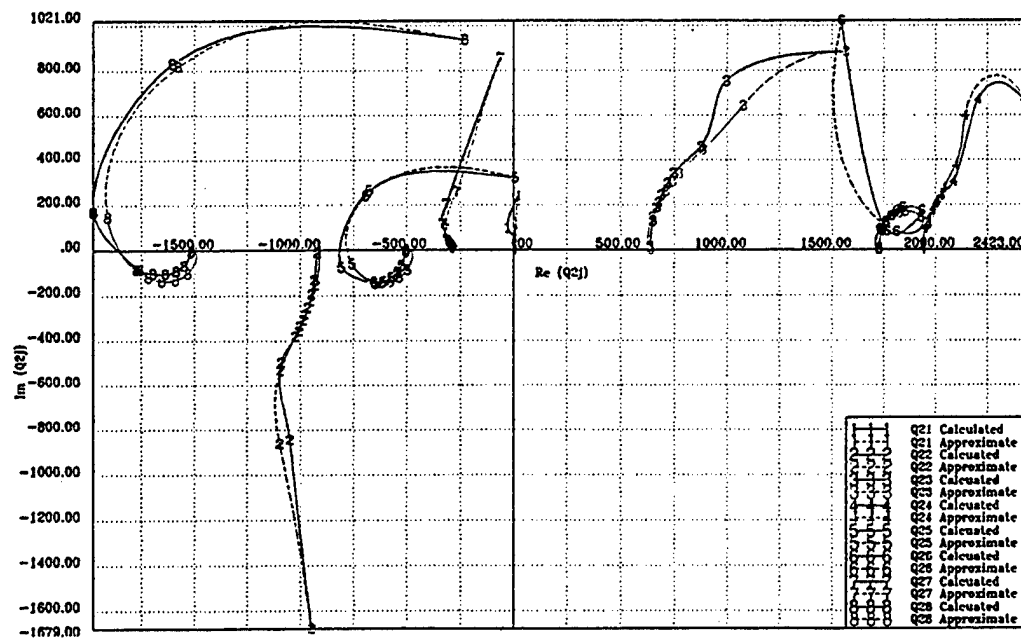


Figure 4.1.7.b Generalized Unsteady Aerodynamic Coefficients  $Q_{2j}$  of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\* and Approximated by Minimum-State Method.



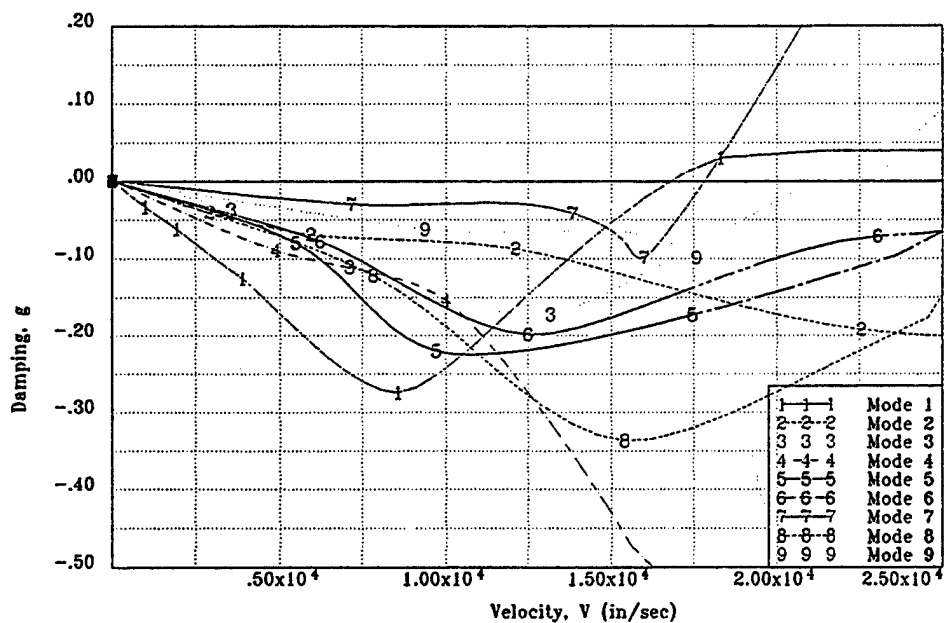
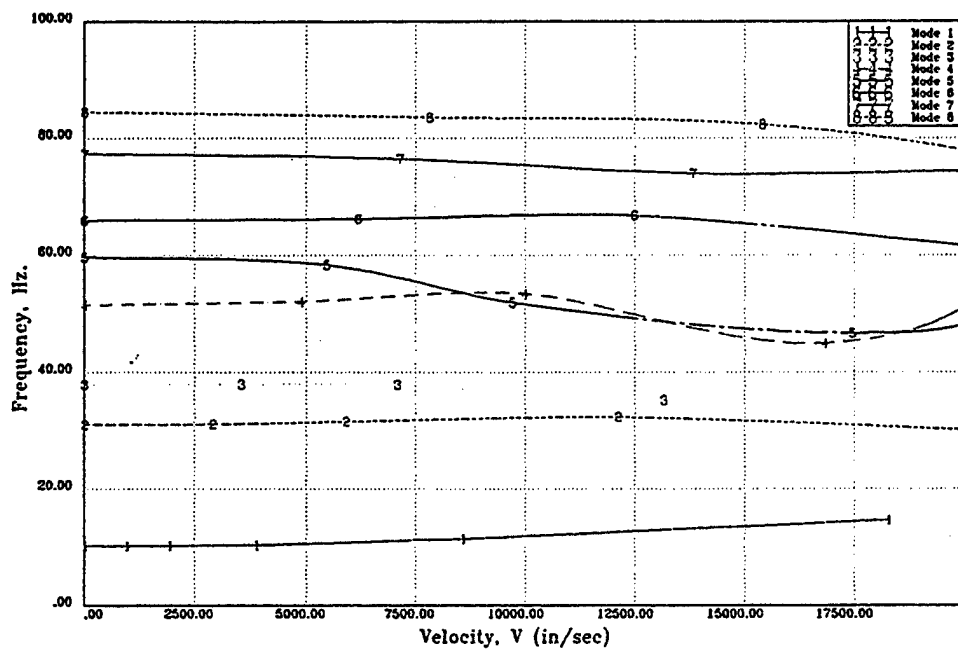


Figure 4.1.8 V-f and V-g Plots of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\*  
(Flutter Speed = 17,337 in/sec, Flutter Frequency = 14.3 Hz.)

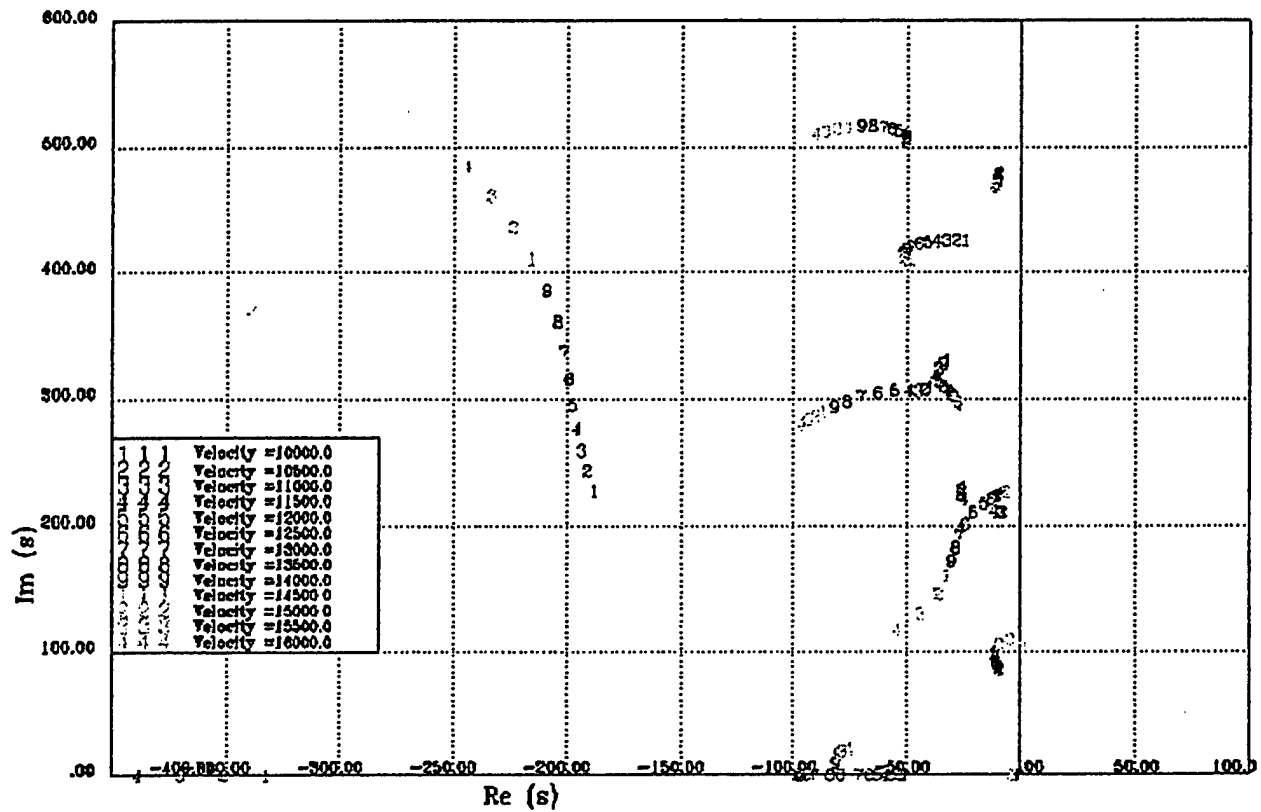


Figure 4.1.9 Root-Locus Plot of GAF Model:  $M = 0.85$ , by ZONA6 of ASTROS\*  
 (Flutter Speed = 15,888 in/sec, Flutter Frequency = 17.32 Hz).

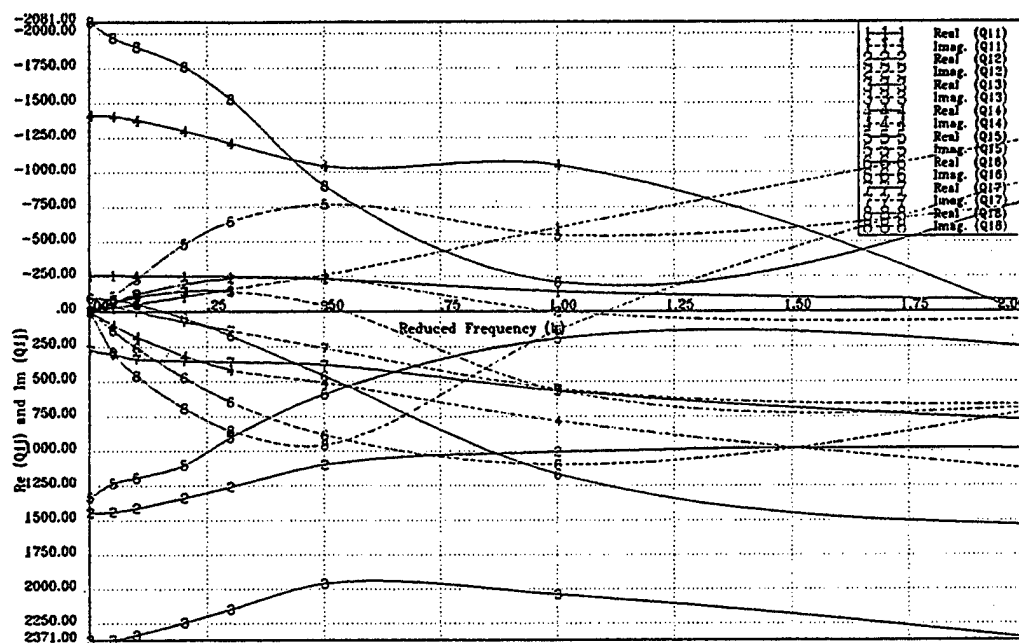


Figure 4.1.10.a Generalized Unsteady Aerodynamic Coefficients  $Q_{1j}$  of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\*.

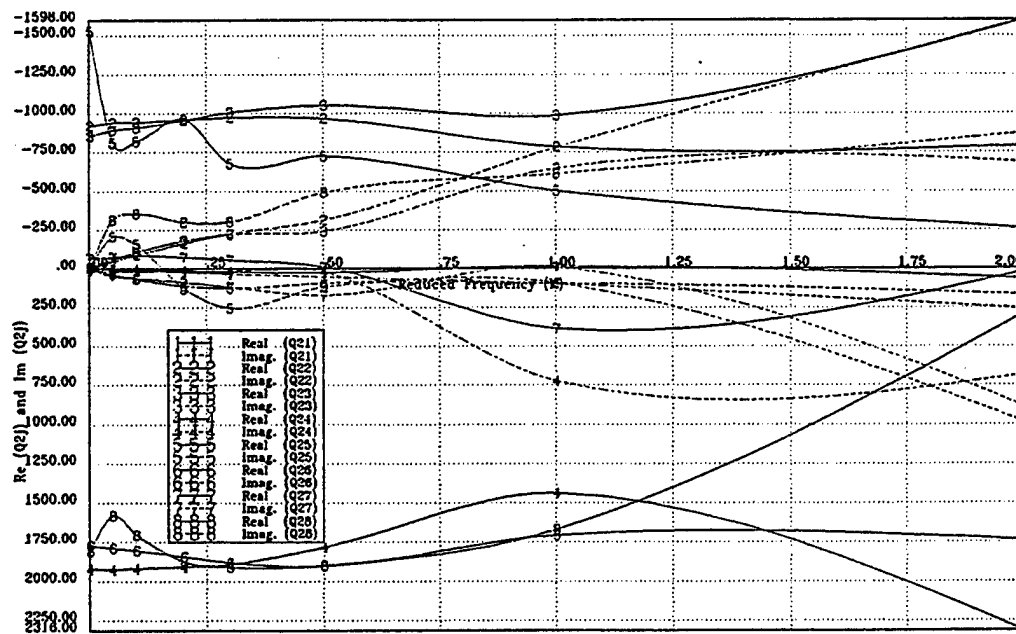


Figure 4.1.10.b Generalized Unsteady Aerodynamic Coefficients  $Q_{2j}$  of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\*.

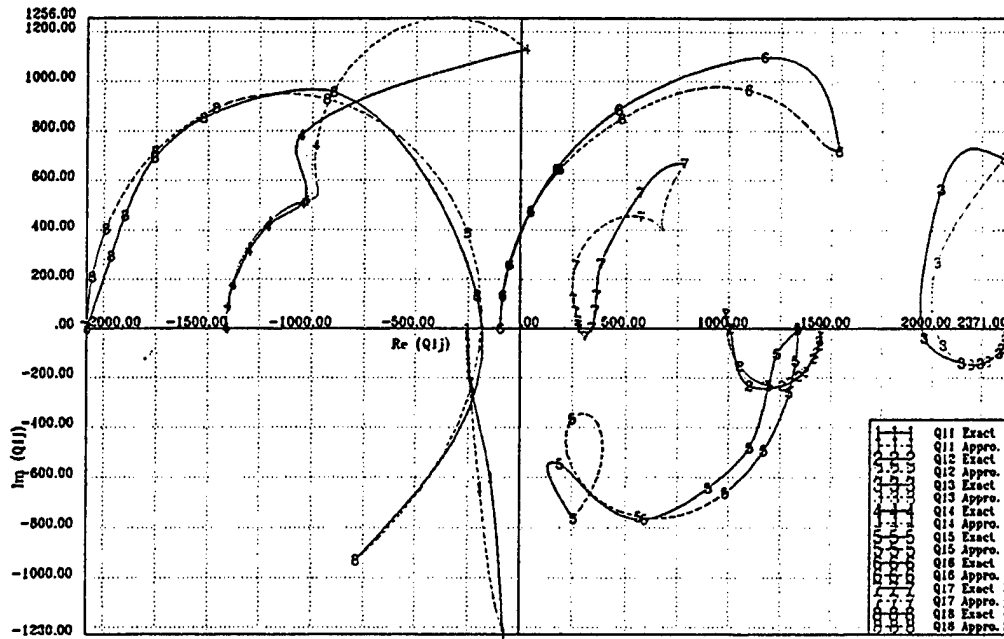


Figure 4.1.11.a Generalized Unsteady Aerodynamic Coefficients  $Q_{1j}$  of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\* and Approximated by Minimum-State Method.

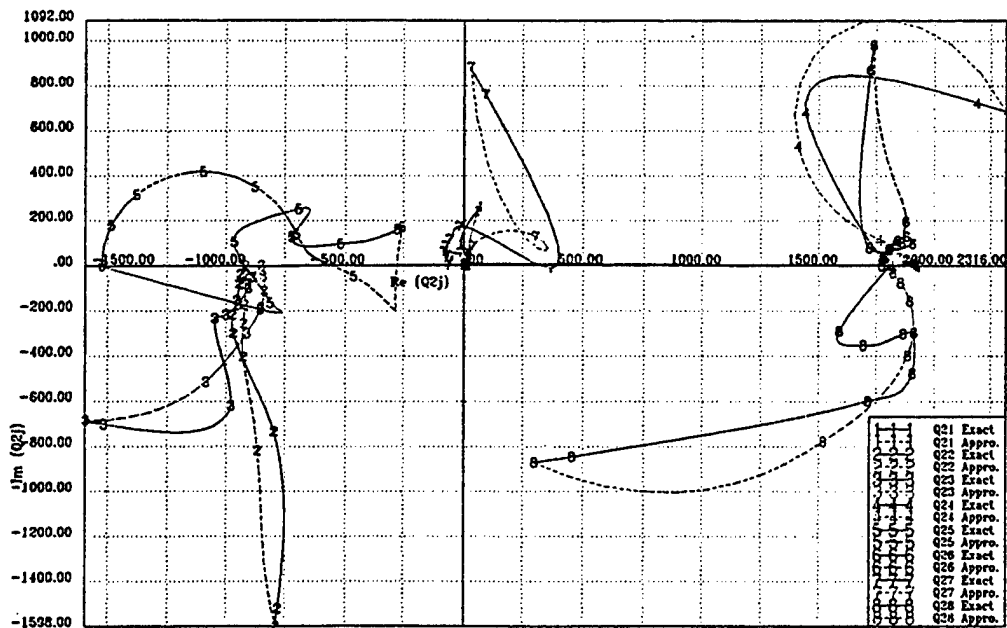


Figure 4.1.11.b Generalized Unsteady Aerodynamic Coefficients  $Q_{2j}$  of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\* and Approximated by Minimum-State Method.

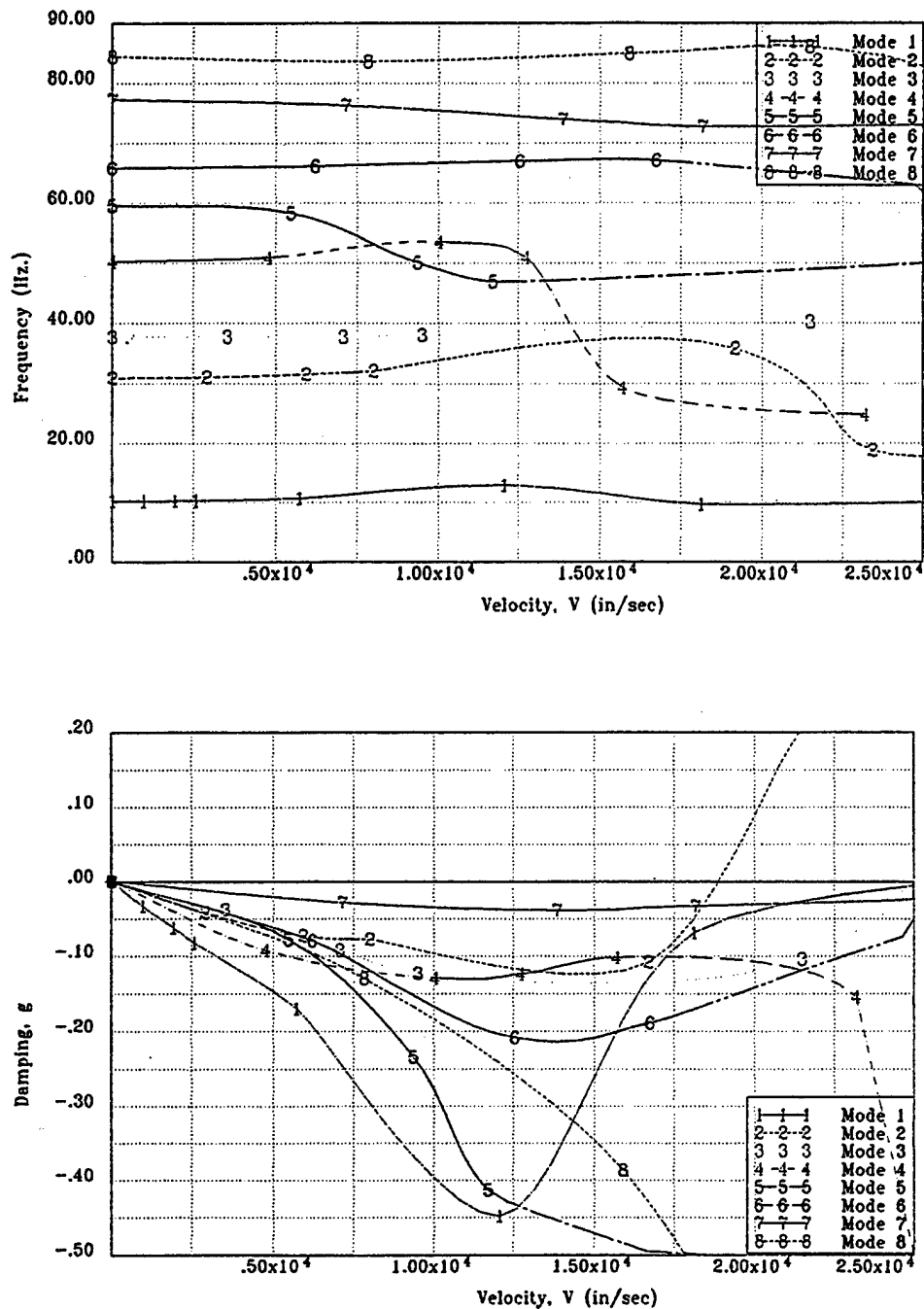


Figure 4.1.12 V-f and V-g Plots of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\*  
(Flutter Speed =  $18,172$  in/sec, Flutter Frequency =  $18.1$  Hz).

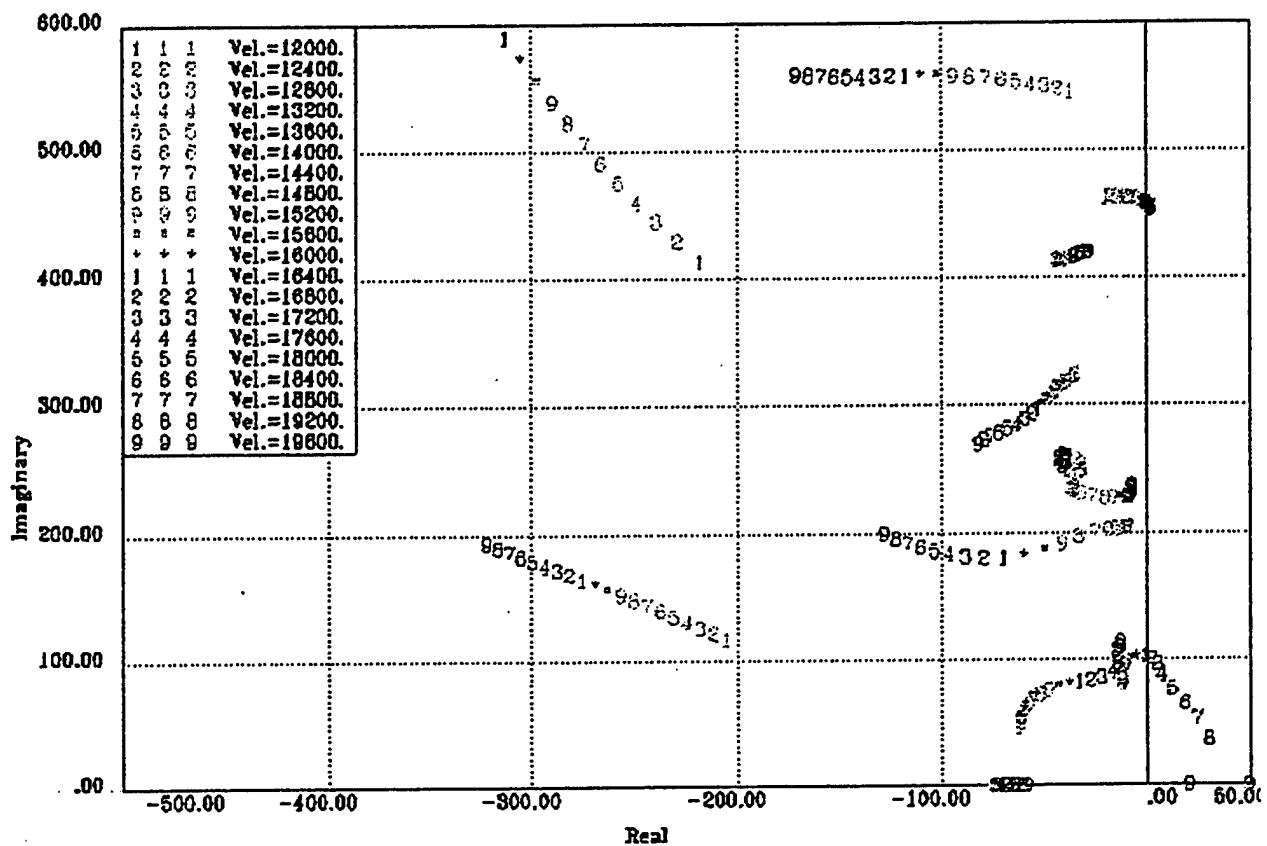


Figure 4.1.13 Root-Locus Plot of GAF Model:  $M = 0.85$ , by ZTAIC of ASTROS\*  
(Flutter Speed = 16,581 in/sec, Flutter Frequency = 15.6 Hz).

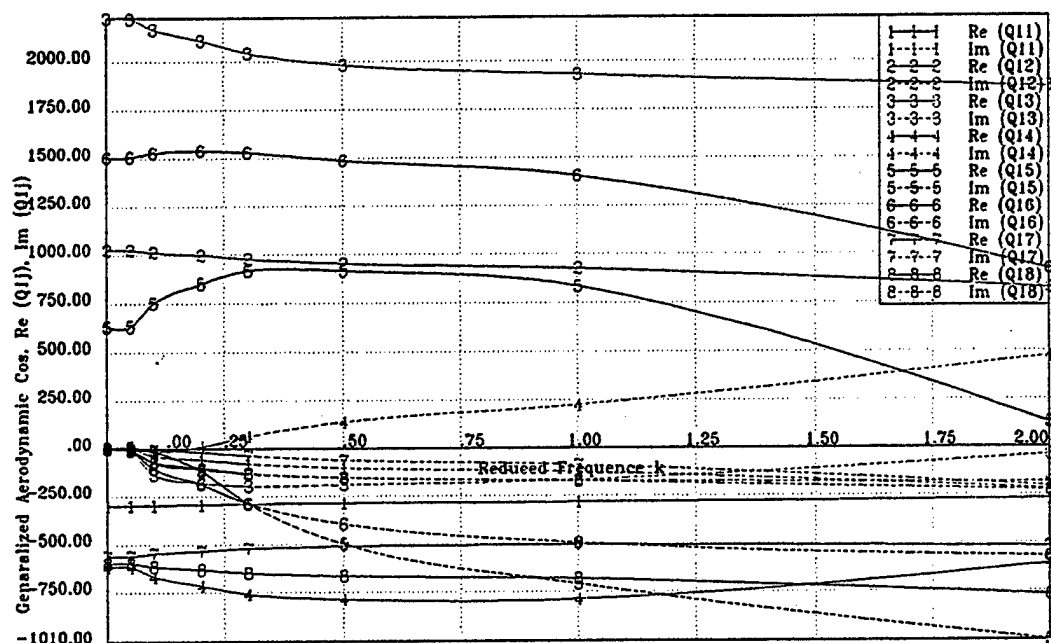


Figure 4.1.14 Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 1.15$ , by ZONA7 of ASTROS\*.

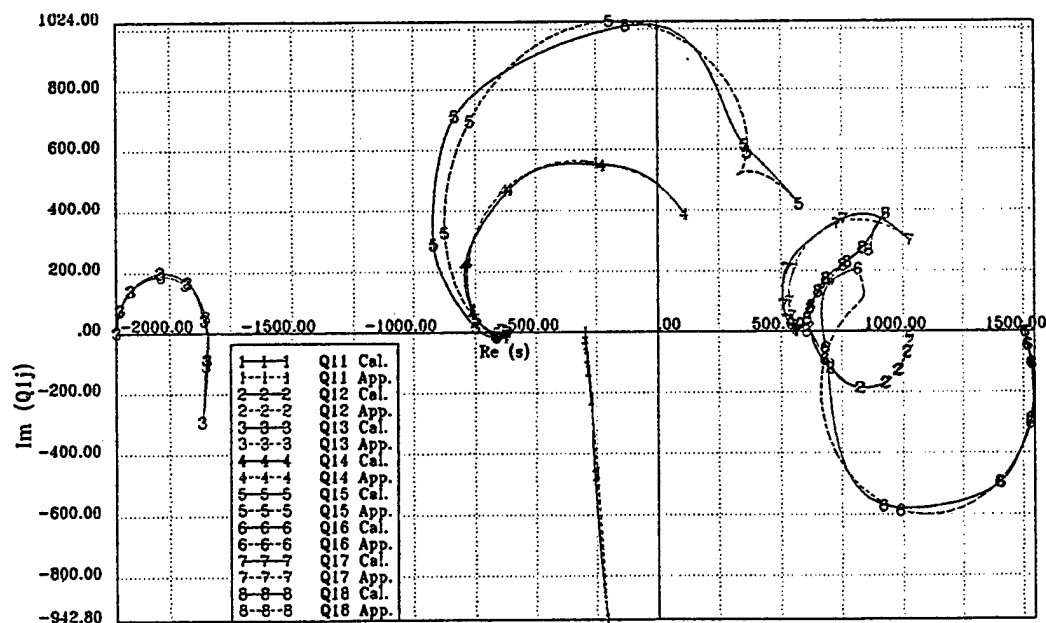


Figure 4.1.15 Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 1.15$ , by ZONA7 of ASTROS\* and Approximated by Minimum-State Method.

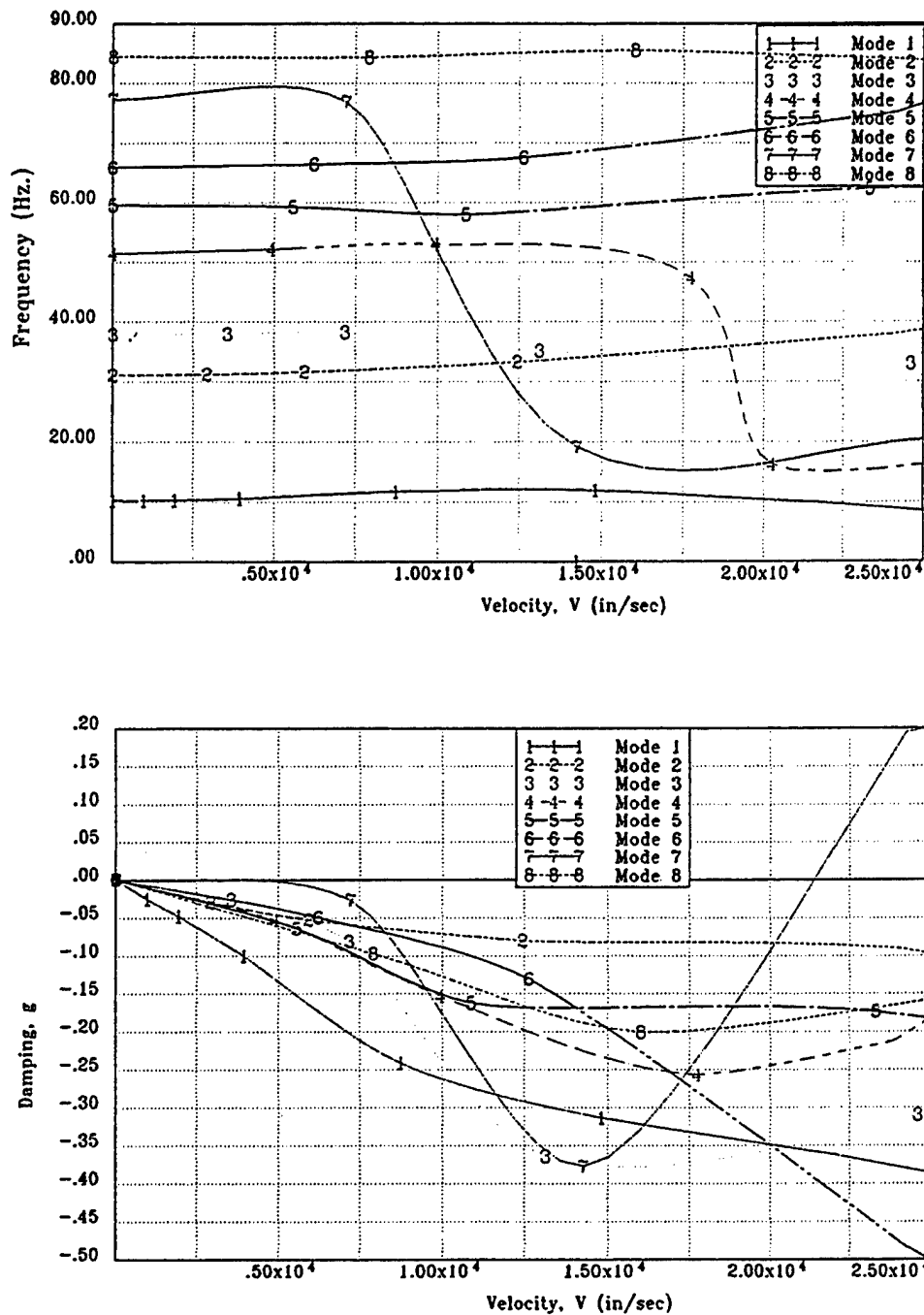


Figure 4.1.16 V-f and V-g Plots of GAF Model:  $M = 1.15$ , by ZONA7 of ASTROS\* (Flutter Speed = 20,776 in/sec, Flutter Frequency = 19.8 Hz).



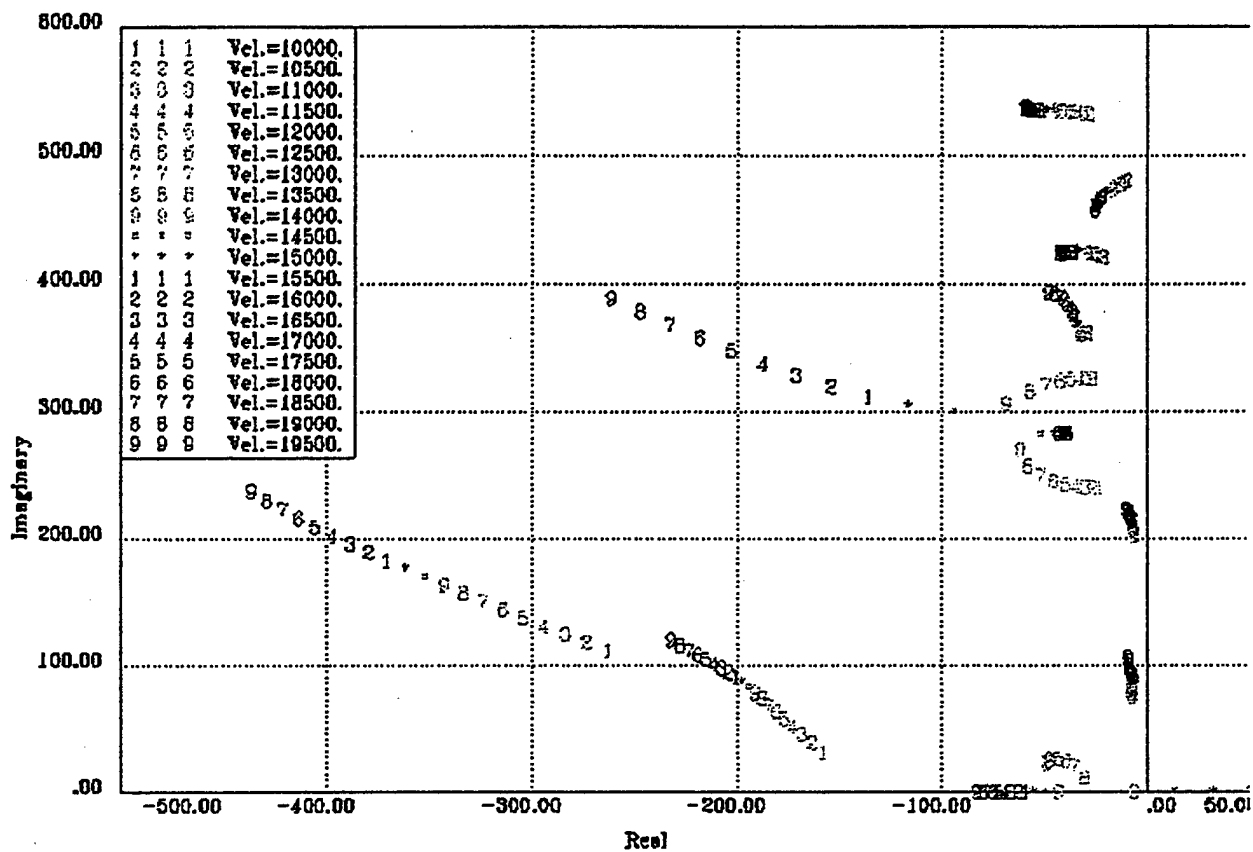


Figure 4.1.17 Root-Locus Plot of GAF Model:  $M = 1.15$ , by ZONA7 of ASTROS\*  
(Divergence Speed = 14,170 in/sec, No Flutter).

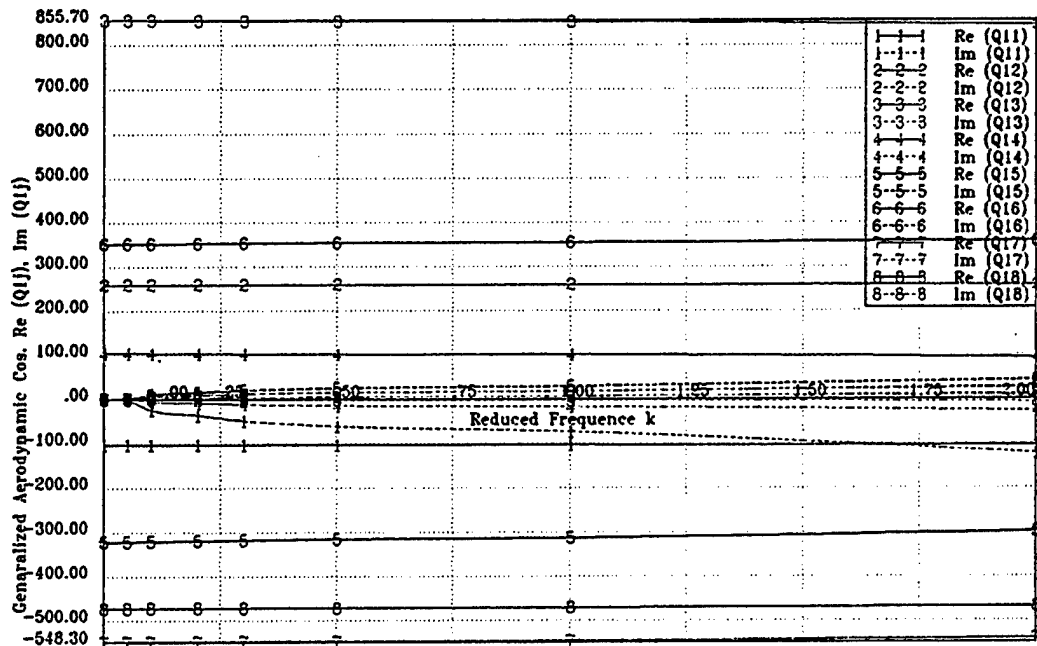


Figure 4.1.18 Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 3.0$ , by ZONA7U of ASTROS\*.

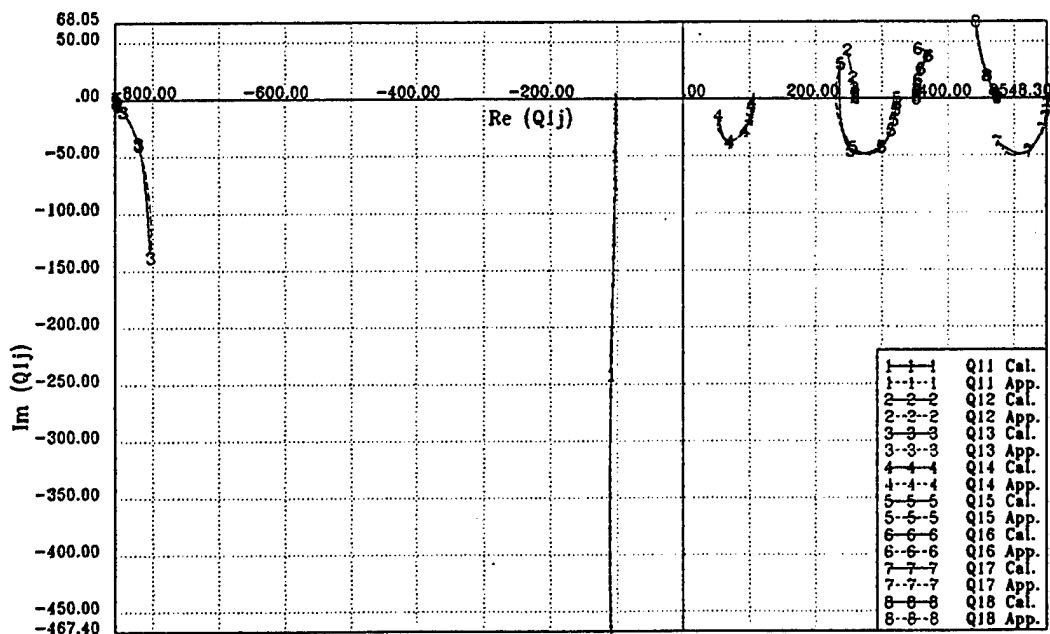


Figure 4.1.19 Generalized Unsteady Aerodynamic Coefficients  $Q_{ij}$  of GAF Model:  $M = 3.0$ , by ZONA7U of ASTROS\* and Approximated by Minimum-State Method.

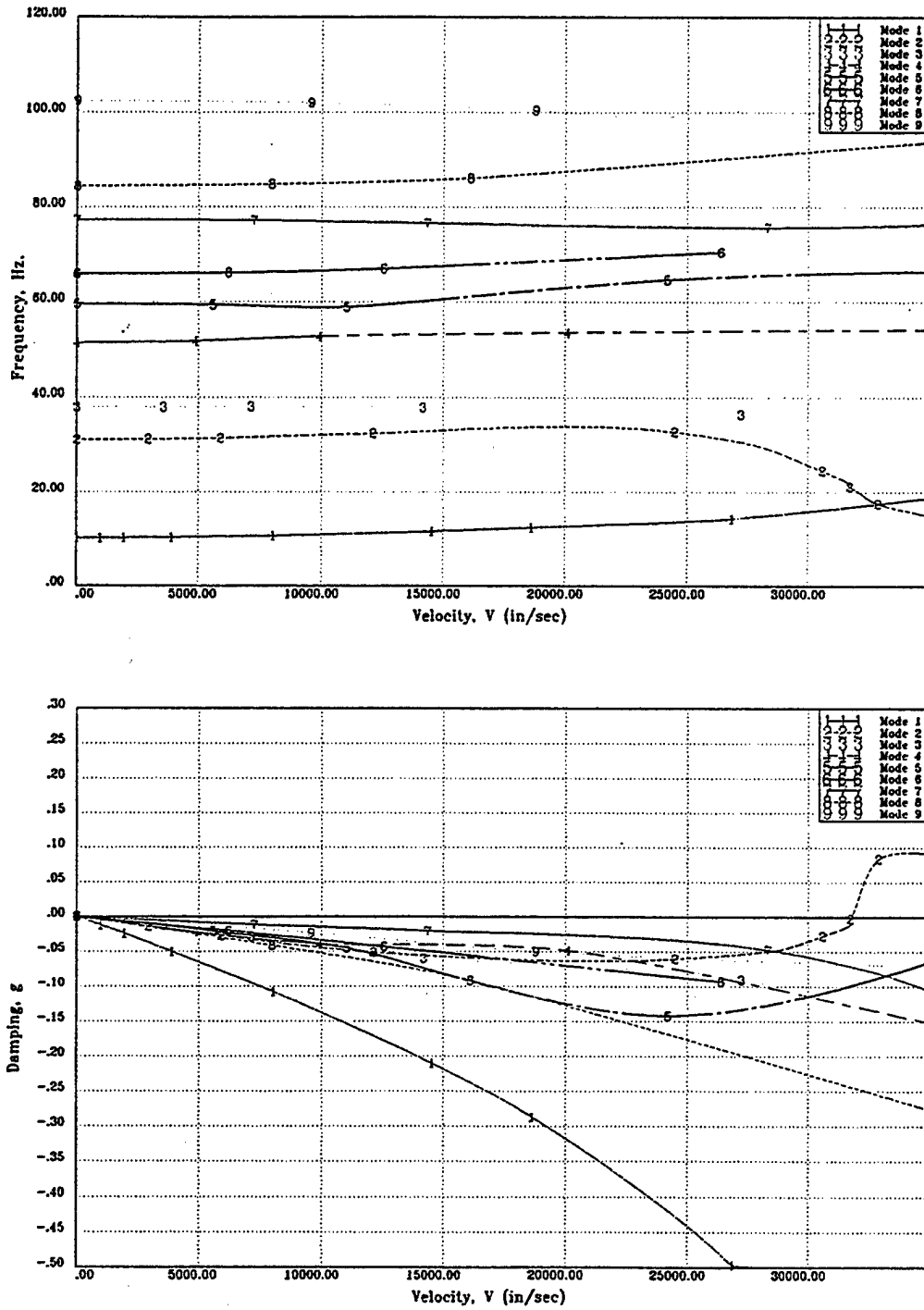


Figure 4.1.20 V-f and V-g Plots of GAF Model:  $M = 3.0$ , by ZONA7U of ASTROS\*  
(Flutter Speed = 31,743 in/sec, Flutter Frequency = 21.1 Hz).

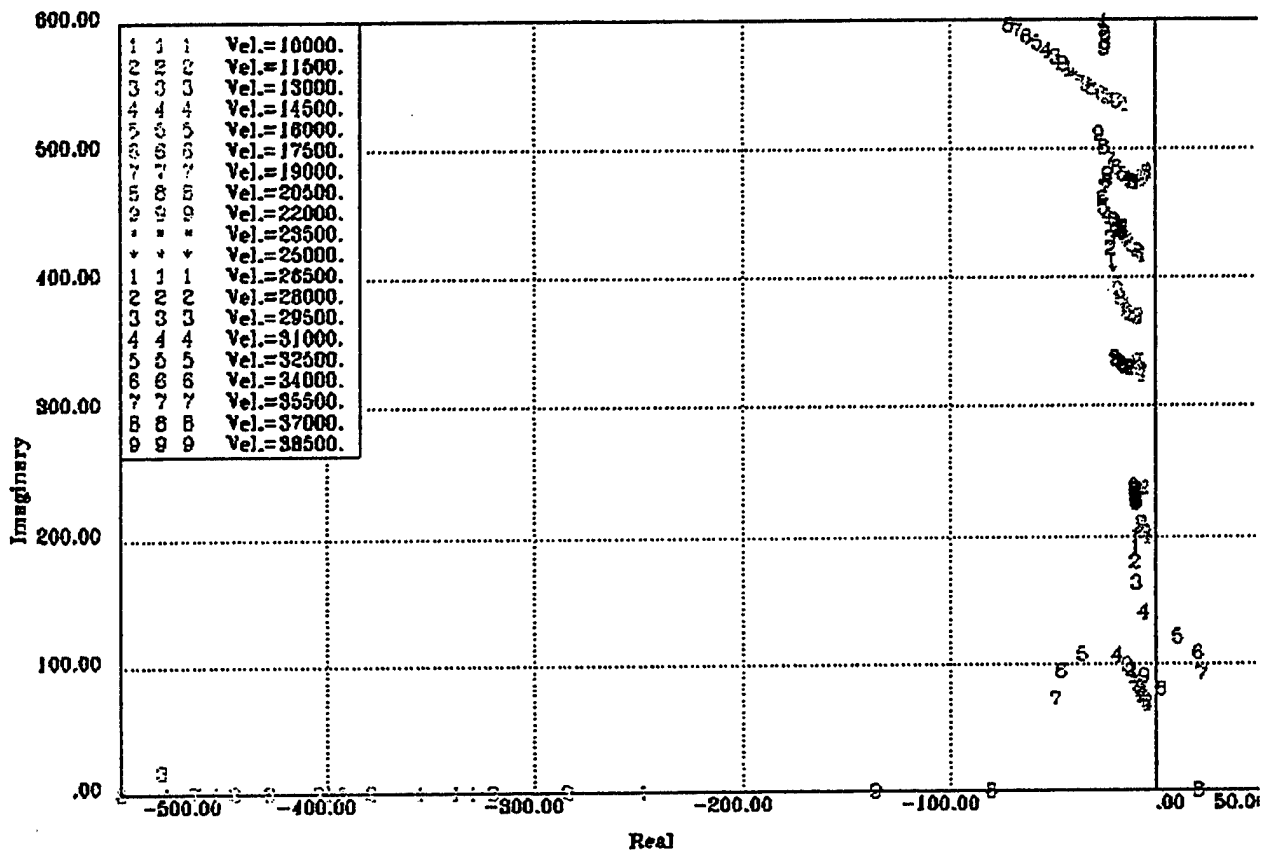


Figure 4.1.21 Root-Locus Plot of GAF Model:  $M = 3.0$ , by ZONA7U of ASTROS\*  
(Flutter Speed = 31,536 in/sec, Flutter Frequency = 21.3 Hz).

## 4.2 Case 1.b: GAF (Generalized Advanced Fighter) Wing Model Optimization

- **Purpose:** To test a public domain model in static, normal modes, and flutter optimization and MDO.
- **Description of input and results:**

### 4.2.1 Static Optimization

Static structural design optimization was performed. The design variables were the thicknesses of all skin elements. The objective function was the total weight of the skins. The constraints were the requirements for wing tip displacement and the stresses in the skins. The required wing tip displacement, 27.07 in, was the same as the result in the analysis of the original wing model. The required stress of 64,000 psi was the maximum stress in the same analysis. The number of global design variables was 52, and the design variables and their numbering are shown in Fig 4.2.1. The design variables were defined by DESVARP cards, which converted the properties of the elements into design variables. The upper and lower skins had the same property numbers and, thus, were the same design variables. This had the effect of linking the design variables of the upper and lower skins. The lower boundary of the design variables was the minimum material size, 0.118 in.

As a result of the static design optimization, the weight was reduced from 343.49 lbs to 313.37 lbs. In this optimization, the thicknesses of all skins started from their minimum basic material sizes. The iteration history of the design optimization is shown in Fig 4.2.2 and Table 4.2.1. The required CPU time was 1 minute 55.5 seconds. An 8.8 % weight reduction was achieved for this short CPU time in 15 iterations. The convergence was excellent.

### 4.2.2 Normal Modes Optimization

In the normal modes optimization, the lower bound of the first frequency was used as a constraint. The required frequency of 10.22 Hz was the same as the result from the original analysis of the model.

As a result of the normal modes design optimization, the weight was reduced from the original weight of 343.49 lbs to 312.26 lbs. The iteration history of the design optimization is also shown in Fig 4.2.2 and in Table 4.2.2. The required CPU time was 2 minute 48.3 seconds. A 9.1 % weight reduction was achieved for this short CPU time in 15 iterations. The convergence was excellent for this case with a structural design optimization and only one constraint.

### 4.2.3 Design Optimization for Static Loads and Normal Modes

Design optimization for static loads and normal modes was then performed. Displacements, stresses, and the lowest frequency were used as constraints. The constraint values, the required wing tip displacement of 27.07 in, the required maximum stress of 64,000 psi, and the required lowest frequency of 10.22 Hz, were the same as resulted from the original analyses.

As a result of the design optimization for the disciplines of statics and normal modes, the weight was reduced from 343.49 *lbs*, the weight of the original structure, to 313.28 *lbs*, for a reduction of about 10 %. More weight could still be taken off for smaller minimum basic sizes. The iteration history of the design optimization is again shown in Fig 4.2.2 and in Table 4.2.3. The final design variable values are given in Table 4.2.4. In this optimization, the initial design variable values were the minimum basic sizes not those from the original structure. This means that the design optimization can be performed easily without any initial sizing calculations either manually or by CAD.

#### 4.2.4 Flutter Optimization

Structural design optimization with a flutter speed constraint was performed for the GAF model at  $M=0.85$ . ZONA6 in ASTROS\* was used for calculating the aerodynamic loads. The constrained flutter speed was 16,107.8 *in/sec*. Flutter sensitivities with respect to design variables were calculated, the flutter constraints were formulated by linear approximation, and the optimization problem was solved using the optimizer NPSOL. The derivatives of the mass matrix and the stiffness matrix, necessary to calculate the flutter sensitivities, were obtained using the MAPOL language in ASTROS\* for the static and normal modes disciplines. An iteration history of the design optimization for flutter speed is shown in Fig 4.2.3 and in Table 4.2.5. In this case, the lengthy set of iterations was stopped without applying the convergence criteria since the intent was only to show the convergence behavior.

#### 4.2.5 Multidisciplinary Design Optimization of Statics, Normal Modes, and Flutter

With flutter speed, static strength, and frequency constraints, multidisciplinary design optimization was performed for the GAF model. The objective function was the total structural weight. The approximate optimization problem was calculated by NPSOL. The sensitivities of the static strength and frequency constraints, as well as the derivatives of the mass and stiffness matrices that are necessary to calculate the flutter sensitivities were obtained via the MAPOL programming language in ASTROS\* from the static and normal modes disciplines. The sensitivity of the objective function, the total structural weight, was also obtained via MAPOL. The constraint values were the required wing tip displacement of 27.07 *in*, the required maximum stress of 64,000 *psi*, the required lowest frequency of 10.22Hz, and the required flutter speed of 16,108 *in/sec*. An iteration history of the multidisciplinary optimization with strength, displacement, natural frequency, and flutter speed constraints is shown in Fig 4.2.4 and Table 4.2.6. The final design variable values are given in Table 4.2.7. A weight reduction of 15.57 *lbs* was achieved compared with the weight of the original model, 343.49 *lbs*; this was a 4.5 % weight reduction in 6 iterations. The GAF model was an actual aircraft wing model supposed to be well designed at the outset, and the material minimum basic sizes were quite thick. Thus, a 4.5 % weight reduction in this small number of iterations can be considered a good result since strength, displacement, normal modes, and flutter constraints were considered simultaneously.

**Table 4.2.1: Design Iteration History of GAF Model: Structural Optimization for Static Loads.**

Iteration Number	Objective Function Evaluation	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
1	2.19373E+02 (Initial Function Value)				
2	2.86841E+02	90	21	45	27 not Converged
3	3.50363E+02	100	8	32	14 not Converged
4	3.40345E+02	36	11	18	6 not Converged
5	3.35738E+02	21	4	16	16 not Converged
6	3.32504E+02	41	3	18	17 not Converged
7	3.21375E+02	22	7	16	4 not Converged
8	3.18522E+02	22	7	17	10 not Converged
9	3.17345E+02	25	3	20	4 not Converged
10	3.16361E+02	23	3	20	4 not Converged
11	3.15494E+02	18	2	17	3 not Converged
12	3.14714E+02	18	3	18	3 not Converged
13	3.14138E+02	19	3	19	3 not Converged
14	3.13609E+02	20	3	19	6 not Converged
15	3.13368E+02	14	2	19	3 Converged

The Final Objective Function Value is:	Fixed	=	3.28112E+02
	+ Designed	=	3.13368E+02
	Total	=	6.41480E+02

**Table 4.2.2 Design Iteration History of GAF Model: Structural Optimization for Normal Modes by ASTROS\*.**

Iteration Number	Objective Function	Function Evaluation	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
1	2.19373E+02	(Initial Function Value)				
2	2.71428E+02	90	21	1	1	not Converged
3	3.30081E+02	93	21	1	1	not Converged
4	3.50735E+02	88	7	1	1	not Converged
5	3.35437E+02	31	6	1	1	not Converged
6	3.26556E+02	23	5	1	1	not Converged
7	3.21226E+02	23	5	1	1	not Converged
8	3.18468E+02	24	5	1	1	not Converged
10	3.15728E+02	37	3	1	1	not Converged
11	3.14820E+02	22	4	1	1	not Converged
12	3.13932E+02	22	4	1	1	not Converged
13	3.13314E+02	18	3	1	1	not Converged
14	3.12698E+02	22	4	1	1	not Converged
15	3.12255E+02	26	2	1	1	Converged

The Final Objective Function Value is:	Fixed	=	3.28112E+02
	+ Designed	=	3.12255E+02
	Total	=	6.40367E+02

**Table 4.2.3 Design Iteration History of GAF Model:  
Structural Optimization for Statics and Normal Modes by ASTROS\*.**

Iteration Number	Objective Function	Function Evaluation	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
1	2.19373E+02 (Initial Function Value)					
2	2.96459E+02	N/A	FSD	N/A	FSD	not Converged
3	3.06451E+02	N/A	FSD	N/A	FSD	not Converged
4	3.04878E+02	N/A	FSD	N/A	FSD	not Converged
8	3.16221E+02	15	4	35	3	not Converged
9	3.15302E+02	18	3	35	3	not Converged
10	3.14613E+02	18	3	34	3	not Converged
11	3.14112E+02	10	3	34	4	not Converged
12	3.13653E+02	30	2	34	13	not Converged
13	3.13341E+02	16	2	34	3	not Converged
14	3.13282E+02	14	2	36	3	Converged
The Final Objective Function Value is:				Fixed	=	3.28112E+02
				+ Designed	=	3.13282E+02
				Total	=	6.41394E+02

**Table 4.2.4 Final Design Variables of GAF Model:  
Structural Optimization for Statics and Normal Modes by ASTROS\*.**

Design Variable	Design Value	Minimum Value	Maximum Value	Objective Sensitivity
102	1.00000E+00	1.00000E+00	2.63158E+01	6.17620D+01
501	1.00000E+00	1.00000E+00	1.00000E+01	2.40229D+00
502	1.00000E+00	1.00000E+00	1.00000E+01	2.37495D+00
503	6.32244E+00	1.00000E+00	1.00000E+01	2.39868D+00
504	1.00000E+00	1.00000E+00	1.00000E+01	2.79464D+00
505	1.00000E+00	1.00000E+00	1.00000E+01	1.80651D+00
506	1.00000E+00	1.00000E+00	1.00000E+01	4.44667D+00
507	1.00000E+00	1.00000E+00	1.00000E+01	4.39610D+00
508	5.62066E+00	1.00000E+00	1.00000E+01	4.43999D+00
509	1.00000E+00	1.00000E+00	1.00000E+01	5.17293D+00
510	1.00000E+00	1.00000E+00	1.00000E+01	3.34383D+00
511	1.00000E+00	1.00000E+00	1.00000E+01	3.96945D+00
512	1.00000E+00	1.00000E+00	1.00000E+01	3.92430D+00
513	4.27849E+00	1.00000E+00	1.00000E+01	3.96349D+00
514	1.00000E+00	1.00000E+00	1.00000E+01	4.61772D+00
515	1.00000E+00	1.00000E+00	1.00000E+01	2.98490D+00



516	1.00000E+00	1.00000E+00	1.00000E+01	3.49222D+00
517	1.11060E+00	1.00000E+00	1.00000E+01	3.45248D+00
518	2.29648E+00	1.00000E+00	1.00000E+01	3.48694D+00
519	1.00000E+00	1.00000E+00	1.00000E+01	8.12499D+00
520	1.00000E+00	1.00000E+00	1.00000E+01	2.62597D+00
521	1.00000E+00	1.00000E+00	1.00000E+01	3.01498D+00
522	1.11721E+00	1.00000E+00	1.00000E+01	2.98071D+00
523	1.43451E+00	1.00000E+00	1.00000E+01	3.01046D+00
524	1.00000E+00	1.00000E+00	1.00000E+01	7.01463D+00
525	1.00000E+00	1.00000E+00	1.00000E+01	2.26705D+00
526	1.00000E+00	1.00000E+00	1.00000E+01	2.53777D+00
527	1.00000E+00	1.00000E+00	1.00000E+01	2.50890D+00
528	1.00000E+00	1.00000E+00	1.00000E+01	2.53393D+00
529	1.00000E+00	1.00000E+00	1.00000E+01	5.90423D+00
530	1.00000E+00	1.00000E+00	1.00000E+01	1.90813D+00
531	1.00000E+00	1.00000E+00	1.00000E+01	2.06054D+00
532	1.00000E+00	1.00000E+00	1.00000E+01	2.03709D+00
533	1.00000E+00	1.00000E+00	1.00000E+01	2.05740D+00
534	1.00000E+00	1.00000E+00	1.00000E+01	4.79383D+00
535	1.00000E+00	1.00000E+00	1.00000E+01	1.54923D+00
536	1.00000E+00	1.00000E+00	1.00000E+01	1.58330D+00
537	1.00000E+00	1.00000E+00	1.00000E+01	1.56532D+00
538	1.00000E+00	1.00000E+00	1.00000E+01	1.58091D+00
539	1.00000E+00	1.00000E+00	1.00000E+01	3.68346D+00
540	1.00000E+00	1.00000E+00	1.00000E+01	1.19032D+00
541	1.00000E+00	1.00000E+00	1.00000E+01	6.12696D-01
542	1.00000E+00	1.00000E+00	1.00000E+01	6.05731D-01
543	1.00000E+00	1.00000E+00	1.00000E+01	6.11756D-01
544	1.00000E+00	1.00000E+00	1.00000E+01	1.42533D+00
545	1.00000E+00	1.00000E+00	1.00000E+01	4.60569D-01

**Table 4.2.5 Design Iteration History of GAF Model:  
Structural Optimization with Flutter Constraint at  $M = 0.85$ .**

Iteration No.	Weight (lbs)	Flutter Speed (in/sec)	Flutter Frequency (rad/sec)
1	343.78	16107.9 (Constraint)	105.74
2	324.12	16029.3	103.21
3	348.26	16200.6	103.85
4	315.77	15979.9	102.46
5	339.22	16158.3	103.13
6	315.77	15979.0	102.46
7	327.59	16076.0	102.86
8	339.76	16162.0	103.03
9	327.47	16077.4	102.78
10	333.61	16121.0	102.90
11	328.68	16085.8	102.82
12	333.15	16104.1	102.85

**Table 4.2.6 Design Iteration History of GAF Model:  
Multidisciplinary Design Optimization at  $M = 0.85$   
(Stress + Displacement + Natural Frequency +Flutter Speed).**

Iteration No.	Weight (lbs)	F. Speed (in/sec)	F.freq. (Hz)	Tip Disp. (in)	M. Stress (psi)	1 <sup>st</sup> Freq. (Hz)
Required		16,107.8		27.38	64,000	10.208
1	219.37	15,232.2	13.72	63.38	164,000	6.00
2	324.61	16,086.6	14.38	37.20	125,000	8.07
3	386.50	16,517.5	14.42	25.57	76,260	9.32
4	366.36	16,492.7	16.42	25.29	64,260	10.28
5	339.64	16,267.7	16.60	26.44	62,550	10.32
6	328.86	16,112.3	16.45	26.44	62,480	10.32
7	327.92	16,106.2	16.44	26.80	63,650	10.27

**Table 4.2.7 Final Design Variable Values of GAF Model:  
Multidisciplinary Design Optimization at  $M = 0.85$   
(Stress + Displacement + Natural Frequency +Flutter Speed).**

Variable	State	Value	L. bound	U. bound	Lagr multip.
VARBL 1	LL	1.0000	1.0000	1.0100	61.60661
VARBL 2	LL	1.3210	1.3210	1.3476	2.417356
VARBL 3	LL	3.0350	3.0350	3.0960	2.413862
VARBL 4	LL	5.0275	5.0275	5.1286	2.405284
VARBL 5	LL	1.0000	1.0000	1.0100	2.803832
VARBL 6	LL	1.0000	1.0000	1.0100	1.755699
VARBL 7	LL	1.3176	1.3176	1.3441	4.126373
VARBL 8	LL	2.8860	2.8860	2.9441	4.255834
VARBL 9	LL	4.3147	4.3147	4.4014	4.670451
VARBL 10	LL	1.0000	1.0000	1.0100	5.299779
VARBL 11	LL	1.0000	1.0000	1.0100	3.263696
VARBL 12	LL	1.1785	1.1785	1.2022	3.411701
VARBL 13	LL	2.1322	2.1322	2.1751	2.354970
VARBL 14	FR	3.4188	3.4037	3.4721	.000000
VARBL 15	LL	1.0000	1.0000	1.0100	4.830757
VARBL 16	LL	1.0000	1.0000	1.0100	2.668114
VARBL 17	LL	1.3602	1.3602	1.3876	2.827459
VARBL 18	LL	1.7225	1.7225	1.7571	2.866750
VARBL 19	LL	1.6573	1.6573	1.6906	3.743286
VARBL 20	LL	1.0000	1.0000	1.0100	8.890014
VARBL 21	LL	1.0000	1.0000	1.0100	2.52555
VARBL 22	LL	1.1280	1.1280	1.1507	2.982377
VARBL 23	LL	1.3032	1.3032	1.3294	3.038492
VARBL 24	LL	1.2682	1.2682	1.2937	3.038216
VARBL 25	LL	1.0000	1.0000	1.0100	7.012024
VARBL 26	LL	1.0000	1.0000	1.0100	2.286383
VARBL 27	LL	1.0000	1.0000	1.0100	2.525305
VARBL 28	LL	1.0221	1.0221	1.0427	2.497412
VARBL 29	LL	1.0000	1.0000	1.0100	2.541466
VARBL 30	LL	1.0000	1.0000	1.0100	5.922578
VARBL 31	LL	1.0000	1.0000	1.0100	1.907490
VARBL 32	LL	1.0000	1.0000	1.0100	2.060489
VARBL 33	LL	1.0000	1.0000	1.0100	2.033227
VARBL 34	LL	1.0000	1.0000	1.0100	2.053379
VARBL 35	LL	1.0000	1.0000	1.0100	4.786958
VARBL 36	LL	1.0000	1.0000	1.0100	1.548409
VARBL 37	LL	1.0000	1.0000	1.0100	1.582935
VARBL 38	LL	1.0000	1.0000	1.0100	1.565027
VARBL 39	LL	1.0000	1.0000	1.0100	1.580414
VARBL 40	LL	1.0000	1.0000	1.0100	3.682065
VARBL 41	LL	1.0000	1.0000	1.0100	1.189650

VARBL 42	LL	1.0000	1.0000	1.0100	.611605
VARBL 43	LL	1.0000	1.0000	1.0100	.605568
VARBL 44	LL	1.0000	1.0000	1.0100	.611541
VARBL 45	LL	1.0000	1.0000	1.0100	1.424990
VARBL 46	LL	1.0000	1.0000	1.0100	.460554
VARBL 47	LL	1.4474	1.4474	1.4765	4.104928
VARBL 48	LL	2.8321	2.8321	2.8890	4.009018
VARBL 49	LL	4.4457	4.4457	4.5350	3.914433
VARBL 50	LL	1.3709	1.3709	1.3985	4.135922
VARBL 51	LL	2.8615	2.8615	2.9190	3.974858
VARBL 52	LL	4.3594	4.3594	4.4470	3.893831

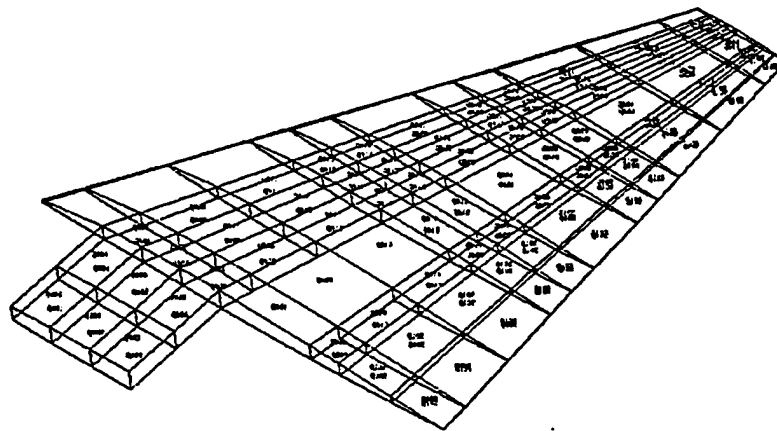


Figure 4.2.1 Design Variables and Numbering of GAF Model.

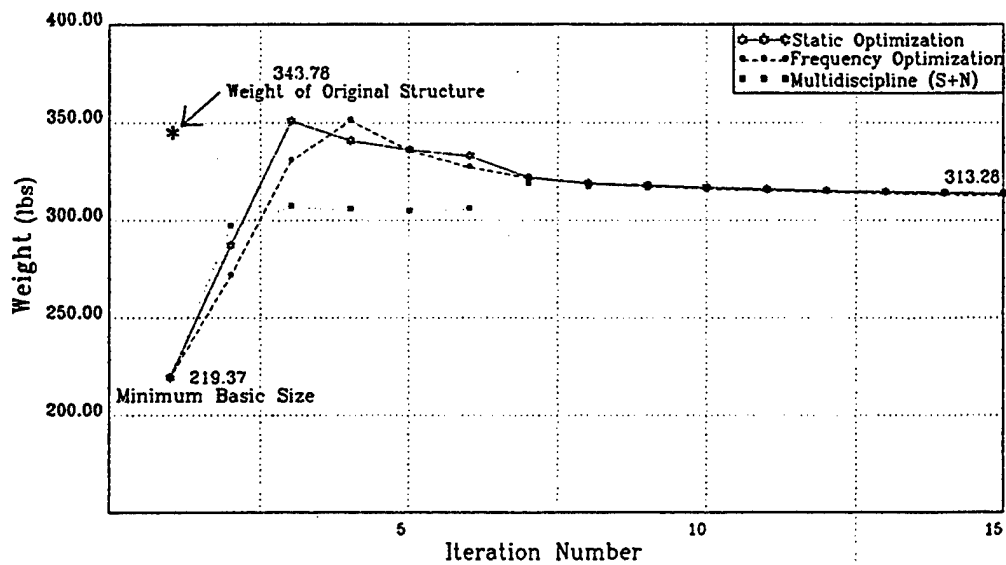


Figure 4.2.2 Iteration History of Structural Design Optimization of GAF Model: Statics, Normal Modes, and Both Disciplines (S + N) by ASTROS\*.

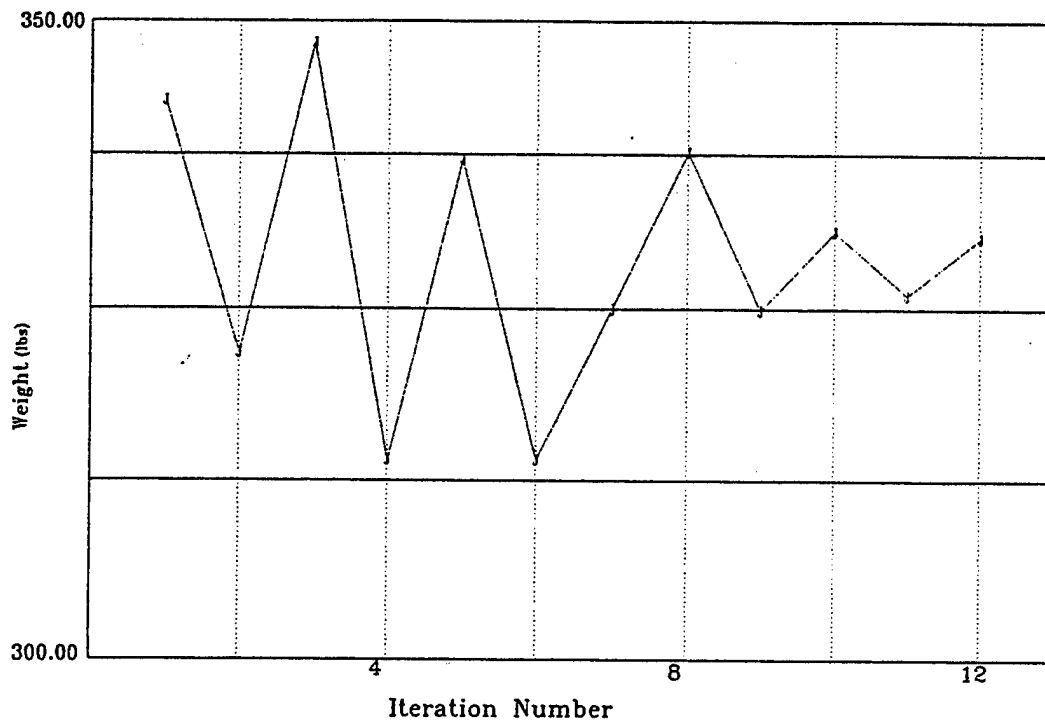


Figure 4.2.3 Iteration History of Structural Design Optimization of GAF Model: Flutter Discipline at  $M=0.85$ , by Root-Locus Method.

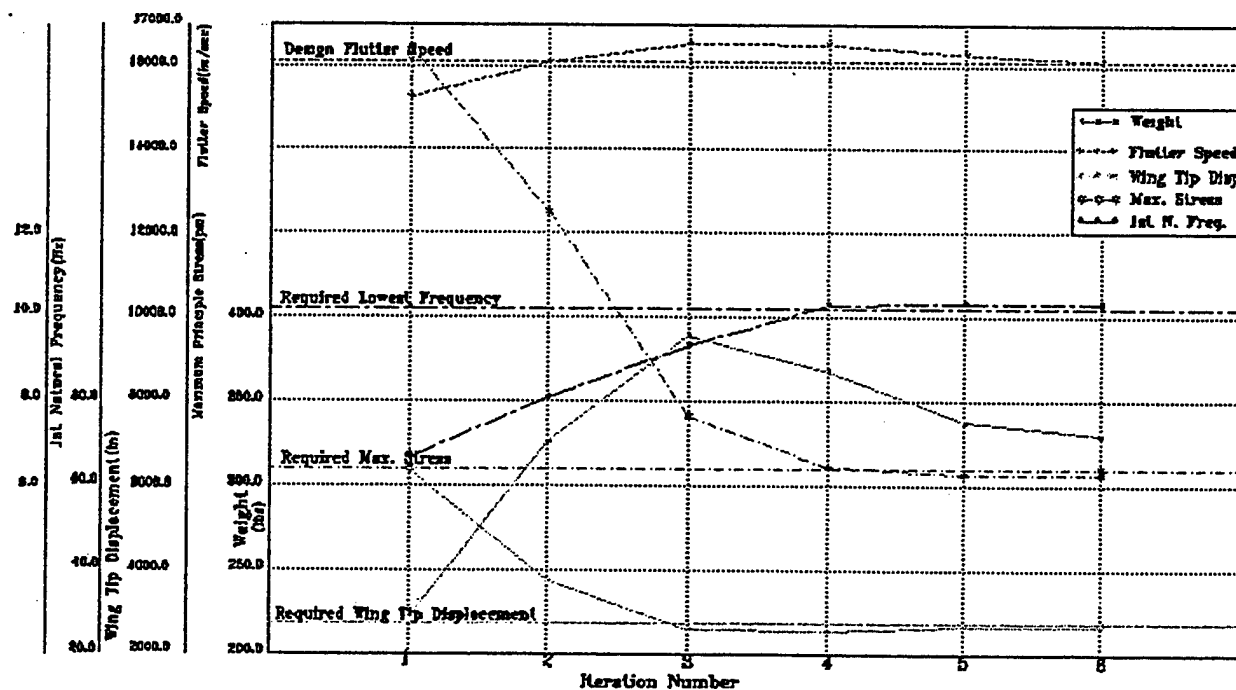


Figure 4.2.4 Design Iteration History of GAF Model: Multidisciplinary Design Optimization (Constraints on stress, displacement, natural frequency, flutter speed).

## ***DAST WING MODEL***

### **4.3 Case 2.a: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Analysis**

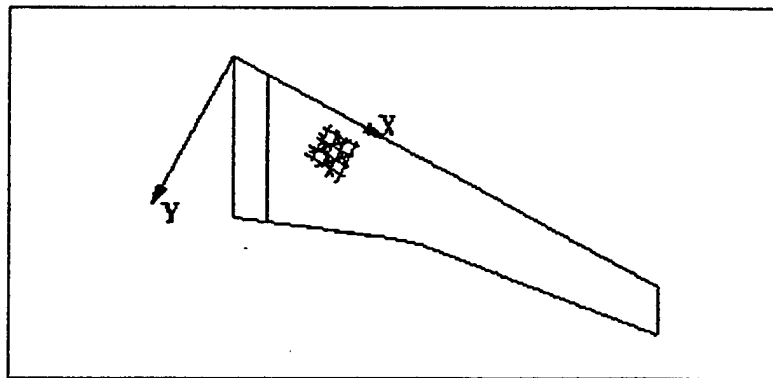
- **Purpose:** To test a composite structural wing model in static aeroelastic, normal modes, and flutter analysis.
- **Description of input and results:**

The DAST wing model was a structural model of a supercritical wing used on a drone in a flight test facility. The ASTROS\* and MSC/NASTRAN data for the DAST model were obtained by converting data from an EAL (Engineering Analysis Language) model. The DAST model was a skin-spar-rib type wing made of composite material. To avoid an excessive number of local modes in the normal modes analysis and to improve performance of the model in the static aeroelastic and flutter analyses, ribs were added to the original structure. The stacking sequence of the composite skin panels was changed from the original stacking sequence  $[90/0]$  to a more realistic  $[90/\pm 45/0]$ .

Analyses and structural design optimizations of a composite wing model were the specific goal here. The boundary condition of the structure was free at the root, and its behavior was thought to be the same as that of a full aircraft. More details about the model, the test cases, and their application to this model are given in Appendix A.

#### **4.3.1 Structural Configuration and Static Aeroelastic Analysis**

A fuselage weight of 1177.2 *lbs* was added to the wing root by a CONM2 entry, and the total weight of the model became 1250.0 *lbs*, half the weight of the DAST model. The wing had two trailing edge control surfaces. Steady flight in the trim condition with control surface deflections was assumed. The skins were modeled by plate elements, composed of four plies. The material coordinates are shown in the following:



The lamina material of the composite was assumed to be AS/3501 graphite/epoxy. The stiffness and strength of each lamina are given below:

Lamina Stiffness:

$$E_1 = 1.8 \times 10^6 \text{ (psi)}$$

$$E_2 = 0.86 \times 10^6 \text{ (psi)}$$

$$\nu_{12} = 0.3$$

$$G_{12} = G_{1z} = G_{2z} = 0.46 \times 10^6 \text{ (psi)}$$

$$\rho = 0.057 \text{ (lbs/in}^3\text{)}$$

Lamina Strength:

$$S_L^{(+)} = 210,000 \text{ (psi)}$$

$$S_L^{(-)} = 170,000 \text{ (psi)}$$

$$S_T^{(+)} = 7,000 \text{ (psi)}$$

$$S_T^{(-)} = 36,000 \text{ (psi)}$$

$$S_{LT} = 9,000 \text{ (psi)}$$

The skins were modeled by **CQUAD4** and **CTRIA3** elements and the spar caps by **CBAR** elements. The property cards for the **CQUAD4** and **CTRIA3** elements were **PCOMP** entries. The structural configuration of the FEM model is shown in Fig 4.3.1. A summary of the number of grid points and elements is shown in the following.

NUMBER OF GRID POINTS	428
NUMBER OF ELEMENTS	1680
CROD	432
CONM2	449
CCBAR	172
CQUAD4	623
CTRIA3	4

Two **CAERO7** cards were used to generate the aerodynamic boxes because the trailing edge consisted of two separate straight lines. The inboard wing was composed of 15 x 7 boxes and the outboard wing of 15 x 10 boxes, thus, the total number of boxes was 275.

Symmetric static aeroelastic analysis was performed and the trim parameters, angle-of-attack and control surface deflection angle, were calculated under a 10g pull-up condition with zero pitching rate and zero pitching acceleration at Mach  $M=0.80$ . The inboard control surface was assumed to be fixed. The trim parameters were calculated when the structure was rigid and when the structure had elastic deformation. The displacements at given **GRID** points and the stresses in each ply of the plate elements were calculated at this trim condition. **ZONA6** was used to calculate the aerodynamics.

The weight data output is shown in Table 4.3.1 including the fuselage weight. The longitudinal stability derivatives of the aircraft for both the rigid and elastic cases are shown in Table 4.3.2. The calculated trim parameters for both the rigid and flexible structure at the trim condition are given in Table 4.3.3. The calculated angle-of-attack,  $4.06^\circ$  for the rigid case, was reasonable and

a large deflection angle,  $-45.98^\circ$ , of the control surface was necessary to obtain trim since no horizontal tail was included. The steady pressure distributions as attributed to each parameter such as thickness, camber, angle-of-attack, pitching rate, pitching acceleration, and control surface deflection are shown in Table 4.3.4. The steady pressure distributions in the trim condition for all trim parameters are shown in Fig 4.3.2. The vertical displacement at GRID point 415 on the wing tip was 5.506 *in*, and the deflection shape in the trim condition is presented in Fig 4.3.3. This value was later used as constraint in the structural design optimization. The required CPU time was 9 minutes 25.0 seconds.

#### 4.3.2 Aerodynamic Configuration and Analysis by ENSAERO

The aerodynamic analysis of the wing was performed by the CFD code, ENSAERO. The aerodynamic configuration of the wing is shown in Fig 4.3.4. The input data for this model were very similar to those for the GAF model. Steady aerodynamic pressure coefficients were calculated for Navier-Stokes flow. For all cases, the Reynolds number was 10,000,000, and spanwise and normal viscous terms were used. For turbulence, the Baldwin-Lomax turbulence model was used and, for correction for vortex flow, Degani-Schiff modeling. The iteration indices were less than  $1.0\text{E-}09$ , and there were about 500 iterations for Euler flow and then another 500+ iterations for Navier-Stokes flow. The total size of the grid was  $151 \times 44 \times 34$  in the x-, y-, and z- directions, respectively. The number of grid points on the wing was  $61 \times 34$  on both the lower and upper surfaces. The results of the calculated aerodynamic pressure coefficients for Navier Stokes flow are shown in Fig 4.3.5 for four cases:

- (1)  $M = 0.70$ ,  $\alpha = 0.0^\circ$ , (Navier-Stokes Flow)
- (2)  $M = 0.70$ ,  $\alpha = 5.0^\circ$ , (Navier-Stokes Flow)
- (3)  $M = 0.80$ ,  $\alpha = 0.0^\circ$ , (Euler Flow)
- (4)  $M = 0.80$ ,  $\alpha = 0.0^\circ$ , (Navier-Stokes Flow)

Fig 4.3.5 shows that the DAST model was just entering the transonic regime at Mach  $M = 0.7$  when the angle-of-attack was  $0.0^\circ$  and was in the transonic regime at Mach 0.8. The strength of the shock in Euler flow was larger than that in Navier-Stokes flow.

#### 4.3.3 Normal Modes Analysis Using ASTROS\*

Natural frequencies, the associated modes shapes, and the generalized stiffness and mass matrices were calculated in the normal modes discipline as for the GAF model. To calculate eigenvalues, the INV (Inverse Power) method was used. Normal modes data for 10 modes from the lowest to 200.0 *Hz* were calculated for a symmetric boundary condition. The axial direction of the fuselage was fixed. The first two modes were the rigid body modes, vertical translation and pitching rotation. The lowest seven natural frequencies of the elastic modes were 11.3, 48.7, 55.7, 103.3, 130.8, 147.8, and 199.0 *Hz*. The required CPU time was 2 minutes 11.0 seconds.

The results of the computations are shown in Table 4.3.5, and the mode shapes are plotted in Fig 4.3.6. These data were later used in the flutter analysis. The lowest natural frequency, 10.22 *Hz*, was used as a constraint in the normal modes design optimization.



#### 4.3.4 Flutter Analysis

Flutter analyses were performed by the K-method in ASTROS\* and by the root-locus method for a Mach number of  $M = 0.80$  using ZONA6 and ZTAIC methods. The results from ASTROS\* and the root-locus method were compared and are shown in Table 4.3.6. The generalized unsteady aerodynamic loads calculated in ASTROS\* were used in the root-locus method.

These generalized unsteady aerodynamic loads at  $M = 0.85$  calculated by ZONA6 in ASTROS\* and are shown in Fig 4.3.7. The generalized unsteady aerodynamic loads calculated by ZONA6 and approximated by the minimum-state method at  $M = 0.85$  are presented in Fig 4.3.8. The V-f and V-g plots for the flutter results by ZONA6 in ASTROS\* are shown in Fig 4.3.9 and the root-locus plots to calculate the flutter speed using the aerodynamics of ZONA6 in ASTROS\* are given in Figs 4.3.10. The V-f and V-g plots for the flutter results by ZTAIC in ASTROS\* are shown in Fig 4.3.11, and the root-locus plots to calculate the flutter speed using the aerodynamics of ZTAIC in ASTROS\* are given in Figs 4.3.12. The flutter speed and flutter frequency by the K-method and ZONA6 were 14,358 *in/sec* and 48.67 *Hz*, respectively. The flutter speed and flutter frequency by the root-locus method and ZONA6 were 13,490 *in/sec* and 36.3 *Hz*, respectively. The flutter speed and flutter frequency by the K-method and ZTAIC were 11,800 *in/sec* and 56.01 *Hz*, respectively. Finally, the flutter speed and flutter frequency by the root-locus method and ZTAIC were 12,892 *in/sec* and 49.30 *Hz*, respectively. The required CPU time by the K-method and ZONA6 of ASTROS\* was 13 minutes 13.5 seconds and that by the K-method and ZTAIC of ASTROS\* 5 hours 22 minutes 31.4 seconds, respectively.

Table 4.3.1 Weight Data Output of DAST Model.

OUTPUT FROM GRID POINT WEIGHT GENERATOR					
REFERENCE POINT = 1					
XO = 2.417731E+02, YO = 1.805970E+01, ZO = 5.992480E+01					
MO					
* 1.3002E+03	0.0000E+00	0.0000E+00	0.0000E+00	-1.258E+03	6.7508E+03 *
* 0.0000E+00	1.3002E+03	0.0000E+00	1.2586E+03	0.000E+00	2.6715E+04 *
* 0.0000E+00	0.0000E+00	1.3002E+03	-6.7508E+03	-2.671E+04	0.0000E+00 *
* 0.0000E+00	1.2586E+03	-6.7508E+03	3.3057E+05	5.025E+04	2.8499E+04 *
* -1.2586E+03	0.0000E+00	-2.6715E+04	5.0253E+04	8.815E+05	1.1363E+03 *
* 6.7508E+03	2.6715E+04	0.0000E+00	2.8499E+04	1.136E+03	1.1457E+06 *
DIRECTION					
AXIS SYSTEM(S)	MASS	X-C.G.	Y-C.G.	Z-C.G.	
X	1.300231E+03	0.000000E+00	-5.192037E+00	-9.680215E-01	
Y	1.300231E+03	2.054661E+01	0.000000E+00	-9.680215E-01	
Z	1.300231E+03	2.054661E+01	-5.192037E+00	0.000000E+00	
I(Q)					
* 5.62043E+05 *					
* 2.22358E+05 *					
* 4.03149E+05 *					

Table 4.3.2 Non-Dimensional Longitudinal Stability Derivatives of DAST Model:  
10g Pull-up Maneuver,  $M = 0.8$ , by ZONA6 of ASTROS\* for Rigid and Flexible Structure.

TRIM IDENTIFICATION = 1		REFERENCE GRID = 446				
REFERENCE AREA = 2.8236E+03		REFERENCE CHORD = 4.0000E+01				
<< LIFT >> << PITCHING MOMENT >>						
	RIGID	RIGID	FLEX.	RIGID	RIGID	FLEXIBLE
PARAMETER	DIRECT	SPLINED		DIRECT	SPLINED	
Thickness/Camber	0.9860	0.9876	0.9097	-0.5291	-0.5291	-0.4653
Angle of Attack (1/deg)	0.2222	0.2224	0.2193	-0.0821	-0.0822	-0.0751
Angle of Attack (1/rad)	12.7330	12.7418	12.5669	-4.7045	-4.7117	-4.3015
Pitch Rate (s/deg)	0.3004	0.3007	0.2889	-0.1578	-0.1579	-0.1427
Pitch Rate (s/rad)	17.2142	17.2293	16.5505	-9.0398	-9.0457	-8.1754
Control Surface 1 (1/deg)	0.0255	0.0255	0.0241	-0.0119	-0.0119	-0.0110
Control Surface 1 (1/rad)	1.4584	1.4597	1.3820	-0.6799	-0.6804	-0.6292
Control Surface 2 (1/deg)	0.0105	0.0105	0.0086	-0.0104	-0.0104	-0.0085
Control Surface 2 (1/rad)	0.6039	0.6039	0.4951	-0.5945	-0.5945	-0.4863

**Table 4.3.3 Trim Parameters of DAST Model:**  
**10g Pull-up Maneuver,  $M = 0.80$ , by ZONA6 of ASTROS\* for Rigid and Flexible Structure.**

**TRIM RESULTS FOR TRIM SET 1 OF TYPE PITCH**

MACH NUMBER 8.00000E-01

DYNAMIC PRESSURE 6.55000E+00

VELOCITY 1.02700E+04

**TRIM PARAMETERS:**

DEFINITION	LABEL	FLEXIBLE	RIGID	
LOAD FACTOR	"NZ"	3.86399E+03	3.86399E+03	(Input)
PITCH ACCELERATION	"QACCEL"	0.00000E+00	0.00000E+00	$rad/s^2$ (Input)
ANGLE OF ATTACK	"ALPHA"	4.03914E+00	4.06115E+00	deg (Computed)
CONTROL SURFACE	"AIL1"	0.00000E+00	0.00000E+00	deg (Input)
CONTROL SURFACE	"AIL2"	-4.50767E+01	-4.59823E+01	deg (Computed)
PITCH RATE	"QRATE"	0.00000E+00	0.00000E+00	deg/s (Input)
THICKNESS/CAMBER	"THKCAM"	1.00000E+00	1.00000E+00	(Input)

**Table 4.3.4 Pressure Distribution of DAST Model:**  
**10g Pull-up Maneuver,  $M = 0.80$ , by ZONA6 of ASTROS\*, for Rigid Structure.**

**\*\*\*\*\* STEADY RIGID AERODYNAMIC PRESSURE OF TRIM PARAMETERS, MACH = 0.8**

	NZ	/ QACCEL	/ THKCAM	/ ALPHA	/ ORATE	/ AIL1	/ AIL2	/
EXT ID	1.00000	1.00000	1.00000	1.00000	1.00000	1.00000	1.00000	
100001	0.000E+00	0.0000E+00	0.1187E+01	0.3902E+00	0.1944E+02	0.1130E-01	0.1297E-02	
100002	0.000E+00	0.0000E+00	0.3618E-02	0.1648E+00	0.5510E+02	0.5688E-02	0.6083E-03	
100003	0.000E+00	0.0000E+00	0.3257E+00	0.1358E+00	0.7387E+02	0.5331E-02	0.5410E-03	
100004	0.000E+00	0.0000E+00	0.3145E+00	0.1146E+00	0.8996E+02	0.5203E-02	0.4977E-03	
100005	0.000E+00	0.0000E+00	0.2030E+00	0.9709E-01	0.1070E+03	0.5334E-02	0.4711E-03	
100006	0.000E+00	0.0000E+00	0.1223E+00	0.8566E-01	0.1186E+03	0.5604E-02	0.4587E-03	
100007	0.000E+00	0.0000E+00	0.1675E+00	0.7631E-01	0.1269E+03	0.5946E-02	0.4493E-03	
100008	0.000E+00	0.0000E+00	0.2747E+00	0.6763E-01	0.1321E+03	0.6348E-02	0.4390E-03	
100010	0.000E+00	0.0000E+00	0.3706E+00	0.5213E-01	0.1314E+03	0.7075E-02	0.4055E-03	
100011	0.000E+00	0.0000E+00	0.5720E+00	0.4458E-01	0.1249E+03	0.7226E-02	0.3770E-03	
100012	0.000E+00	0.0000E+00	0.7607E+00	0.3684E-01	0.1134E+03	0.7027E-02	0.3366E-03	
100013	0.000E+00	0.0000E+00	0.8239E+00	0.2910E-01	0.9704E+02	0.6332E-02	0.2843E-03	
100014	0.000E+00	0.0000E+00	0.7120E+00	0.2675E-01	0.9062E+02	0.5954E-02	0.2648E-03	
100095	0.000E+00	0.0000E+00	0.1553E+00	0.1345E+00	0.1924E+03	0.1359E-01	0.1047E-02	
100096	0.000E+00	0.0000E+00	0.3246E+00	0.1135E+00	0.1798E+03	0.1395E-01	0.9832E-03	
100097	0.000E+00	0.0000E+00	0.3363E+00	0.9745E-01	0.1695E+03	0.1480E-01	0.9392E-03	
100098	0.000E+00	0.0000E+00	0.3187E+00	0.8368E-01	0.1593E+03	0.1623E-01	0.9021E-03	
100099	0.000E+00	0.0000E+00	0.3592E+00	0.7209E-01	0.1489E+03	0.1820E-01	0.8664E-03	
100100	0.000E+00	0.0000E+00	0.4803E+00	0.6178E-01	0.1373E+03	0.2069E-01	0.8246E-03	
100101	0.000E+00	0.0000E+00	0.6898E+00	0.5213E-01	0.1240E+03	0.2341E-01	0.7692E-03	
100102	0.000E+00	0.0000E+00	0.9059E+00	0.4272E-01	0.1080E+03	0.2483E-01	0.6926E-03	
100103	0.000E+00	0.0000E+00	0.1037E+01	0.3365E-01	0.8960E+02	0.2183E-01	0.5918E-03	
100104	0.000E+00	0.0000E+00	0.9455E+00	0.3095E-01	0.8326E+02	0.1956E-01	0.5533E-03	
100105	0.000E+00	0.0000E+00	0.4757E+00	0.1950E-01	0.5492E+02	0.1143E-01	0.3741E-03	
200001	0.000E+00	0.0000E+00	0.1347E+01	0.6808E+00	0.7119E+03	0.4181E-01	0.4223E-02	
200002	0.000E+00	0.0000E+00	0.6021E+00	0.2752E+00	0.3165E+03	0.1890E-01	0.1857E-02	
200003	0.000E+00	0.0000E+00	0.4546E+00	0.2171E+00	0.2684E+03	0.1633E-01	0.1574E-02	

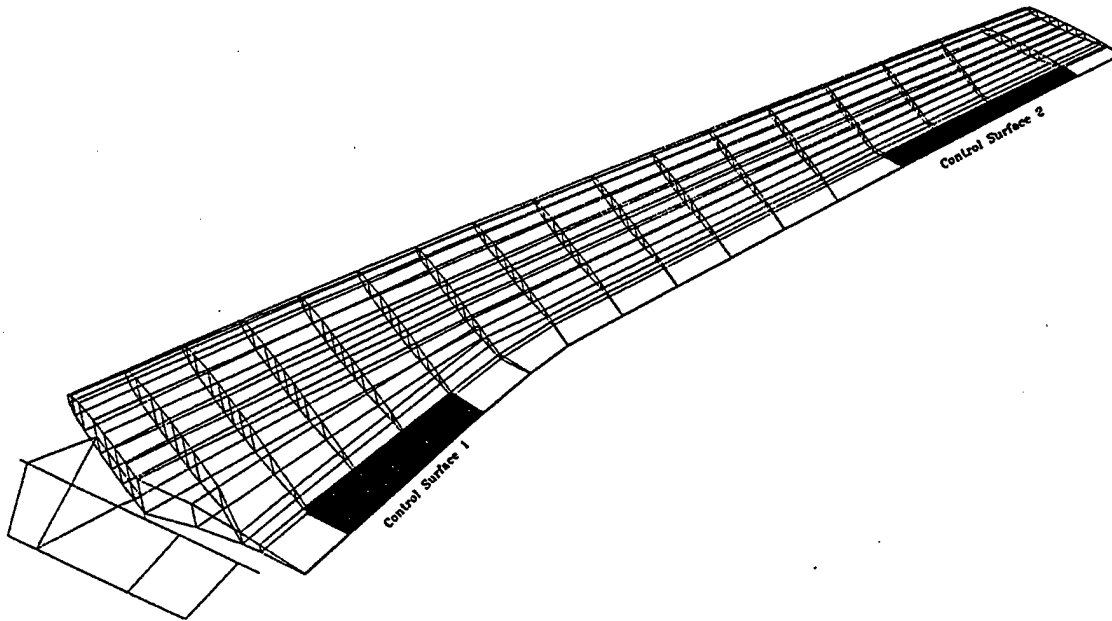
200004	0.000E+00	0.0000E+00	0.3411E+00	0.1745E+00	0.2343E+03	0.1468E-01	0.1382E-02
200005	0.000E+00	0.0000E+00	0.1682E+00	0.1392E+00	0.2075E+03	0.1374E-01	0.1245E-02
200006	0.000E+00	0.0000E+00	0.3490E+00	0.1173E+00	0.1910E+03	0.1351E-01	0.1175E-02
200007	0.000E+00	0.0000E+00	0.3562E+00	0.1005E+00	0.1777E+03	0.1358E-01	0.1127E-02
200008	0.000E+00	0.0000E+00	0.3296E+00	0.8611E-01	0.1650E+03	0.1378E-01	0.1088E-02
200009	0.000E+00	0.0000E+00	0.3721E+00	0.7399E-01	0.1524E+03	0.1393E-01	0.1049E-02
200010	0.000E+00	0.0000E+00	0.4953E+00	0.6319E-01	0.1392E+03	0.1375E-01	0.1002E-02
200141	0.000E+00	0.0000E+00	0.1783E+00	0.5911E-01	0.1498E+03	0.2110E-02	0.1439E-01
200142	0.000E+00	0.0000E+00	0.1566E+00	0.4419E-01	0.1179E+03	0.1622E-02	0.1467E-01
200143	0.000E+00	0.0000E+00	0.1282E+00	0.3330E-01	0.9427E+02	0.1258E-02	0.1525E-01
200144	0.000E+00	0.0000E+00	0.1625E+00	0.2552E-01	0.7700E+02	0.9911E-03	0.1575E-01
200145	0.000E+00	0.0000E+00	0.2705E+00	0.1968E-01	0.6344E+02	0.7840E-03	0.1564E-01
200146	0.000E+00	0.0000E+00	0.4903E+00	0.1504E-01	0.5200E+02	0.6138E-03	0.1425E-01
200147	0.000E+00	0.0000E+00	0.6968E+00	0.1123E-01	0.4173E+02	0.4692E-03	0.1147E-01
200148	0.000E+00	0.0000E+00	0.8203E+00	0.8135E-02	0.3242E+02	0.3474E-03	0.8347E-02
200149	0.000E+00	0.0000E+00	0.6733E+00	0.7355E-02	0.2975E+02	0.3151E-03	0.7491E-02
200150	0.000E+00	0.0000E+00	0.2064E+00	0.4303E-02	0.1867E+02	0.1880E-03	0.4241E-02

Table 4.3.5 Results of Normal Modes Analysis of DAST Model.

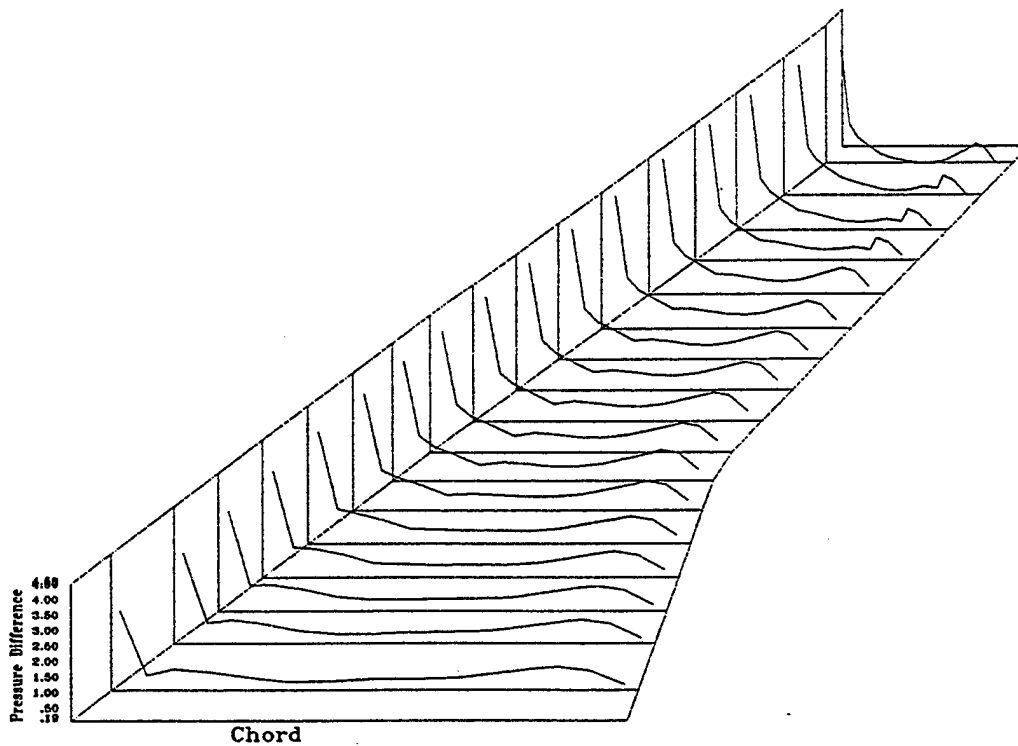
MODE	EXTRACTION	EIGENVALUE	FREQUENCY	GENERALIZED	
	ORDER	(rad/sec) <sup>2</sup>	(Hz)	MASS	STIFFNESS
1	1	0.00000E+00	0.00000E+00	1.00000E+00	0.00000E+00
2	2	0.00000E+00	0.00000E+00	1.00000E+00	0.00000E+00
3	7	5.03062E+03	1.12884E+01	1.00000E+00	5.03062E+03
4	6	9.34976E+04	4.86654E+01	1.00000E+00	9.34976E+04
5	4	1.22573E+05	5.57209E+01	1.00000E+00	1.22573E+05
6	3	4.21470E+05	1.03325E+02	1.00000E+00	4.21470E+05
7	5	6.75673E+05	1.30824E+02	1.00000E+00	6.75673E+05
8	8	8.62662E+05	1.47822E+02	1.00000E+00	8.62662E+05
9	9	1.56335E+06	1.98998E+02	1.00000E+00	1.56335E+06

Table 4.3.6 Results of Flutter Analyses of DAST Model.

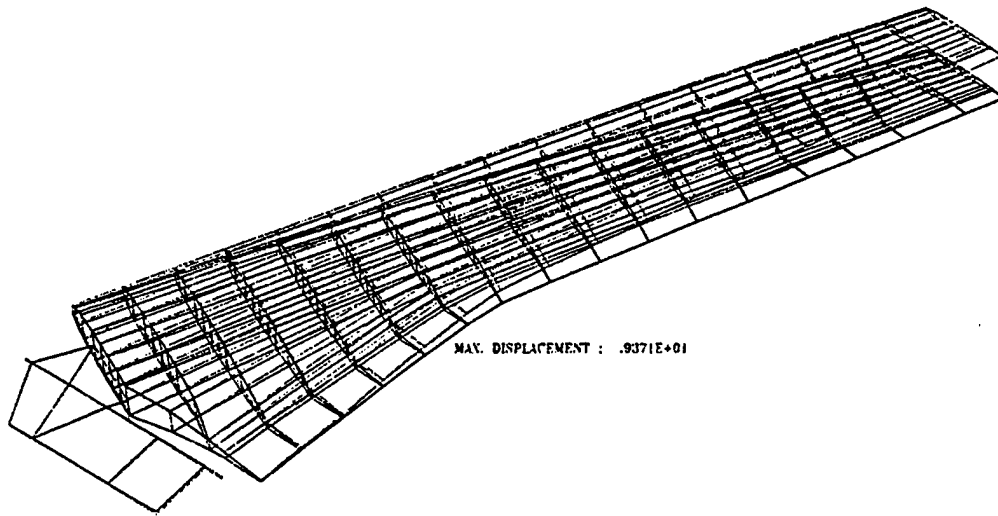
No.	Mach	Method	Flutter Speed (in/sec)	Flutter Freq. (Hz)	Remarks
1	0.80	k-method (ZONA6)	14,357.3	48.67	
2	0.80	Root-locus (ZOZA6)	13,489.5	36.30	
3	0.80	k-method (ZTAIC)	11,800.0	56.01	
4	0.80	Root-locus (ZTAIC)	12,892.0	49.30	



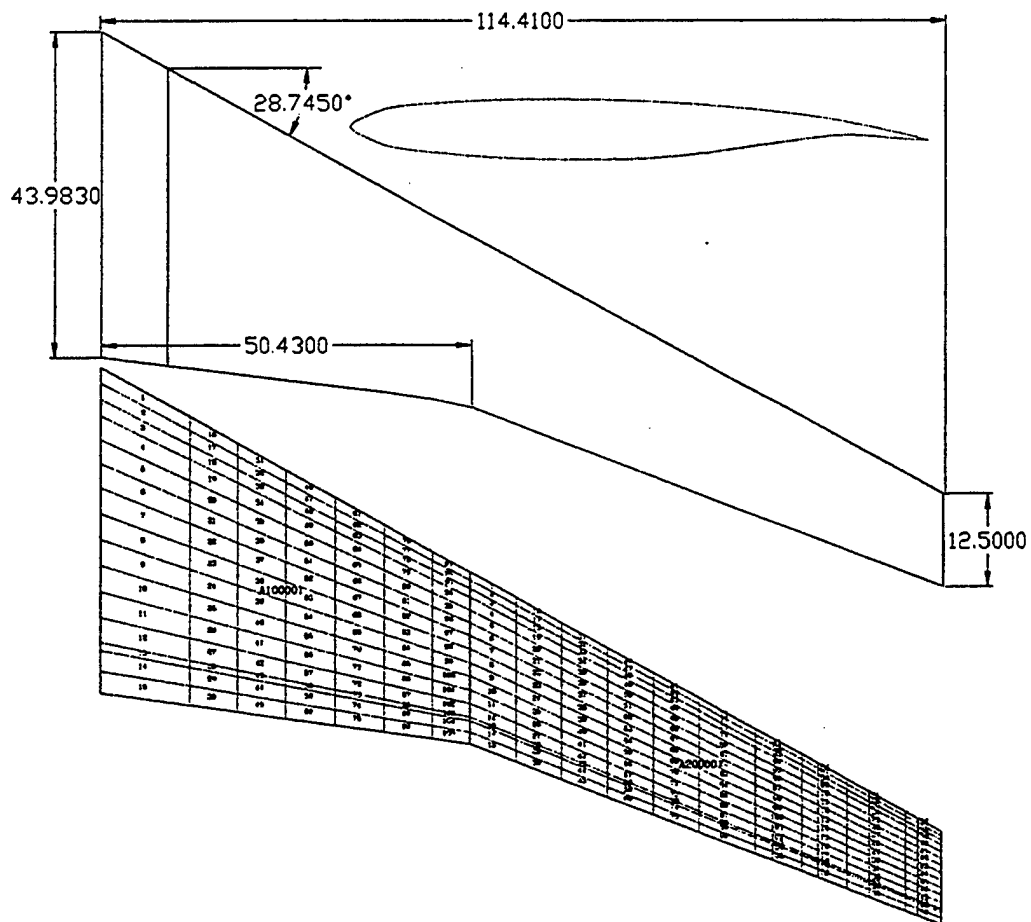
**Figure 4.3.1** Structural Configuration of DAST Model by FEM.



**Figure 4.3.2** Pressure Distribution of DAST Model: 10g Pull-up Trim Condition,  $M = 0.80$ , by ZONA6 of ASTROS\*.



**Figure 4.3.3** Deflection Shape of DAST Model: 10g Trim Condition,  $M = 0.80$ , by ZONA6 of ASTROS\*.



**Figure 4.3.4** Aerodynamic Planform Configuration of DAST Model.

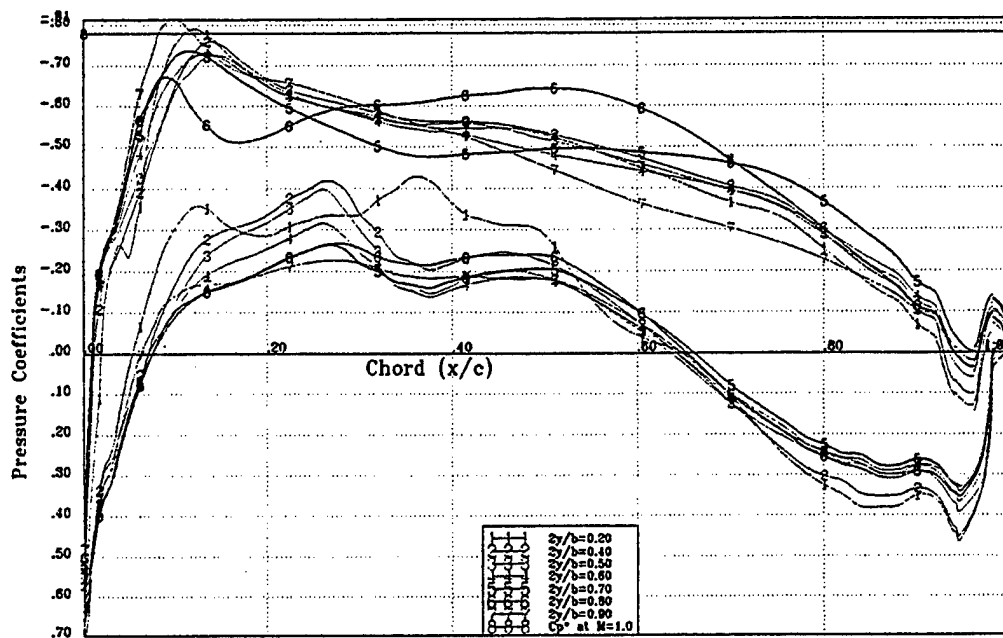


Figure 4.3.5.a Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow:  $M = 0.70$ ,  $AoA = 0.0^\circ$ , by ENSAERO.

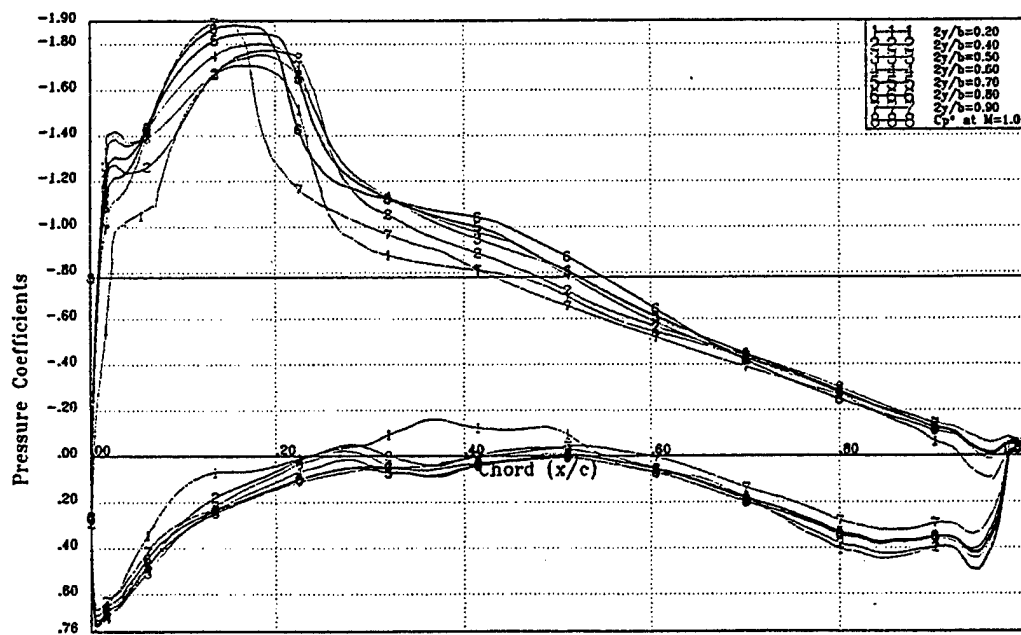


Figure 4.3.5.b Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow:  $M = 0.70$ ,  $AoA = 5.0^\circ$ , by ENSAERO.

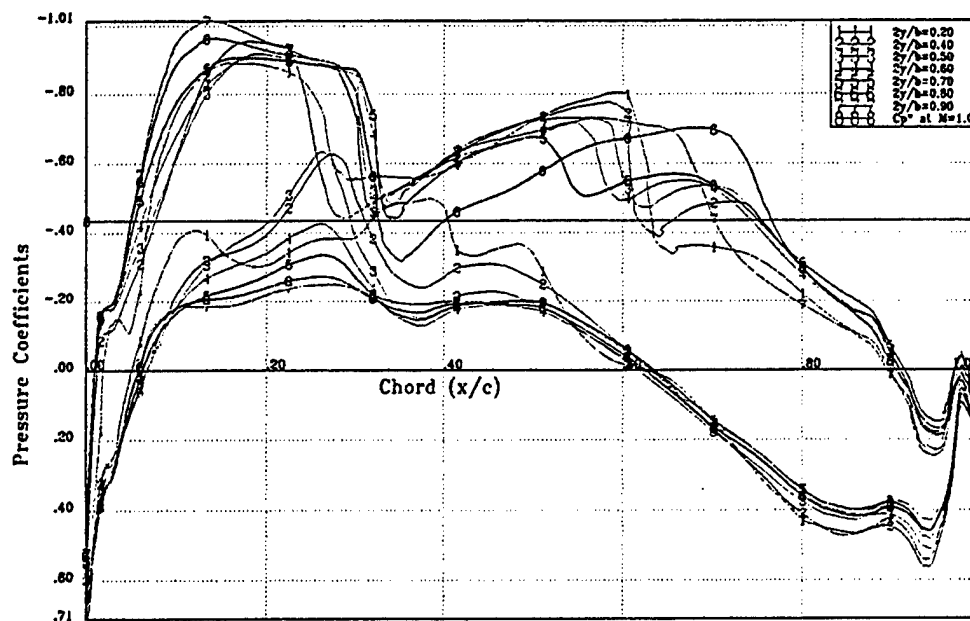


Figure 4.3.5.c Aerodynamic Pressure Coefficients of DAST Model for Euler Flow:  $M = 0.80$ ,  $AoA=0.0^\circ$ , by ENSAERO.

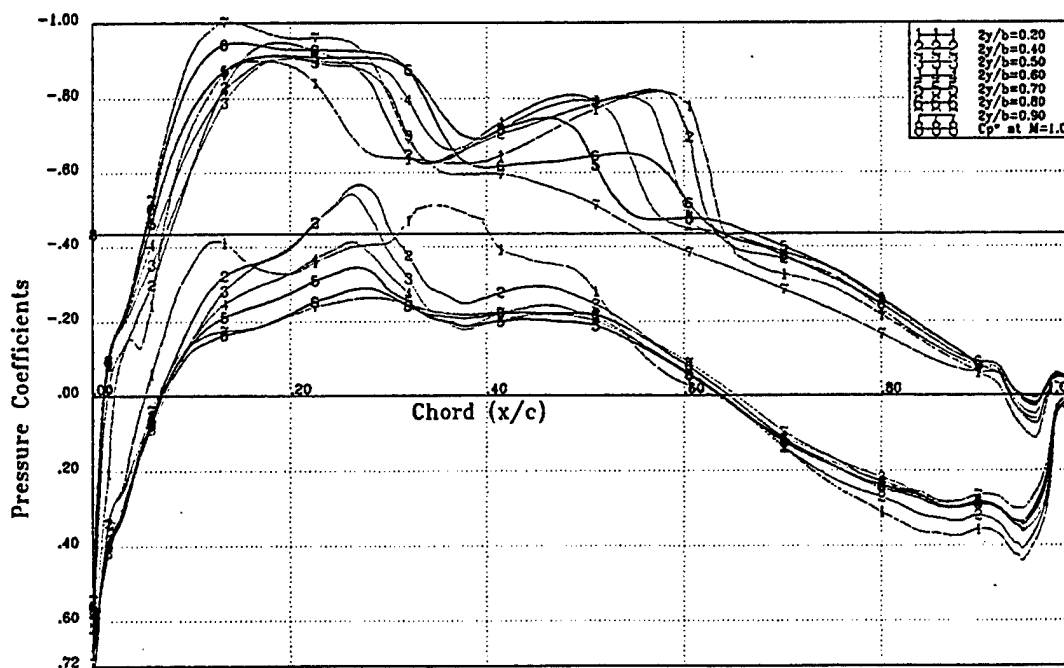


Figure 4.3.5.d Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow:  $M = 0.80$ ,  $AoA=0.0^\circ$ , by ENSAERO.



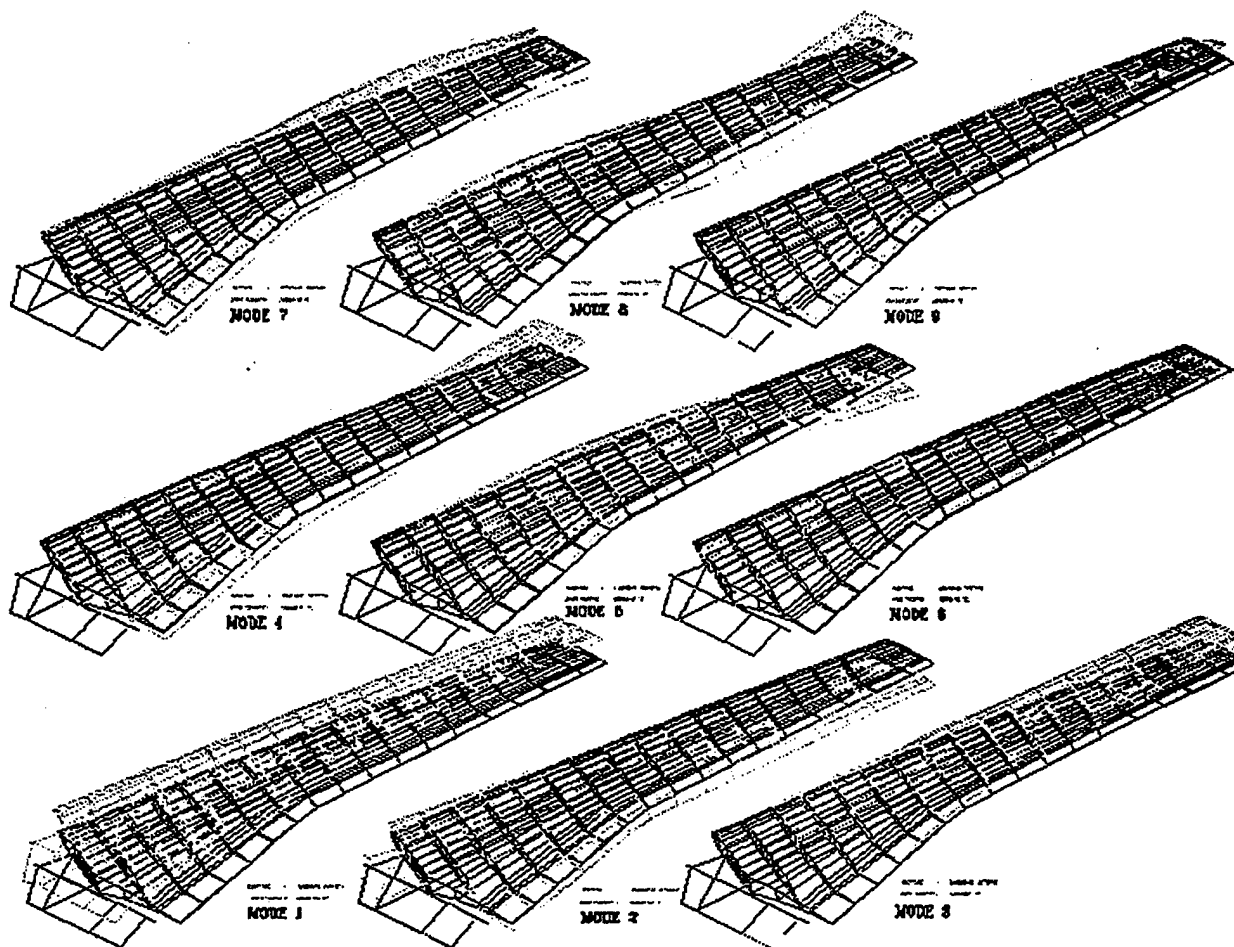


Figure 4.3.6 Normal Modes of DAST Model.

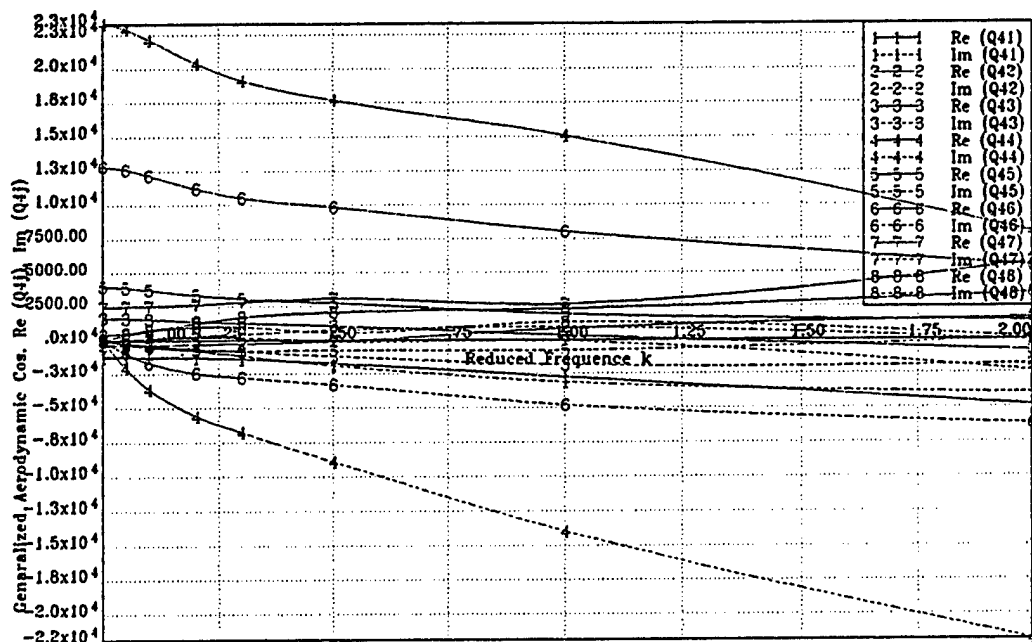


Figure 4.3.7 Generalized Unsteady Aerodynamic Loads of DAST Model:  $M = 0.80$ , by ZONA6 of ASTROS\*.

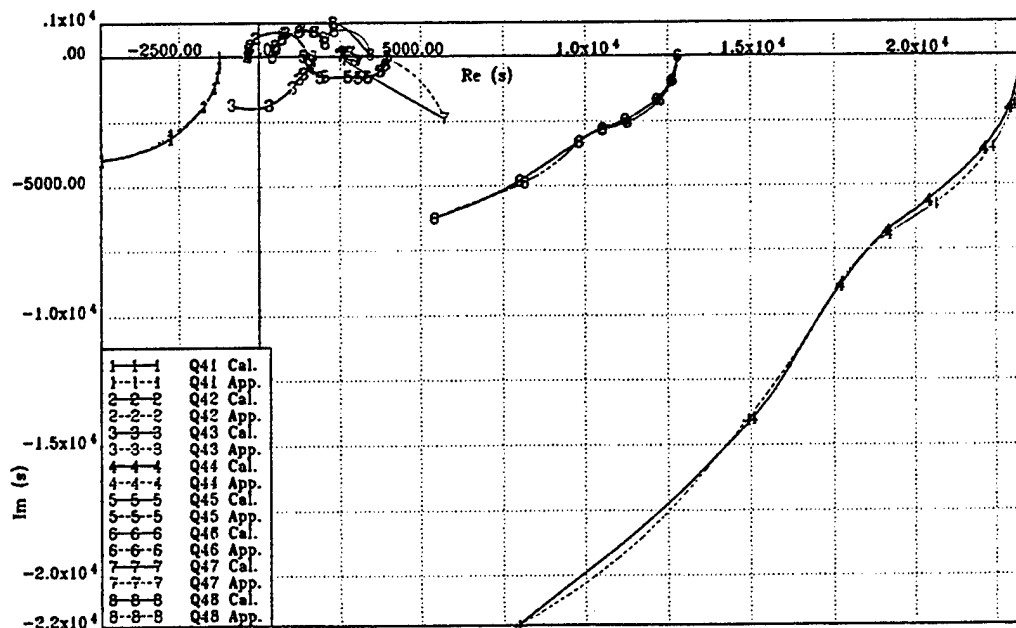


Figure 4.3.8 Generalized Unsteady Aerodynamic Coefficients  $Q_{4j}$  of DAST Model:  $M = 0.80$ , by ZONA6 of ASTROS\* and Approximated by Minimum-State Method.

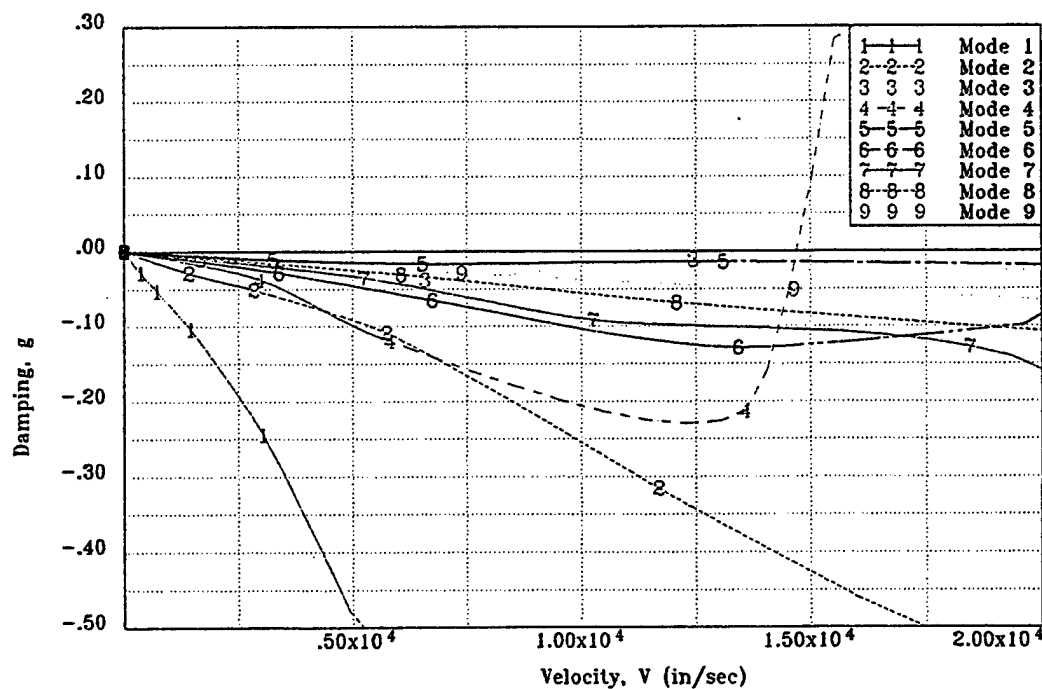
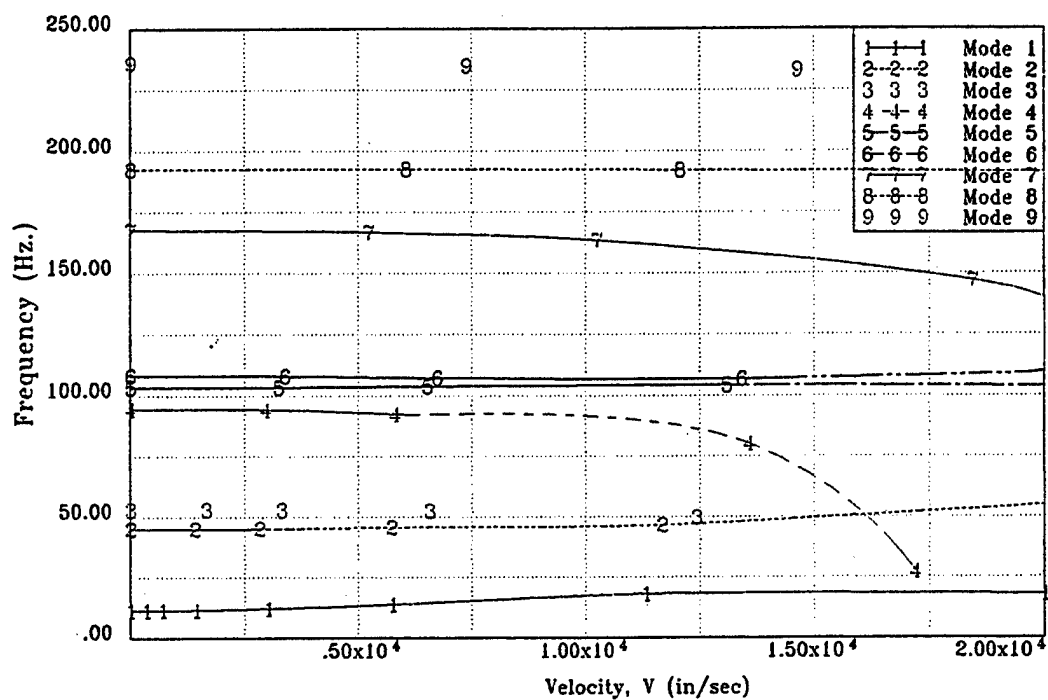


Figure 4.3.9 V-f and V-g Plots of DAST Model:  $M = 0.80$ , by ZONA6 of ASTROS\* (Flutter Speed = 14,358 in/sec, Flutter Frequency = 48.67 Hz).

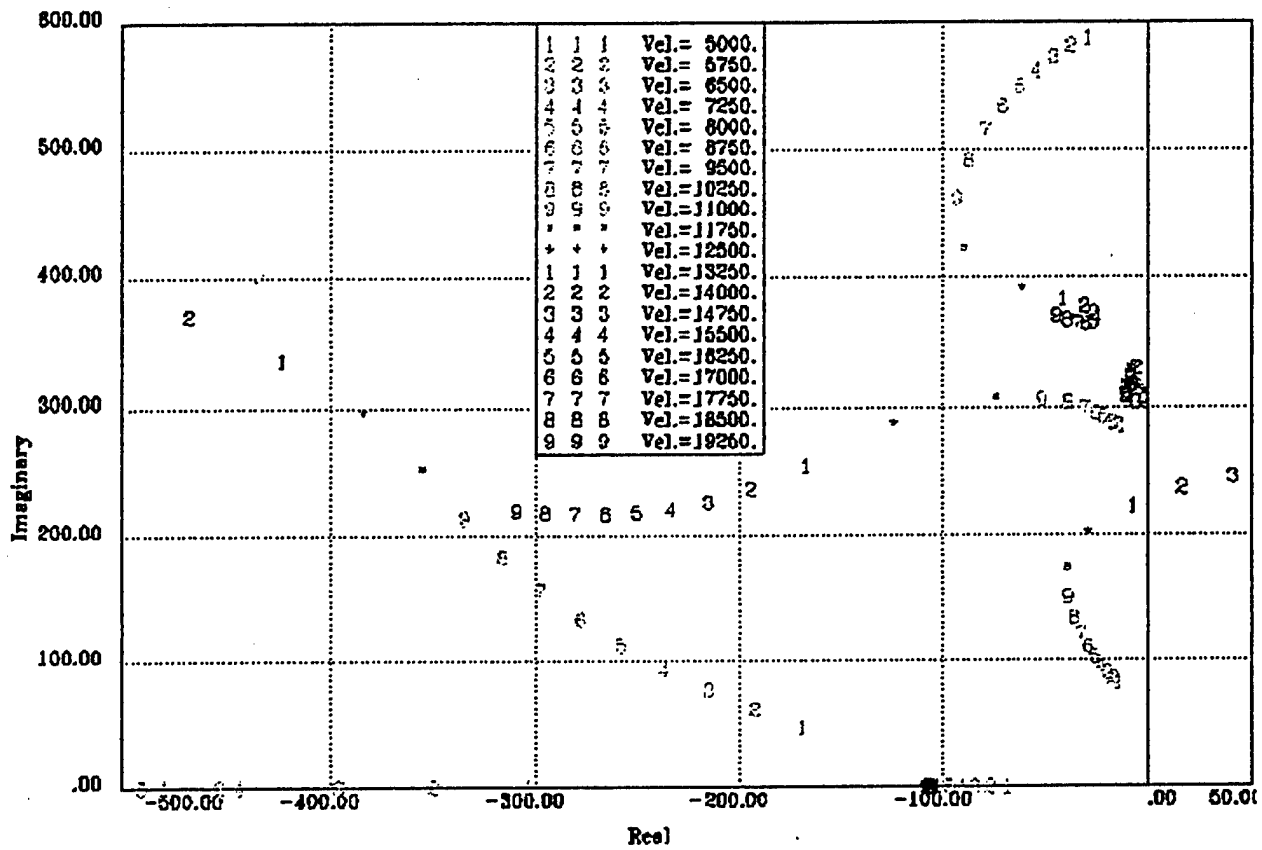


Figure 4.3.10 Root-Locus Plot of DAST Model:  $M = 0.80$ , ZONA6 of ASTROS\* (Flutter Speed = 13,490 in/sec, Flutter Frequency = 36.3 Hz).

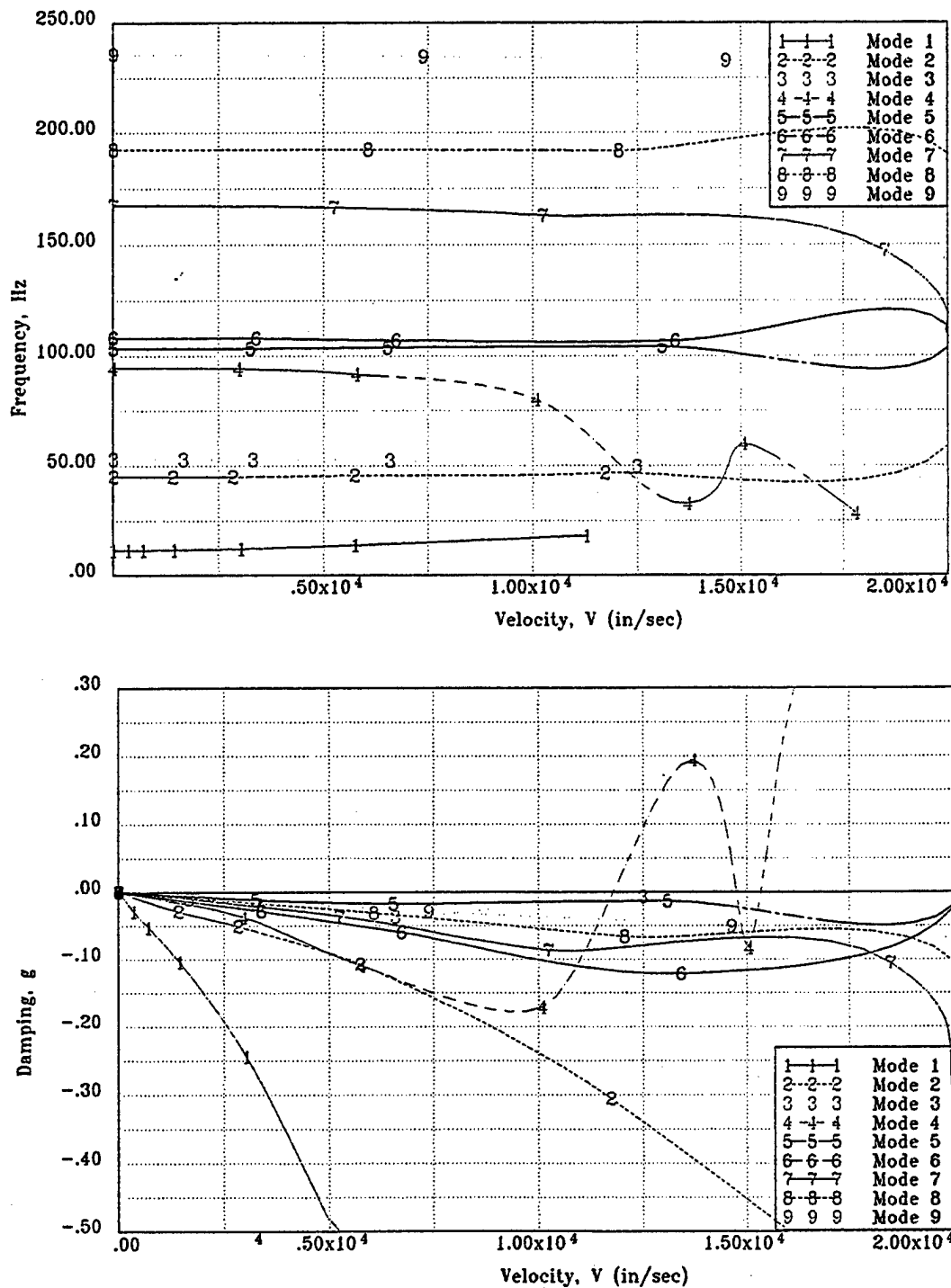


Figure 4.3.11 V-f and V-g Plots of DAST Model:  $M = 0.80$ , by ZTAIC of ASTROS\* (Flutter Speed = 11,800 in/sec, Flutter Frequency = 56.0 Hz)

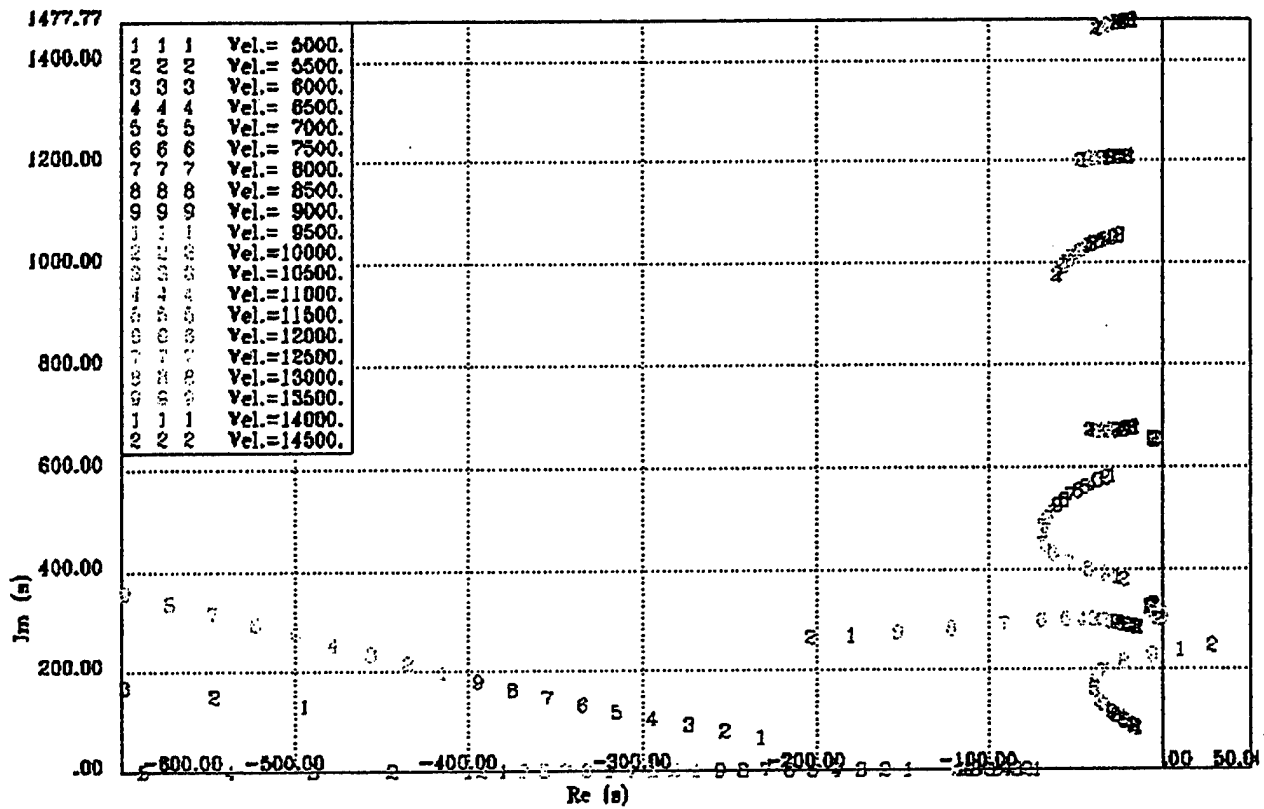


Figure 4.3.12 Root-Locus Plot of DAST Model:  $M = 0.80$ , by ZTAIC of ASTROS\* (Flutter Speed = 12,893 in/sec, Flutter Frequency = 49.3 Hz).

## 4.4 Case 2.b: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Optimization

- **Purpose:** To test a composite structural wing model in static aeroelastic, normal modes, and combined optimization.
- **Description of input and results:**

### 4.4.1 Static Aeroelastic Optimization

Static aeroelastic structural design optimization was performed in the 10g pull-up trim condition. The total weight of the wing skins and the spar caps was optimized. At the final design point, the trim parameters angle-of-attack and control surface deflection angle were required to match those of the analysis. The design variables were the ply thicknesses of the composite material skins and the areas of the spar caps. The minimum thicknesses of the individual plies were assumed to be 0.01 in. A displacement constraint at the wing tip, 5.506 in, was the same as the displacement from the original analysis. The Tsai-Wu failure criteria were used as strength constraints for the composite material. The required stresses in the CBAR elements were taken to be the von Mises stresses.

The design variables were defined by DESVARP entries, and each ply thickness was a design variable. Then, the properties of some of the elements were defined to the same design variables, with the effect of linking the variables. The number of properties to be determined was 989 and the number of global design variables was 254. The design variables and their numbering are shown in Fig 4.4.1.

As a result of the design optimization for static aeroelasticity, the wing weight was reduced from 89.49 lbs to 10.96 lbs in only 18 iterations. The iteration history of the design optimization is shown in Table 4.4.1. The results from the final analysis satisfied the constraints. Required CPU time was 2 hours 40 minutes 33.3 seconds.

### 4.4.2 Normal Modes Optimization

In the normal modes optimization, the constraint was a lower bound on the first elastic natural frequency of the structure. The required frequency was 11.288 Hz, the same as that calculated in the analysis of the original structure.

As a result, the weight was reduced from 89.49 lbs to 9.43 lbs. This result was obtained in only 9 iterations. The iteration history of the design optimization is shown in Table 4.4.2. The required CPU time was 18 minutes 34.0 seconds.

### 4.4.3 Multidisciplinary Design Optimization for Static Aeroelasticity and Normal Modes

Multidisciplinary design optimization for static aeroelasticity and normal modes was performed simultaneously. The displacements and stresses in a 10g trim condition and the lowest natural frequency were again used as the constraints.

As a result, the weight was reduced from 89.49 *lbs* to 10.86 *lbs*. This result was obtained in only 11 iterations. The CPU time was 2 hours 53 minutes 42.3 seconds. The iteration history of the design optimization is shown in Table 4.4.3 and Fig 4.4.2. The final design variables are presented in Table 4.4.4. In the layer list, 1, 2, 3, and 4 identify the 90°, +45°, -45°, and 0° directions of the skin layers, respectively. Here, the thickness of the layer in the 0° direction with layer list number 4 (in the spar direction) was larger than those of the other layers.